

Altitude Terrain Guarding and Guarding Uni-Monotone Polygons

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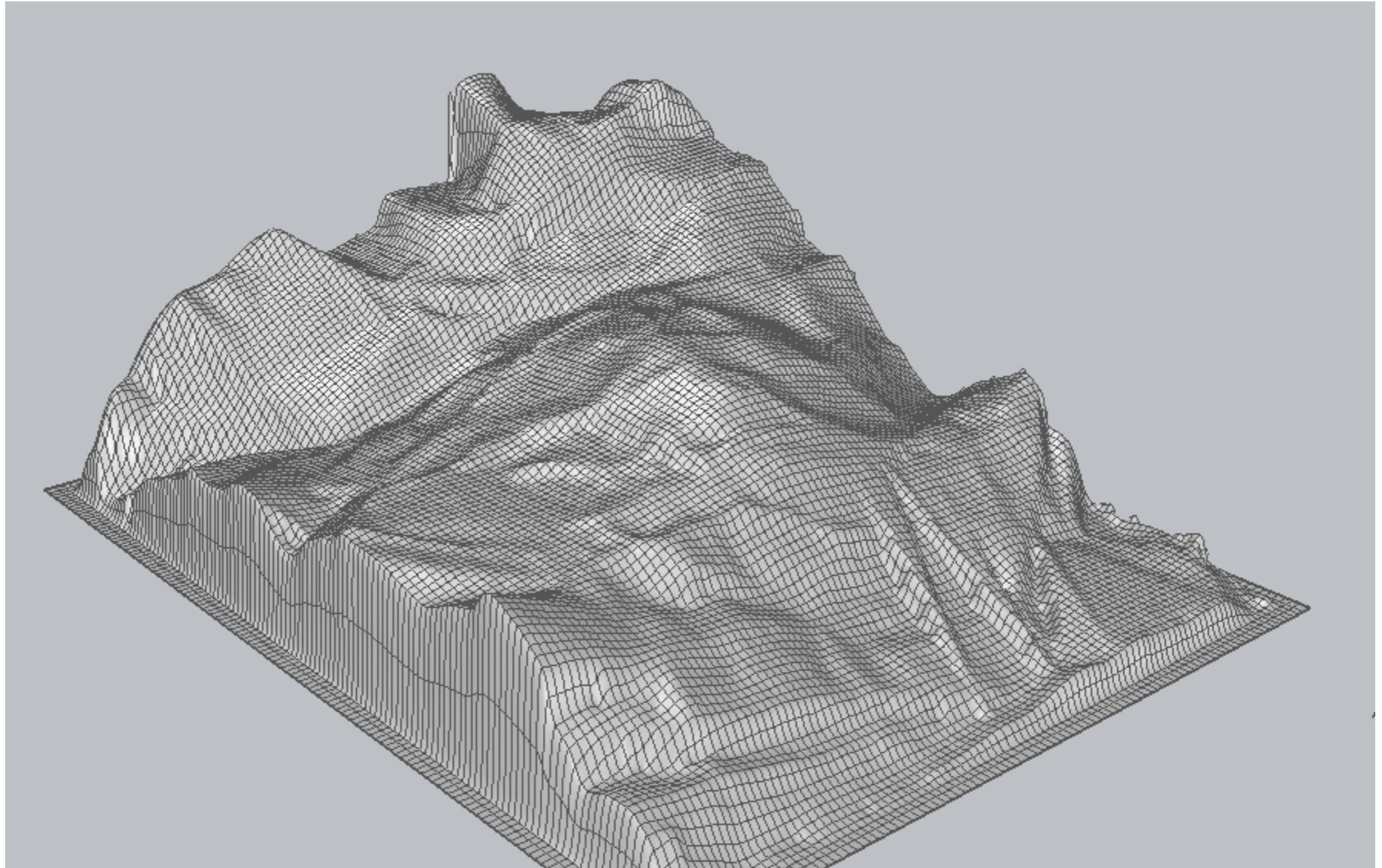


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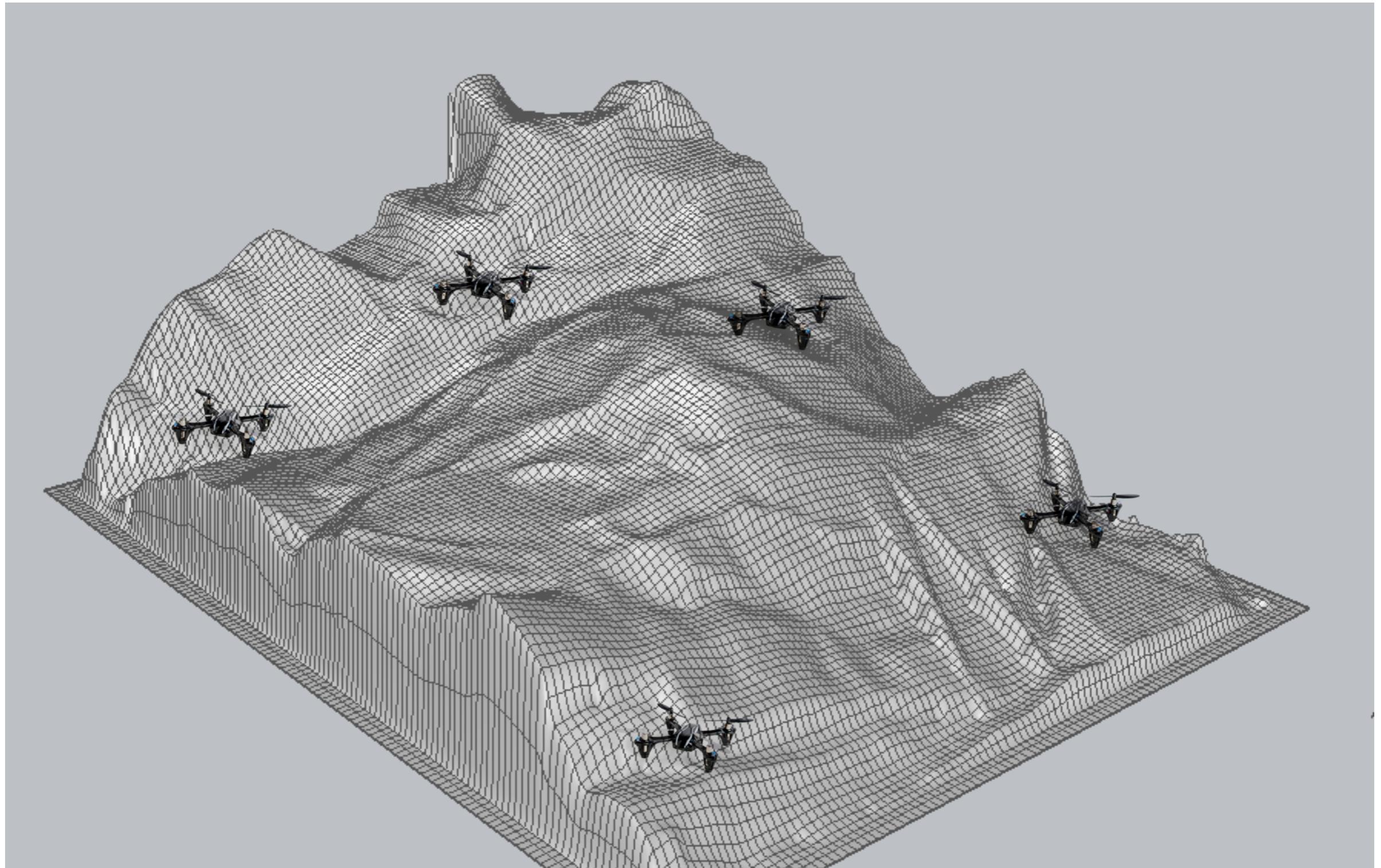


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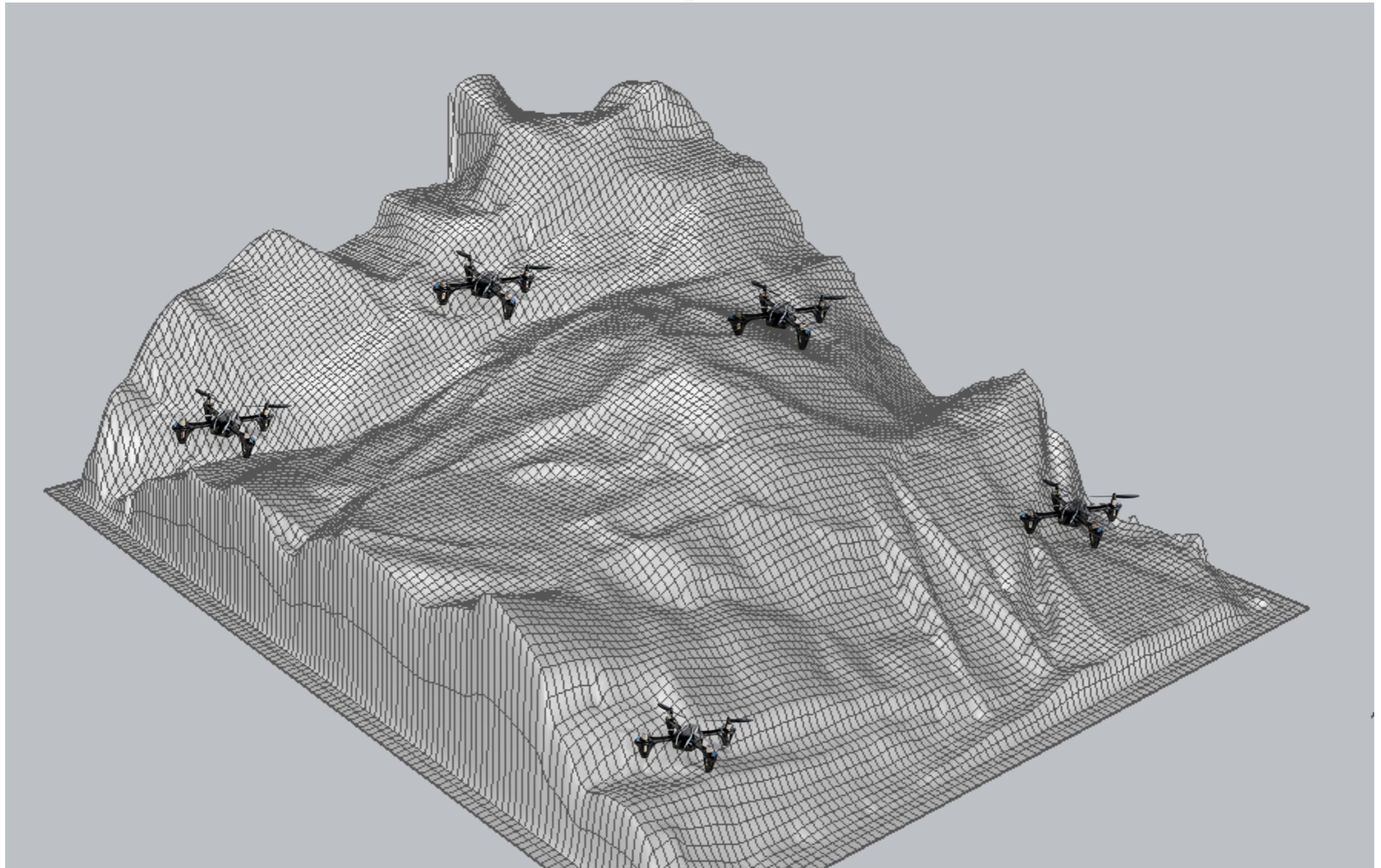


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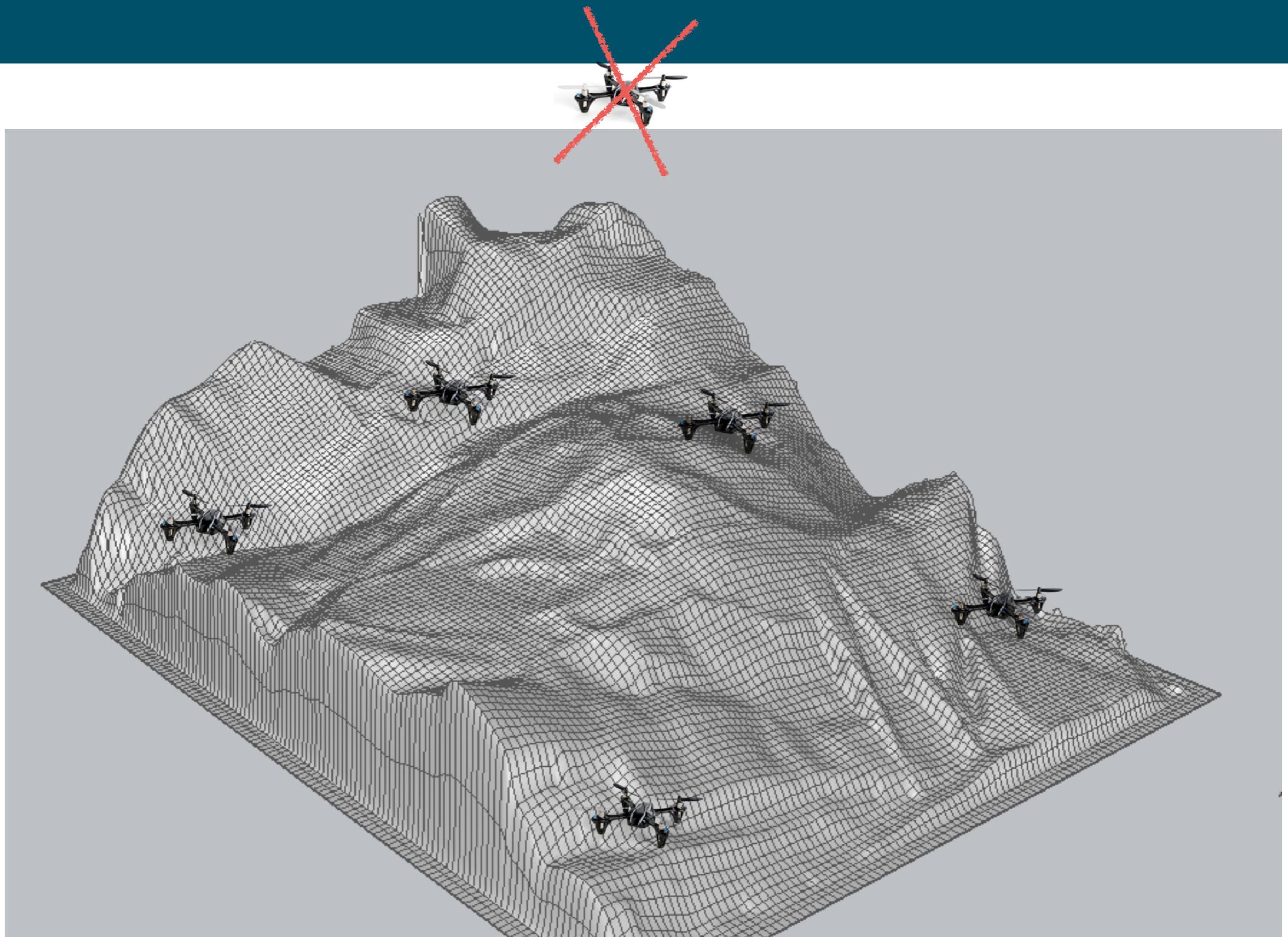


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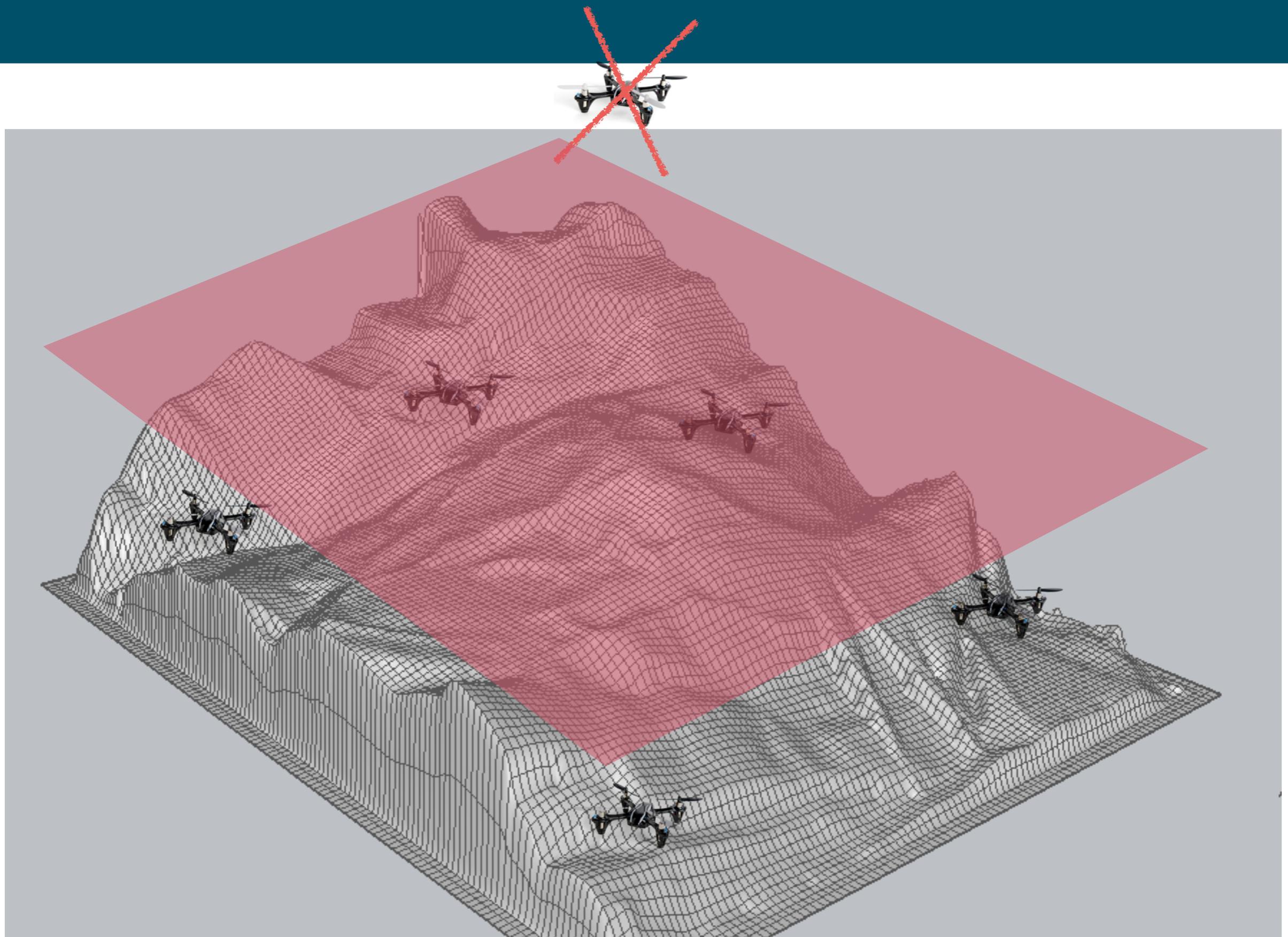


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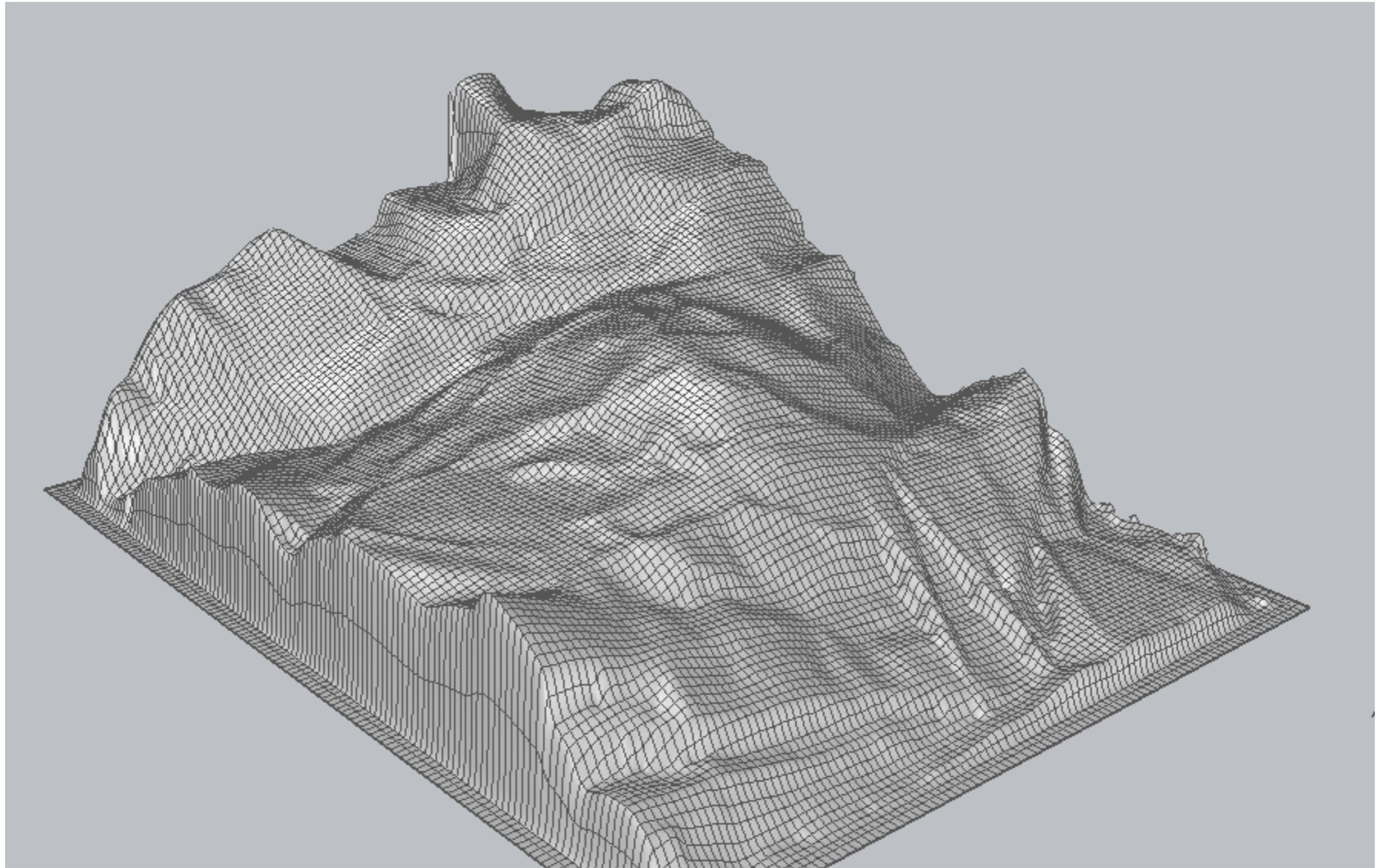


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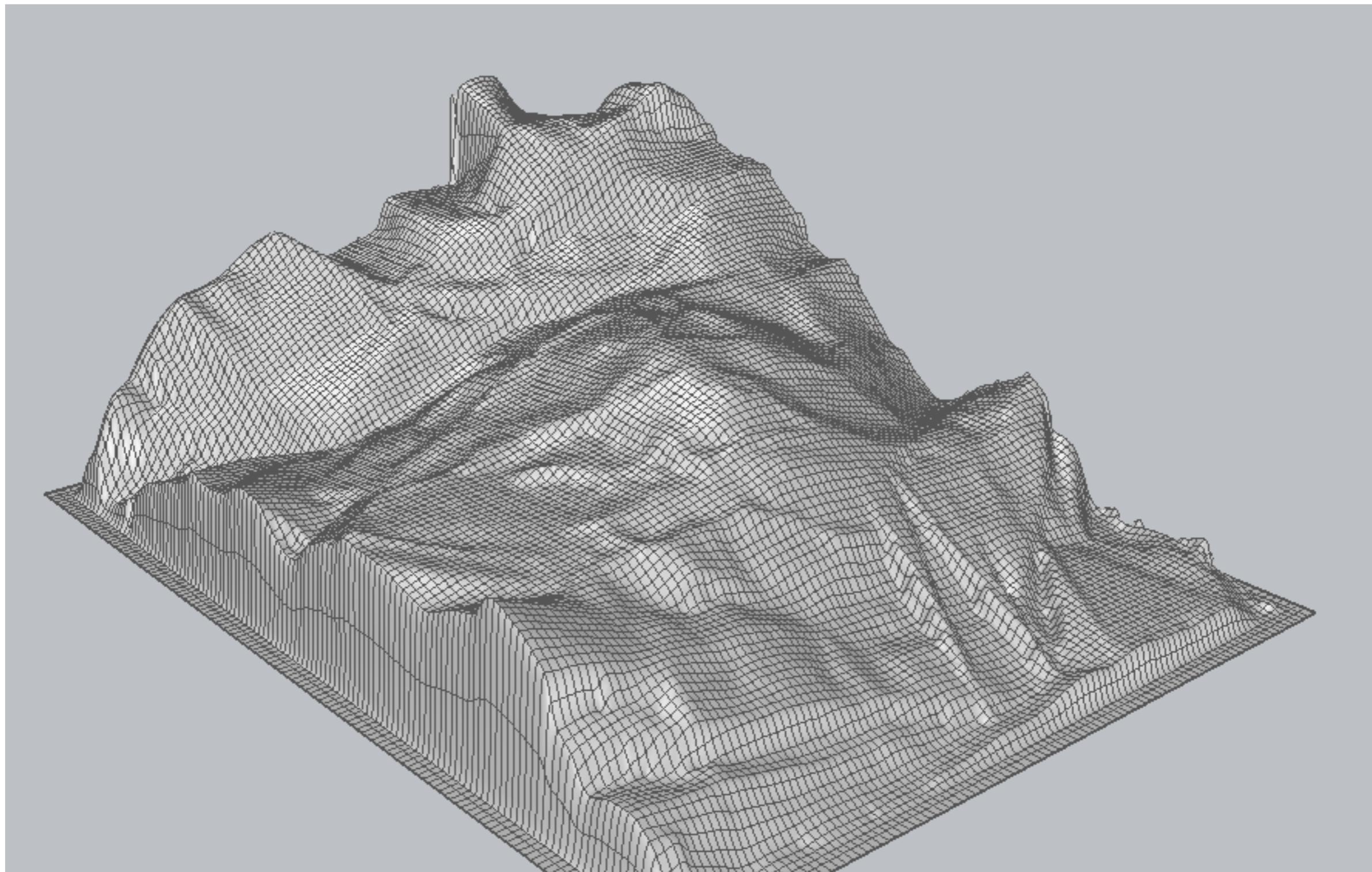
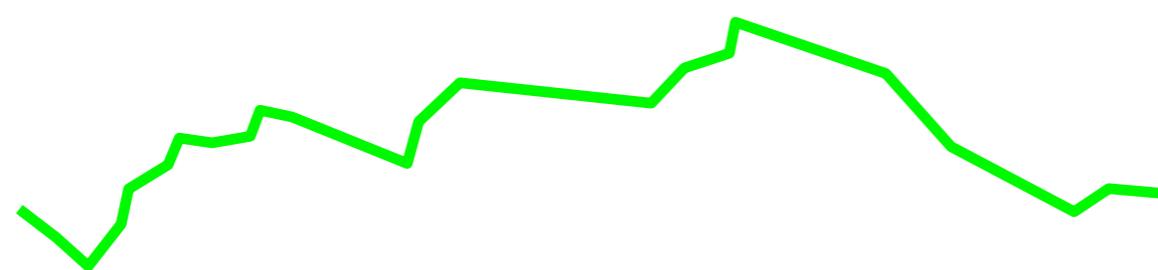


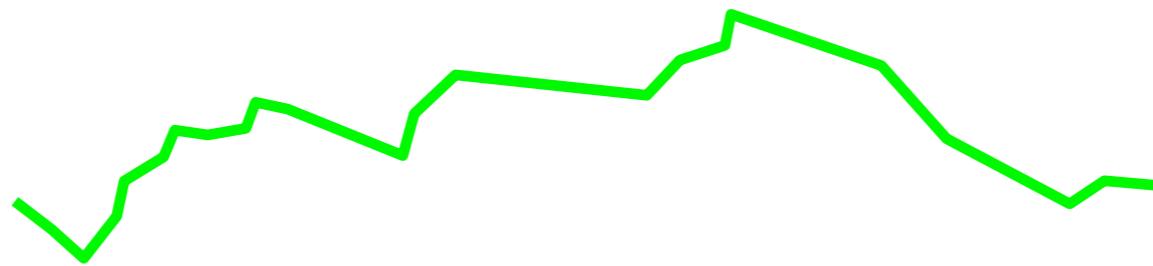
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2.5D

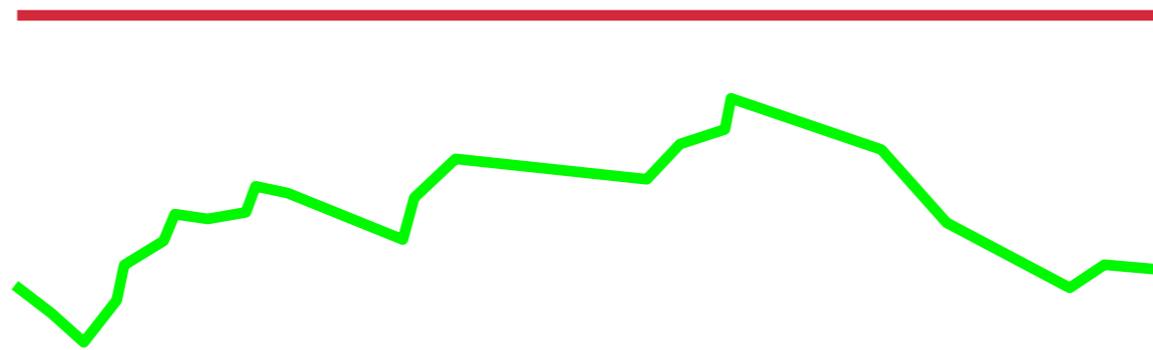


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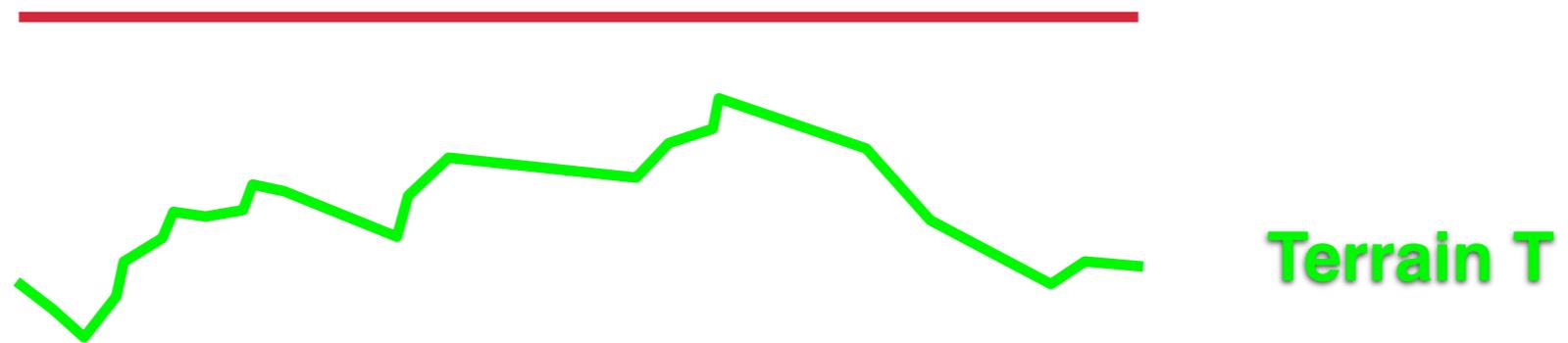
Altitude Terrain Guarding Problem



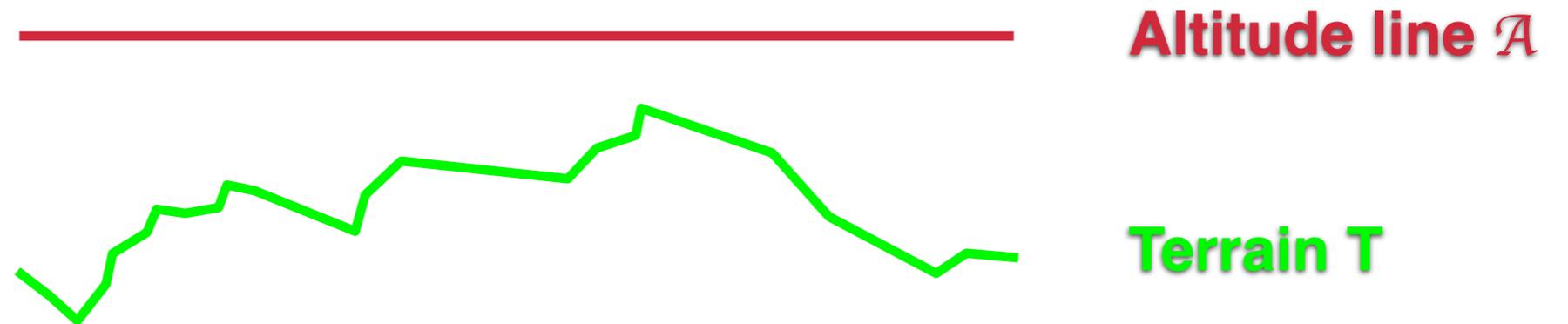
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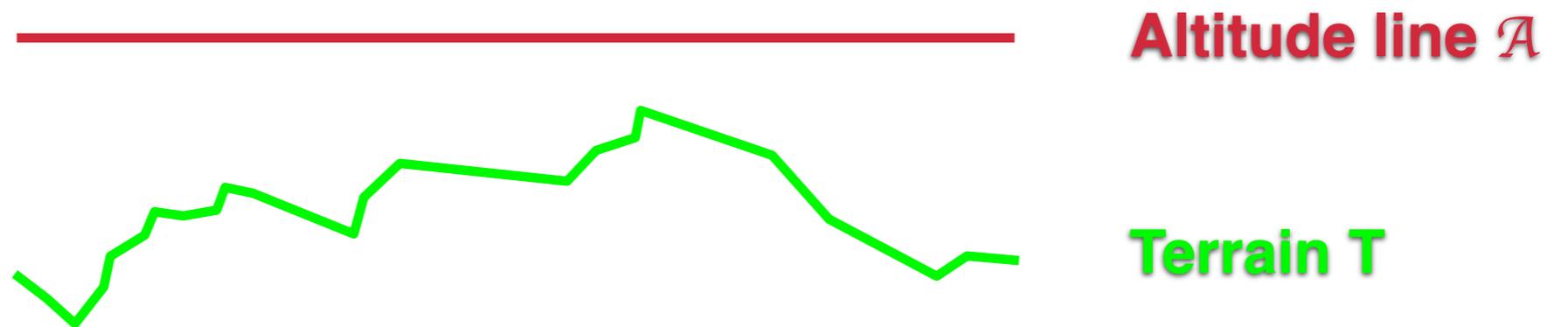
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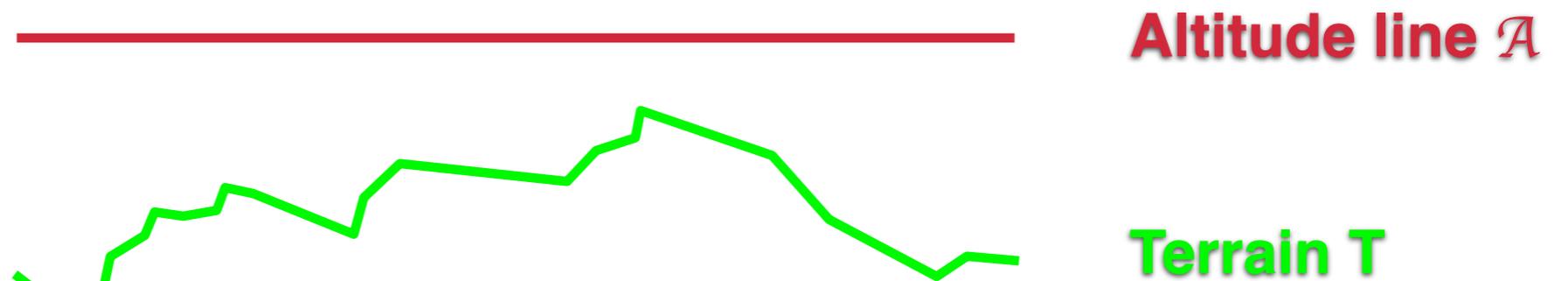


Altitude Terrain Guarding Problem



x-monotone chain of line segments in \mathbb{R}^2
defined by its vertices $V(T) = \{v_1, \dots, v_n\}$

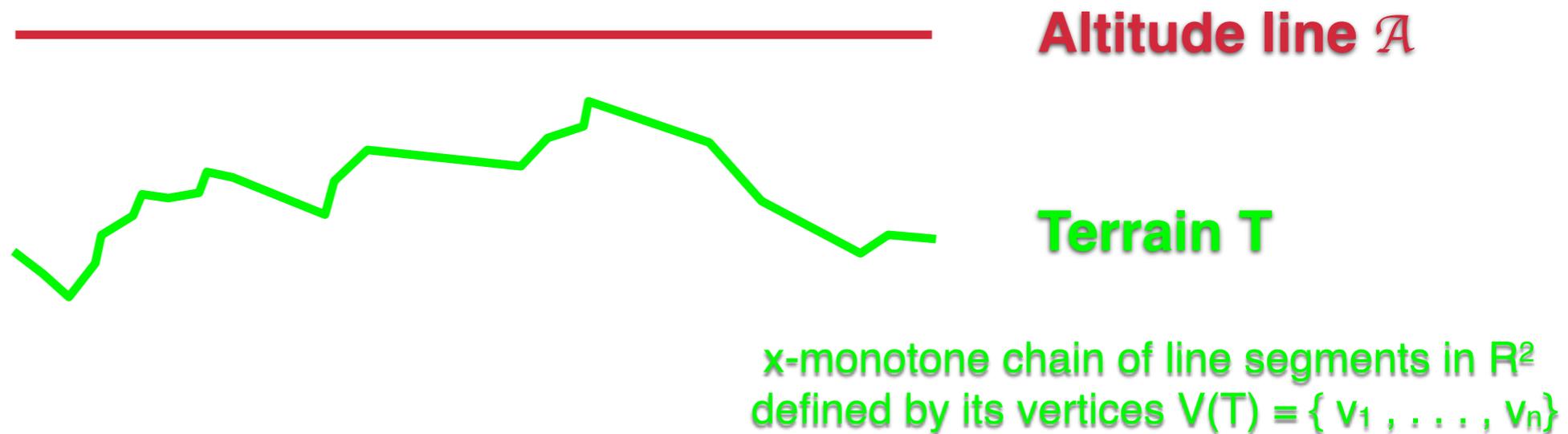
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Monotonicity

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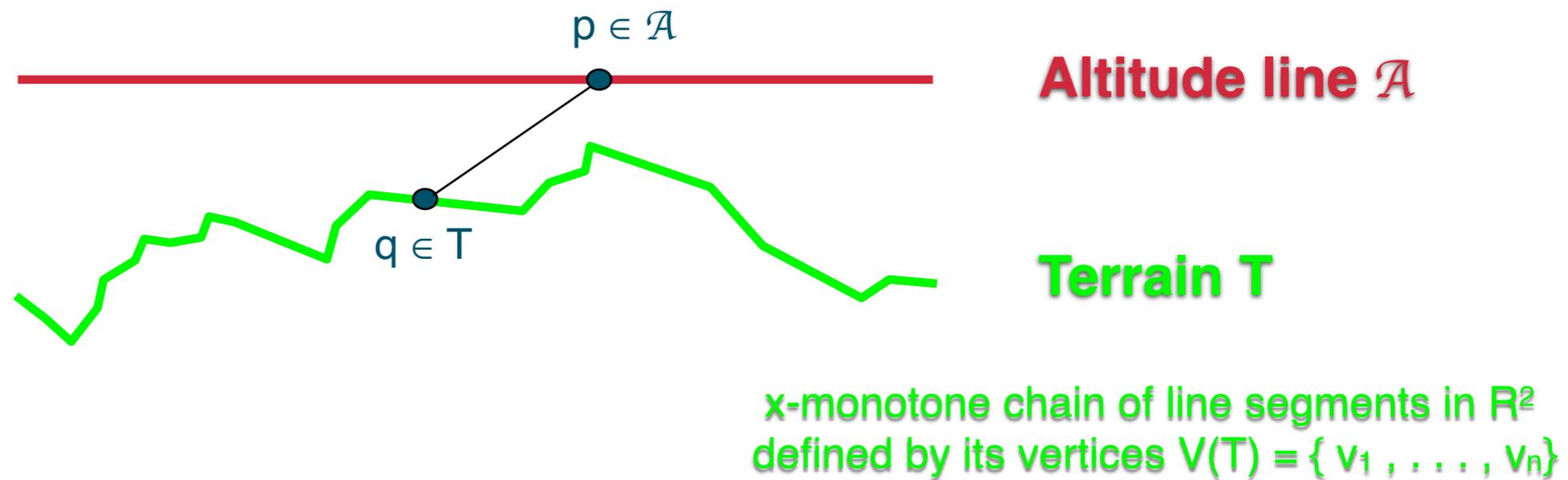


Monotonicity

➔ Points on T are totally ordered wrt to x -coordinate: $p < q$.

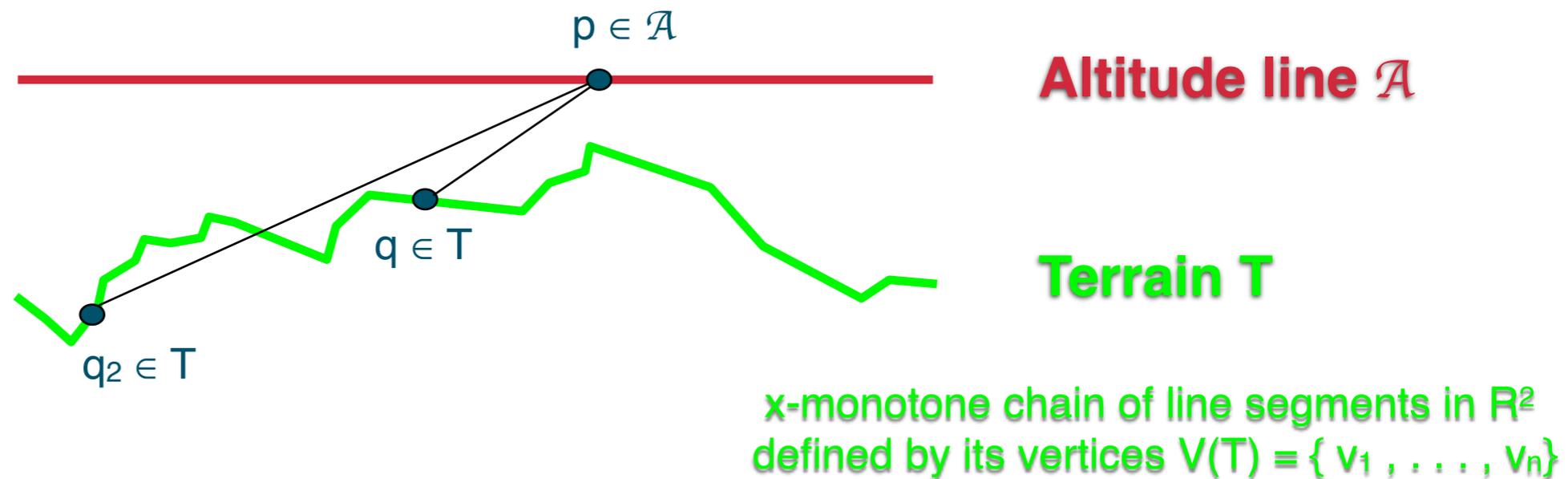
Altitude Terrain Guarding Problem

A point $p \in \mathcal{A}$ sees or covers $q \in T$ if and only if pq is nowhere below T (i.e. pq lies on or above T).



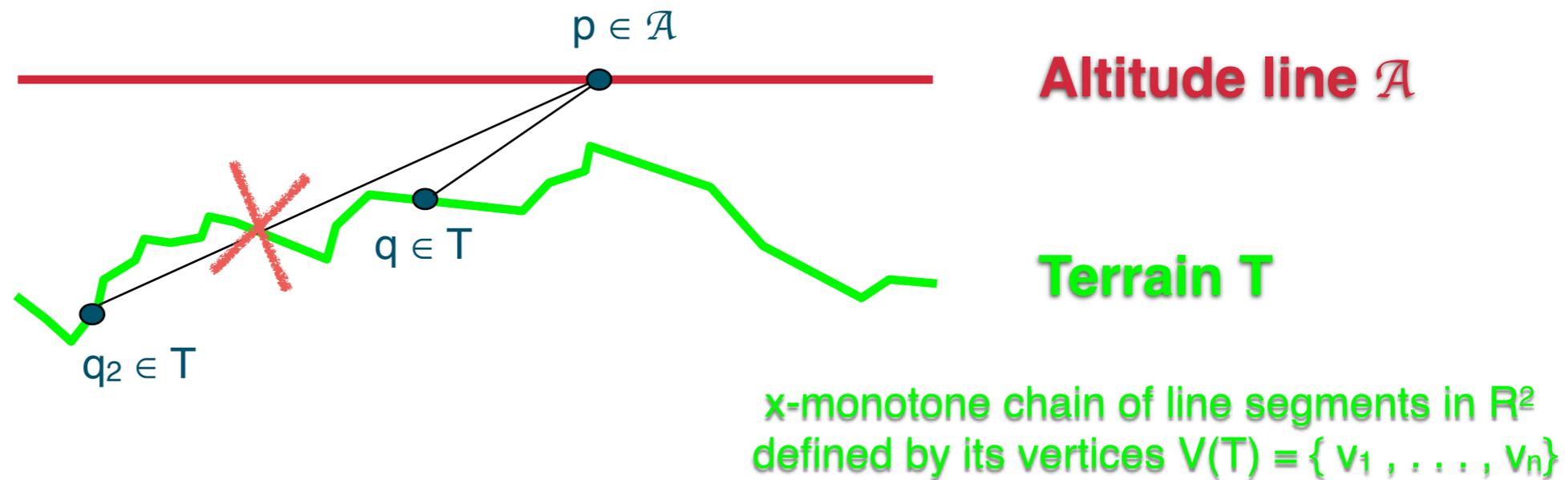
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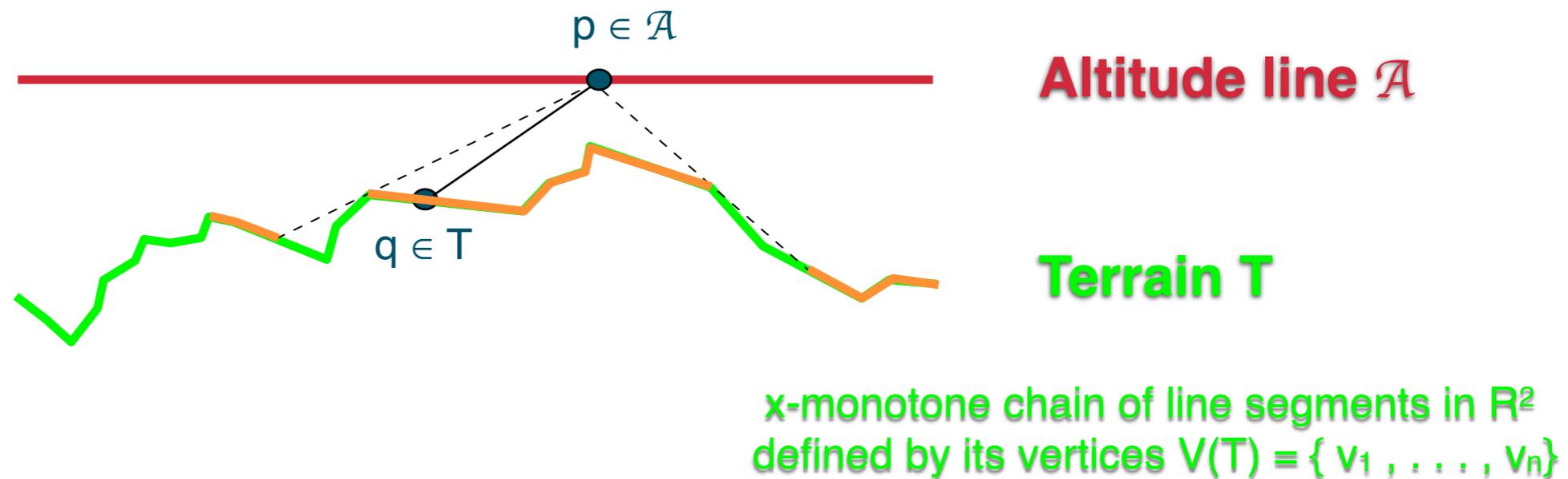
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$V_T(p)$ is the visibility region of p with $V_T(p) := \{q \in T \mid p \text{ sees } q\}$.

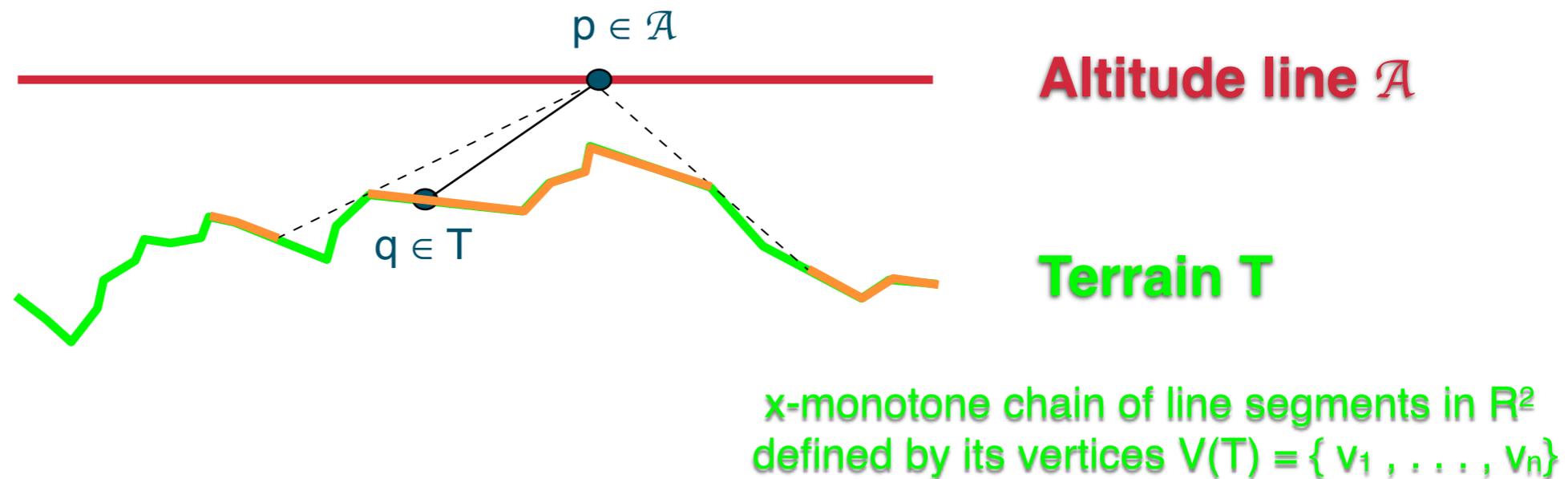


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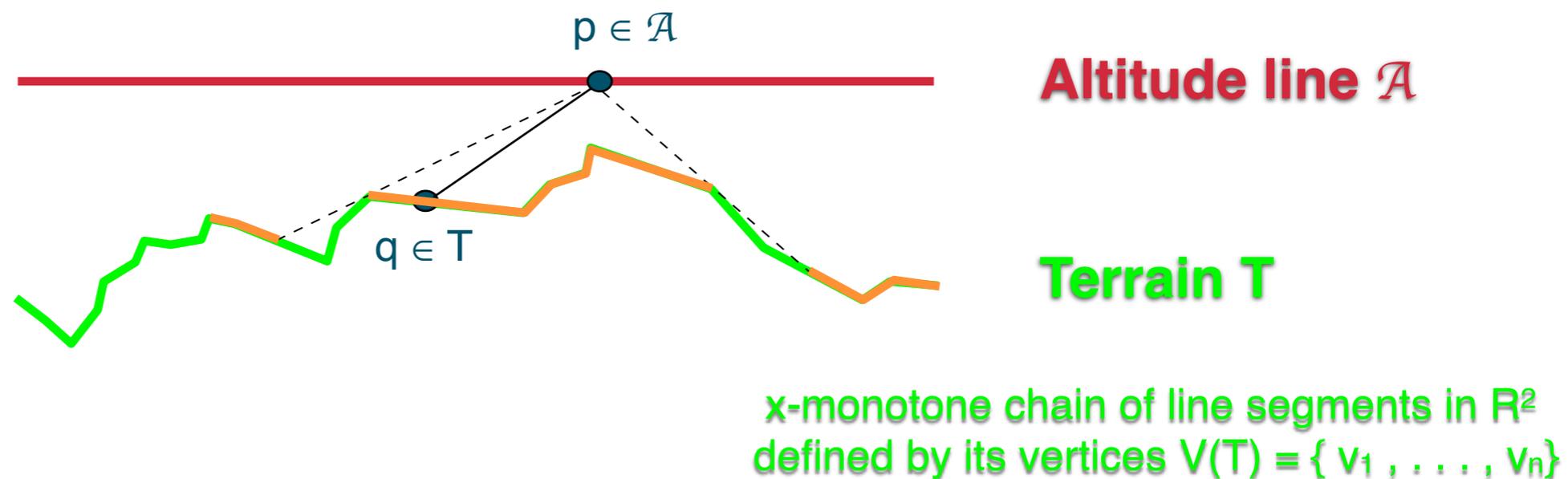


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Altitude Terrain Guarding Problem (ATGP) $ATGP(T, \mathcal{A})$

Given: a terrain T and an altitude line \mathcal{A} .

A minimum set of guards that see all of T .

(Formally: A guard set $G \subseteq \mathcal{A}$ is optimal w.r.t. $ATGP(T, \mathcal{A})$ if G is feasible, that is, $T \subseteq V_T(G)$, and

$|G| = OPT(T, \mathcal{A}) := \min\{|C| \mid C \subseteq \mathcal{A} \text{ is feasible w.r.t. } ATGP(T, \mathcal{A})\}$.)

AGP in uni-monotone polygons

uni-monotone polygon?

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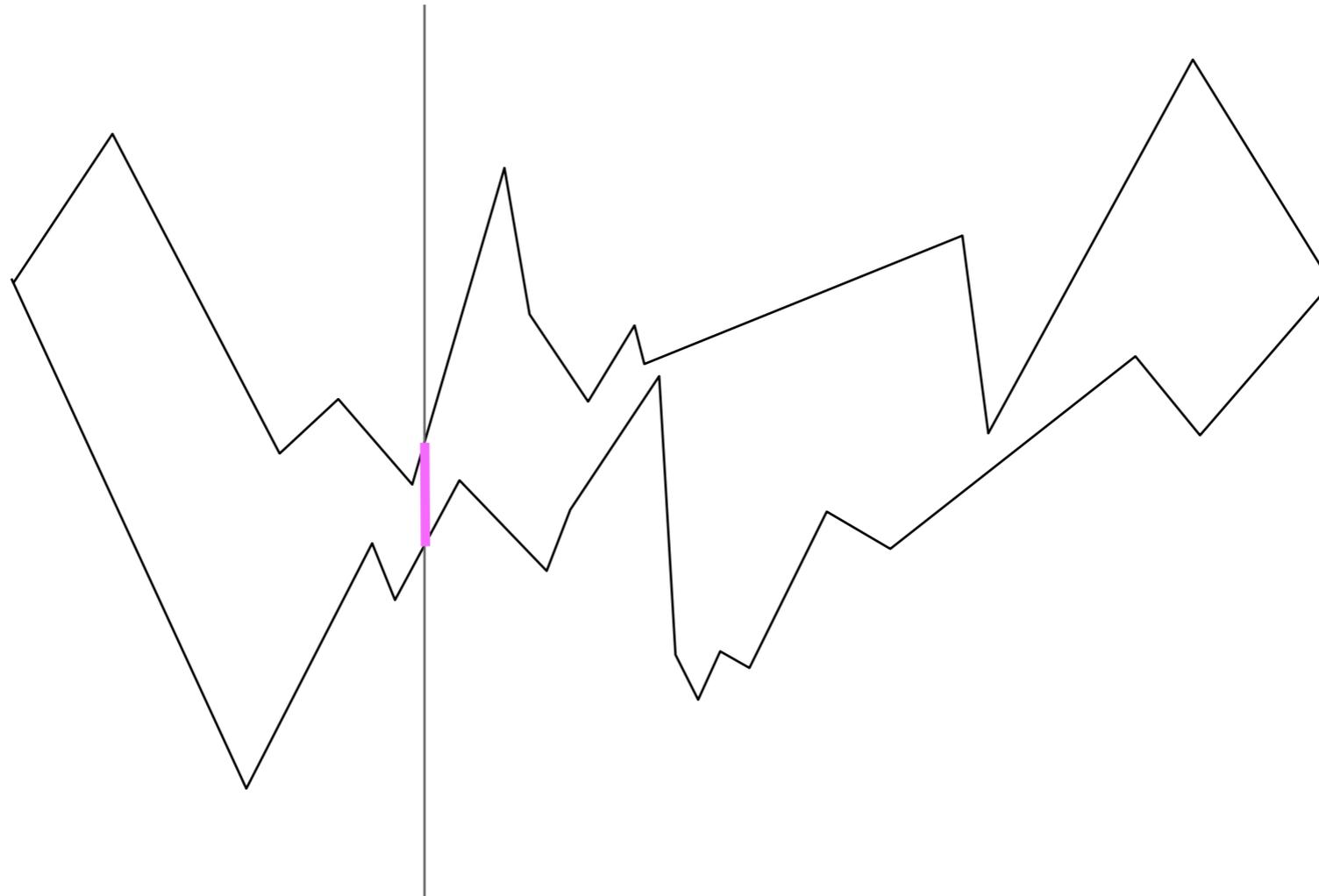
monotone polygon



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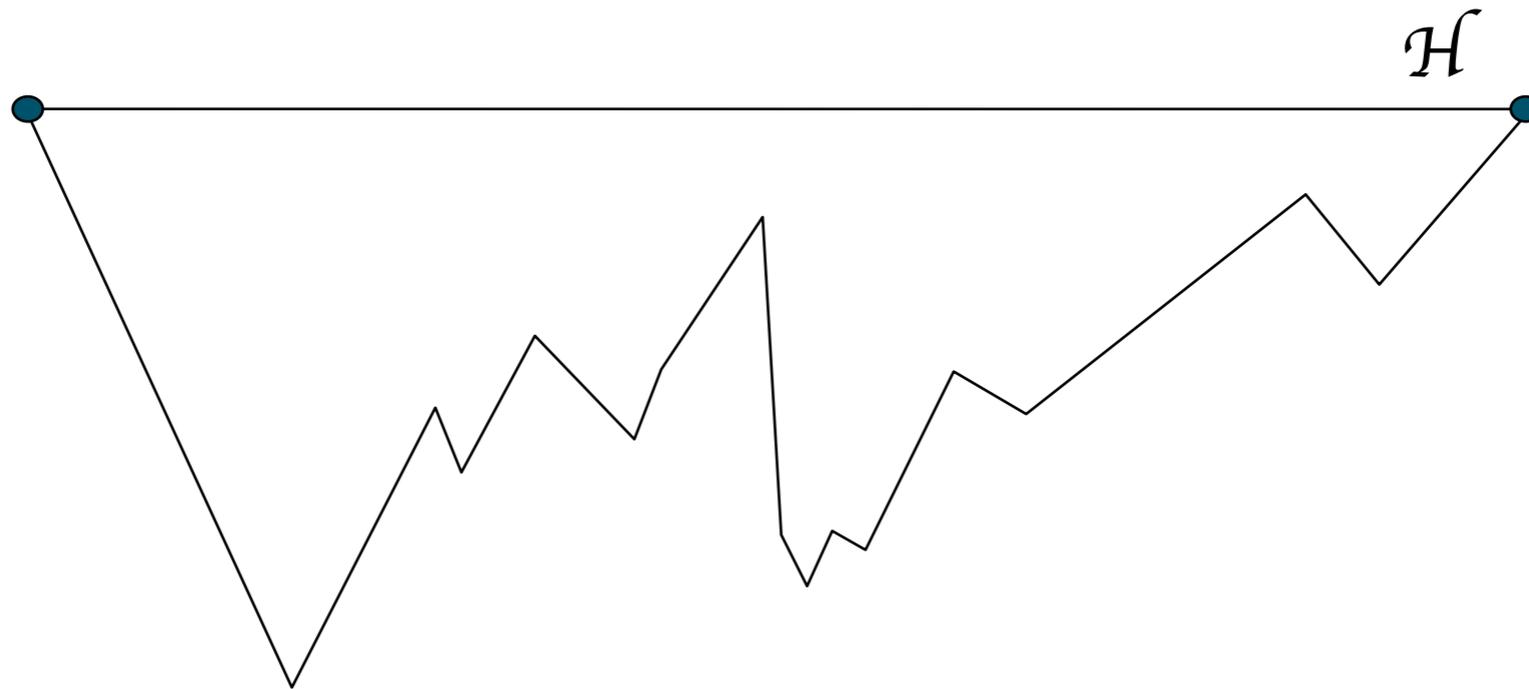
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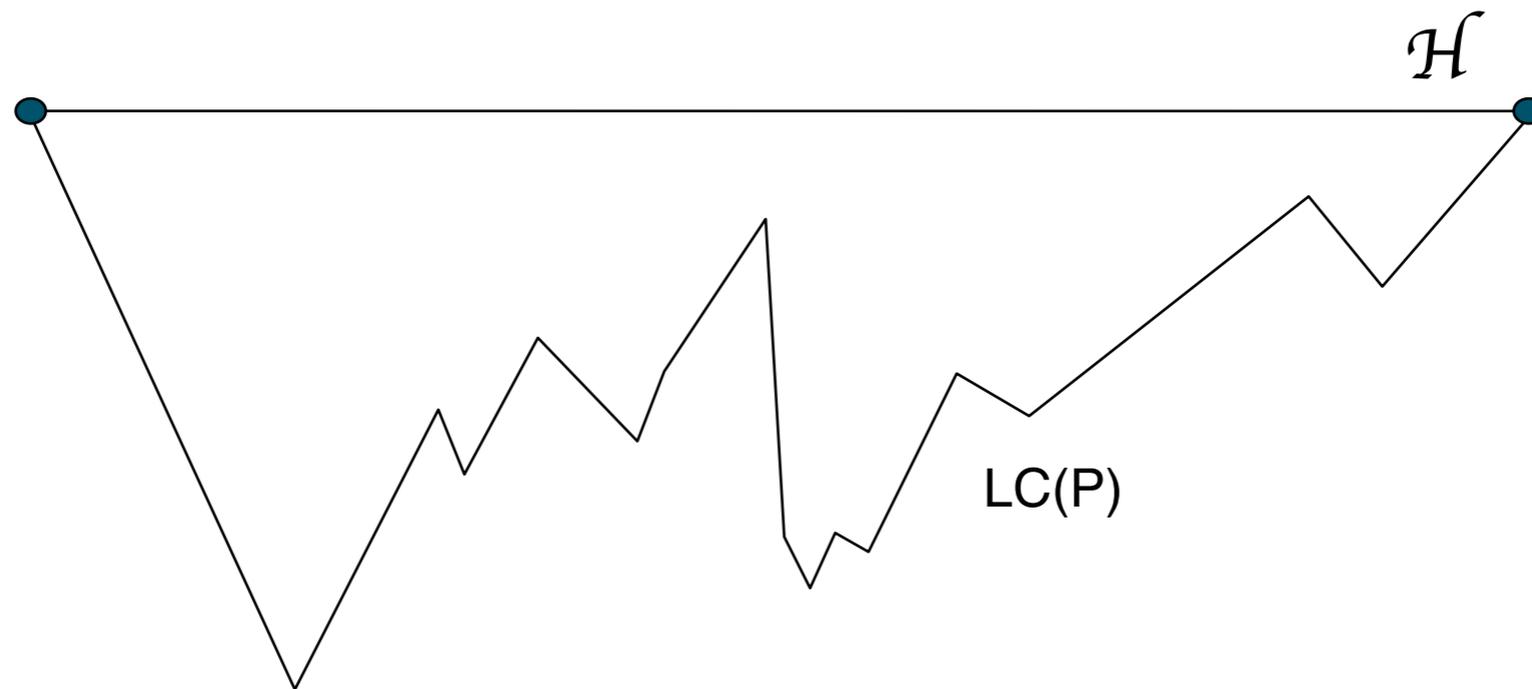
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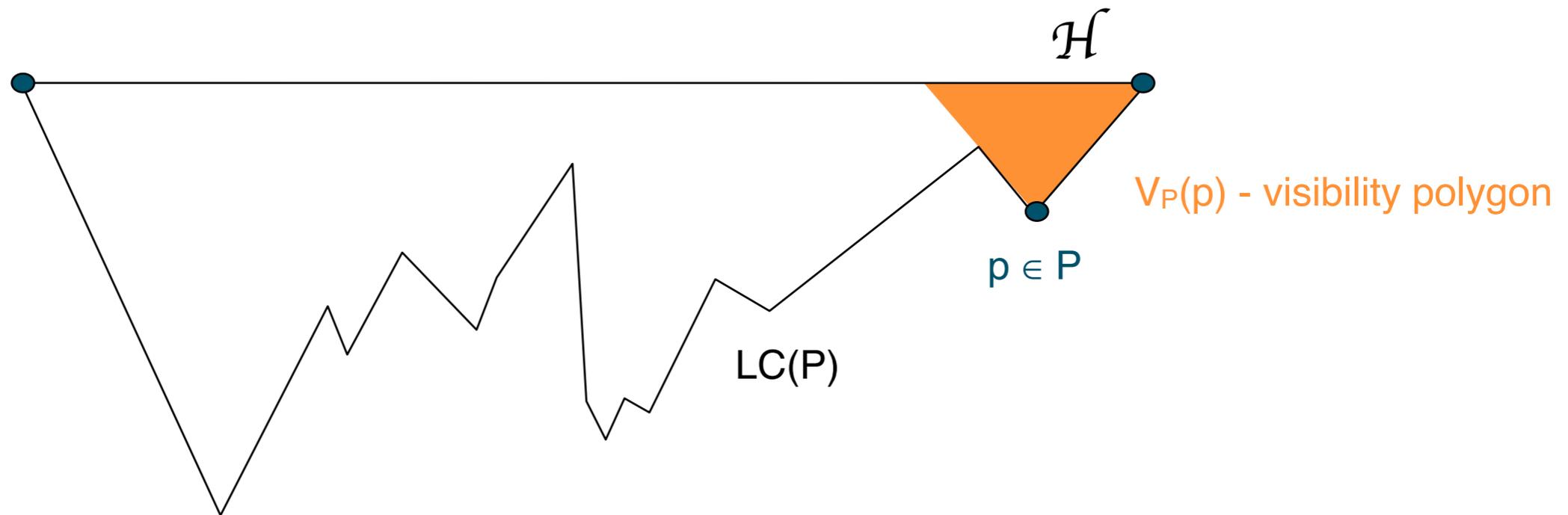
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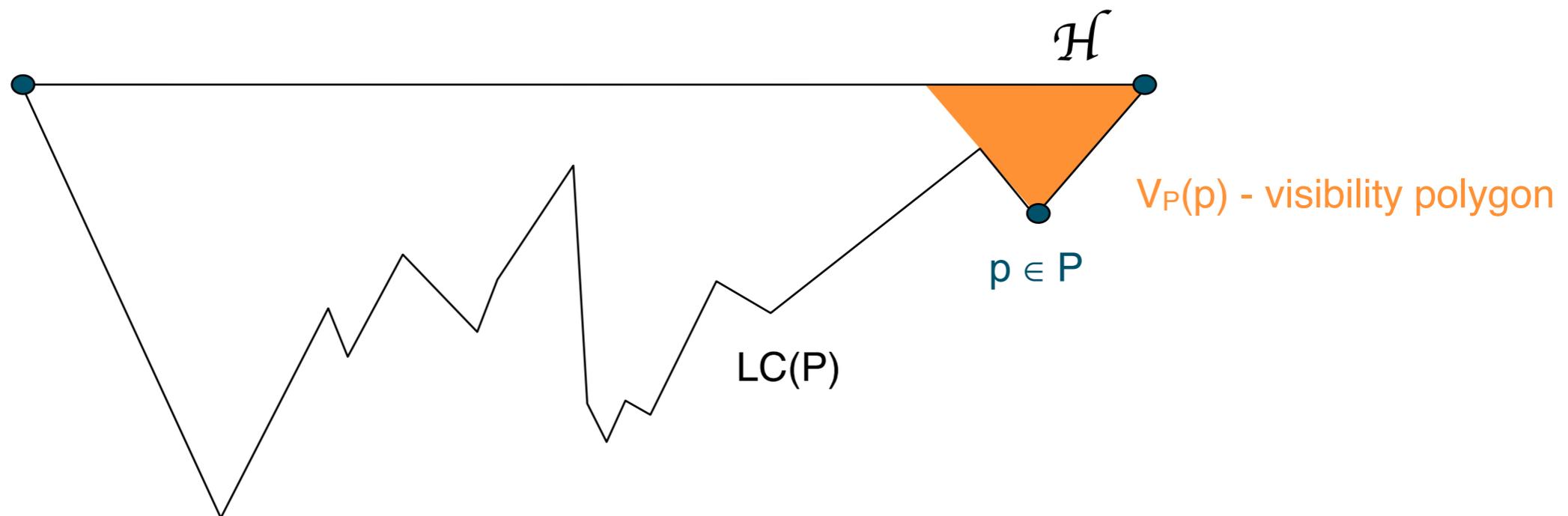
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Formally:

Art Gallery Problem (AGP) $AGP(G, W)$

Given: a polygon P and sets of guard candidates and points to cover $G, W \subseteq P$.

A minimum guard set $C \subseteq G$ that covers W (that is, $W \subseteq V_P(C)$).

We want to solve $AGP(P, P)$.

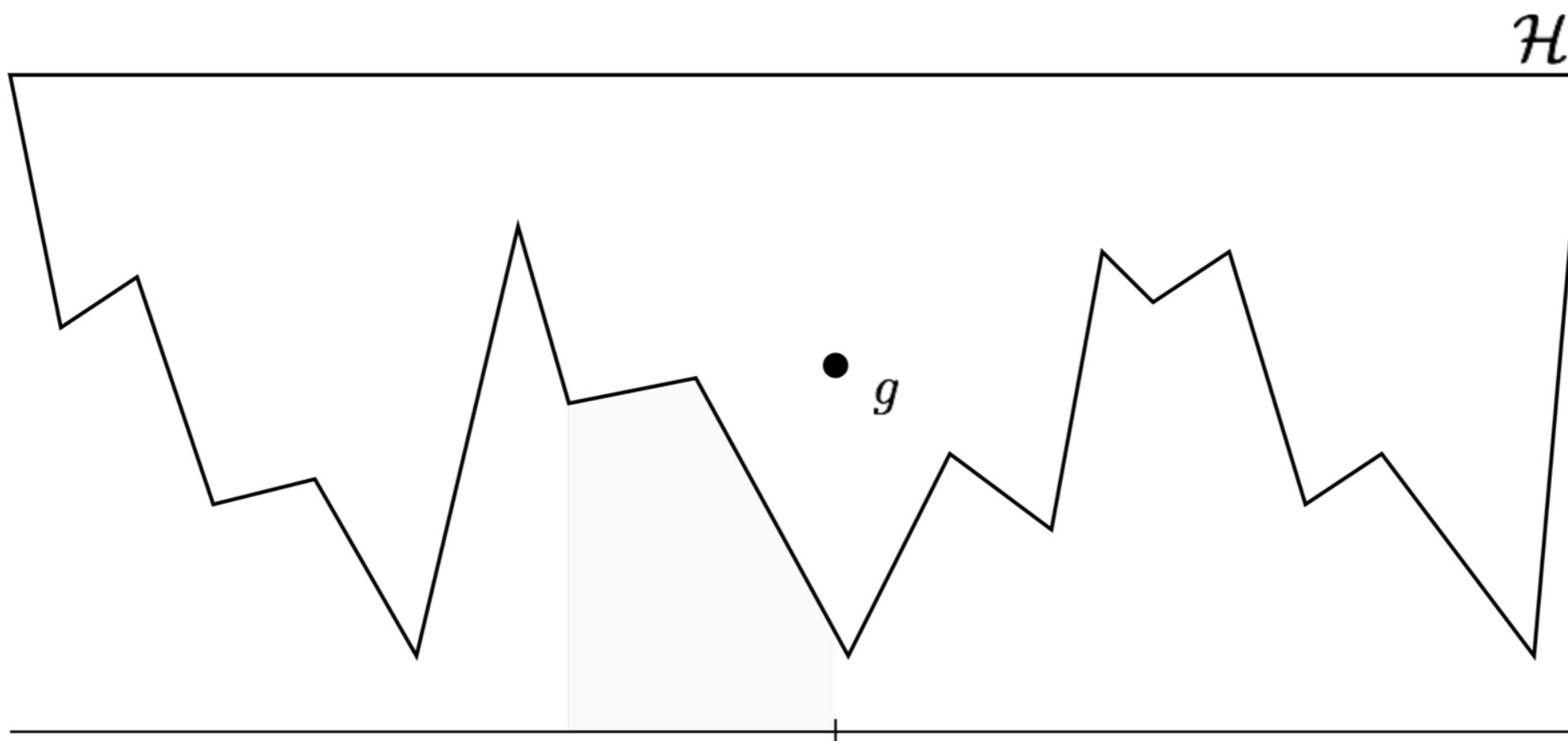
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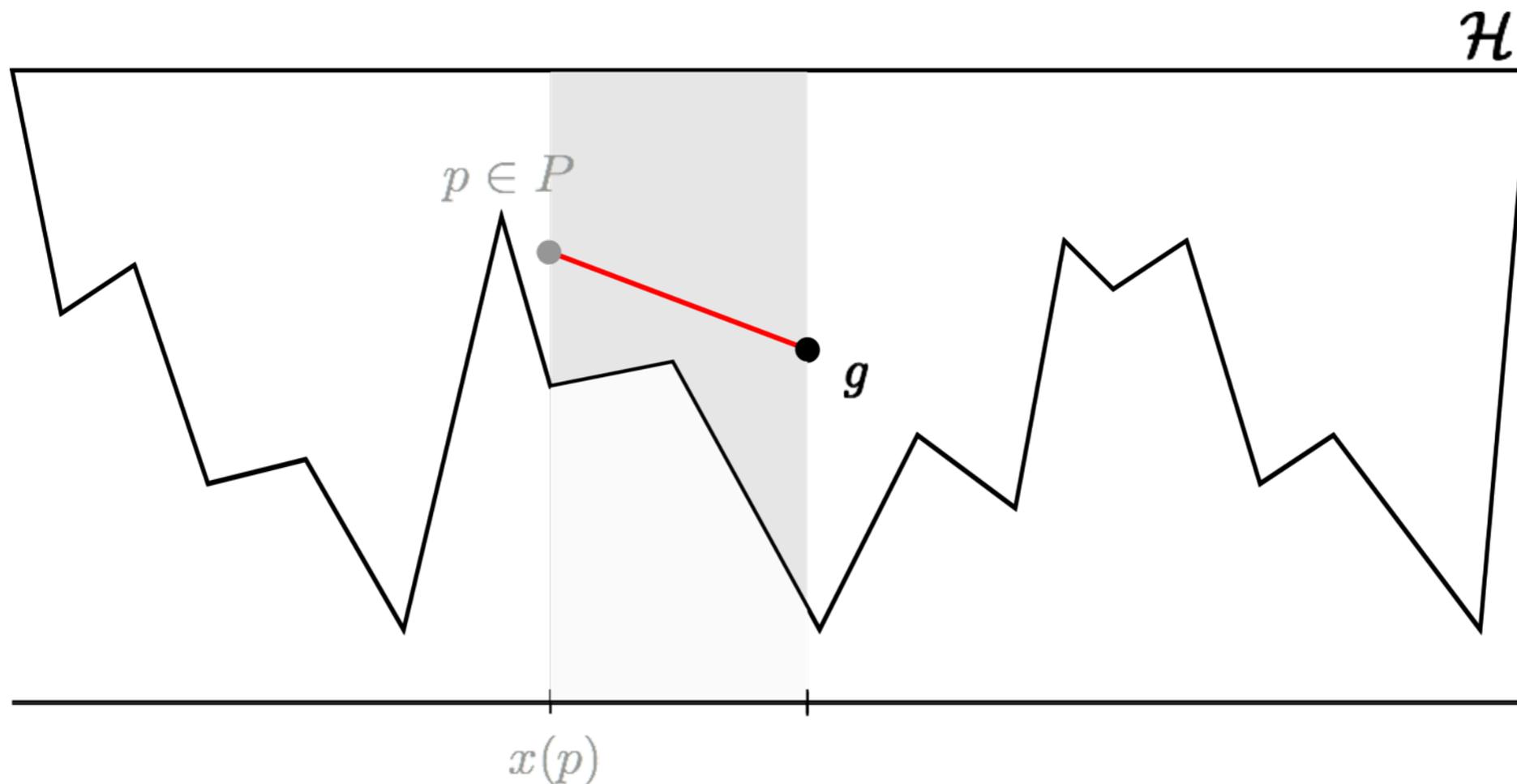
Proof: Consider any optimal guard set G , let $g \in G$ be a guard not located on \mathcal{H}



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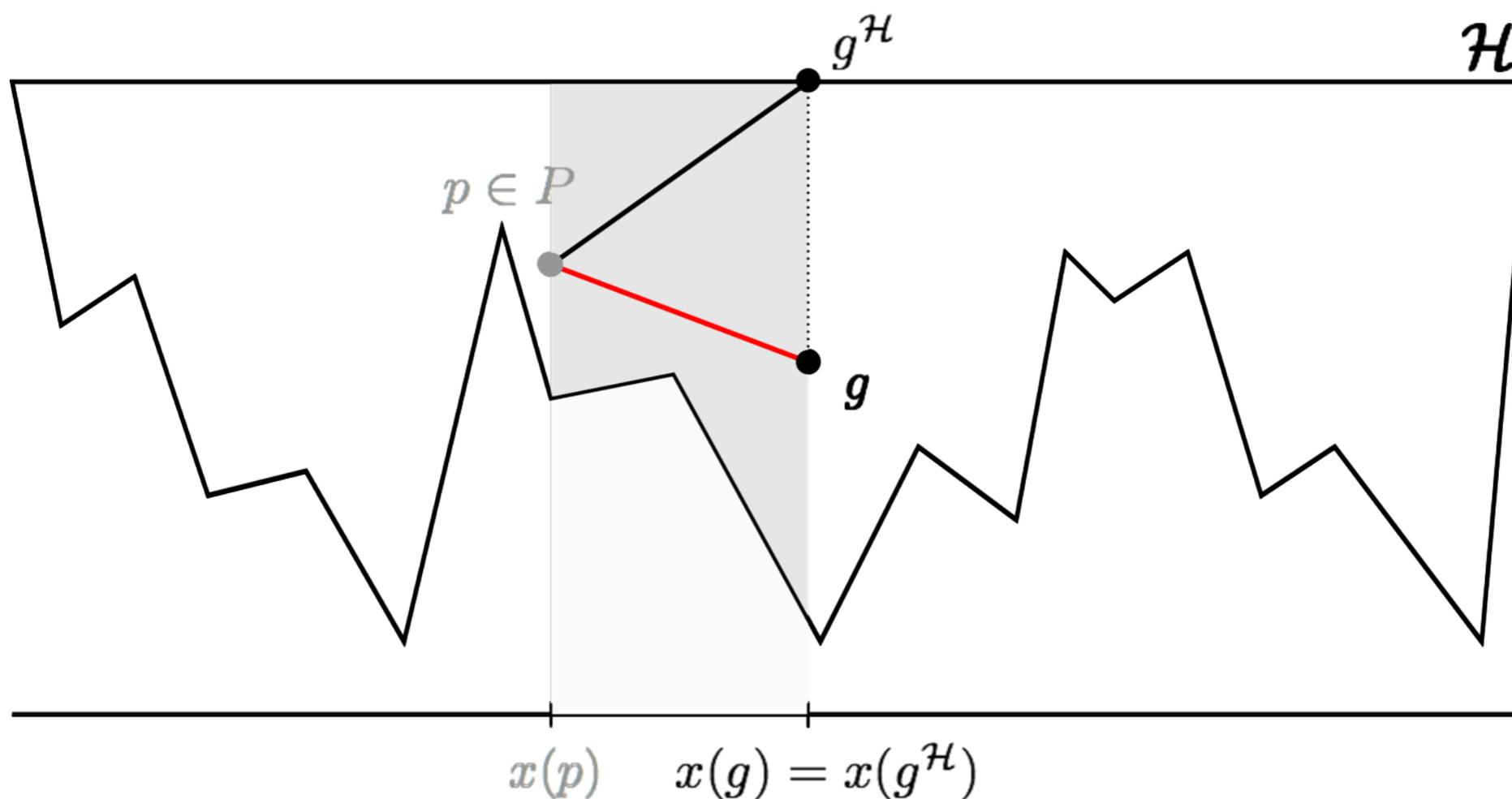
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AGP in uni-monotone polygons

Let P be a uni-monotone polygon, let G be a guard set with $g \in \mathcal{H} \forall g \in G$ that covers $LC(P)$, that is, $LC(P) \subset V_P(G)$. Then G covers all of P , that is, $P \subseteq V_P(G)$.

AGP in uni-monotone polygons

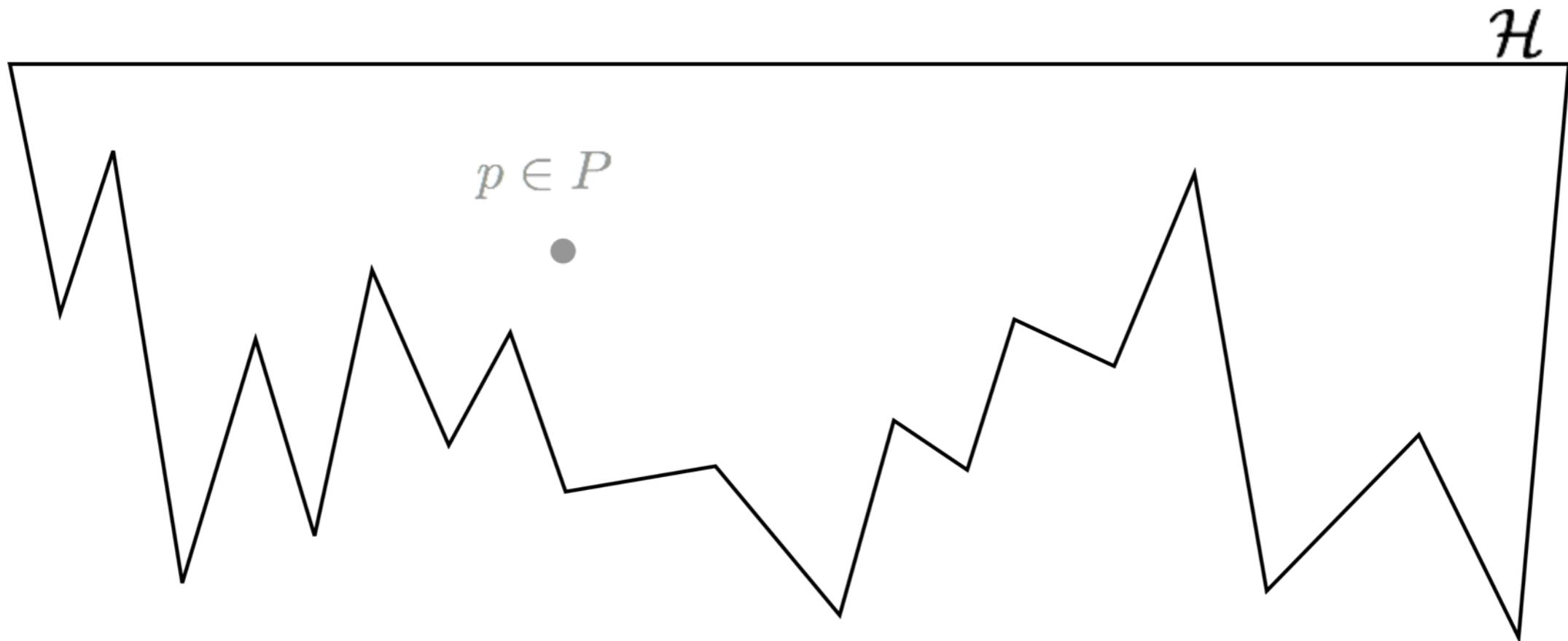
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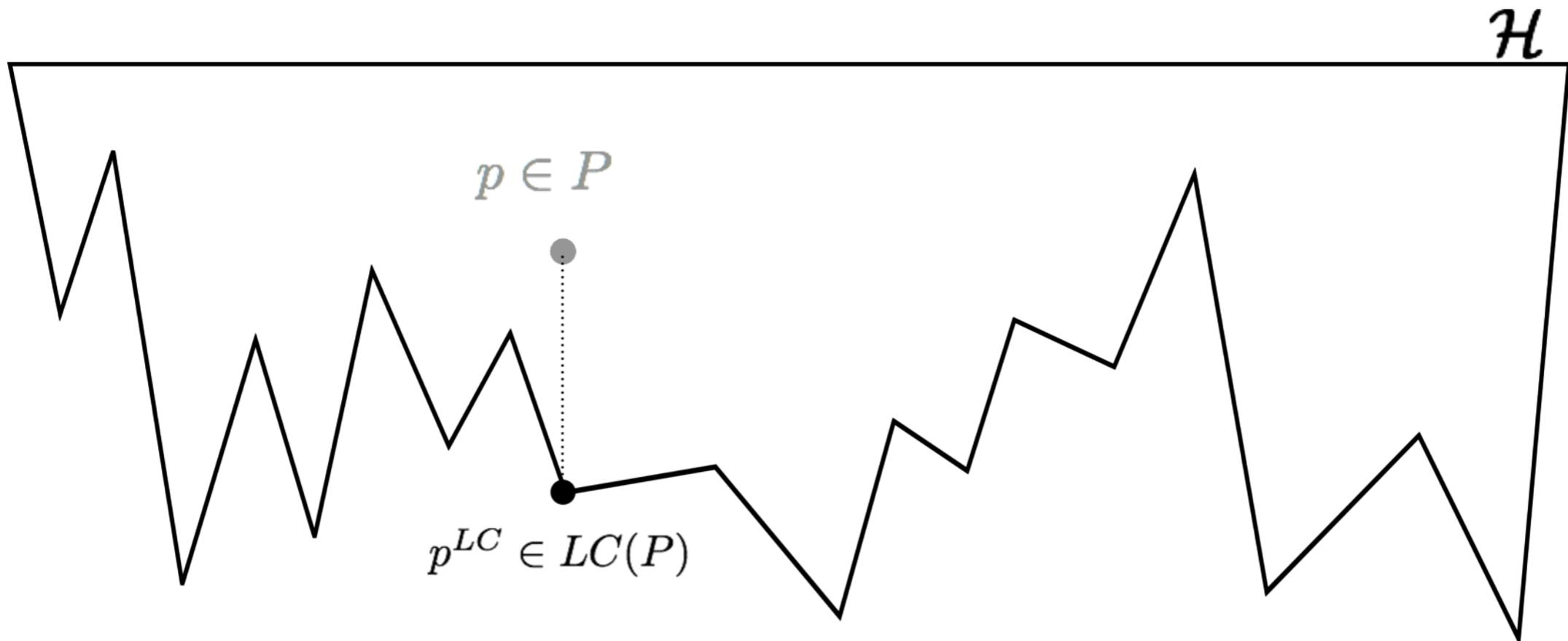
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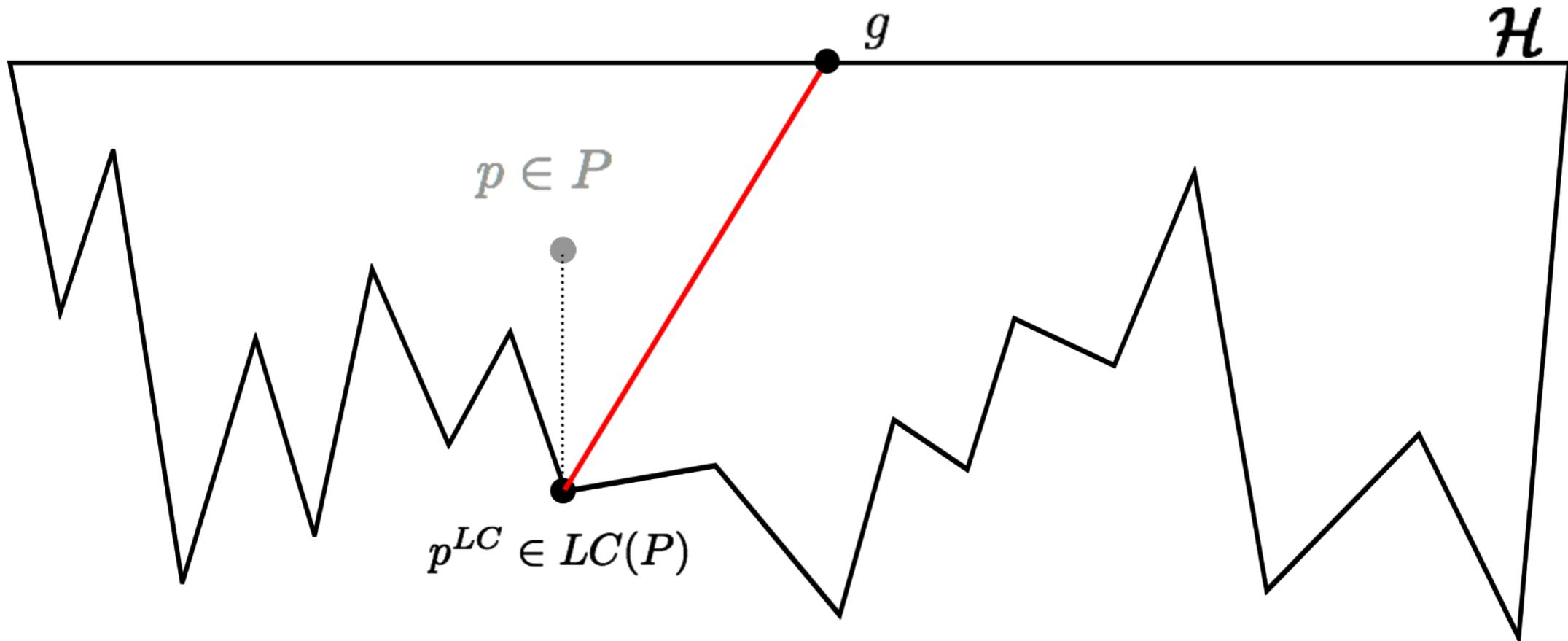
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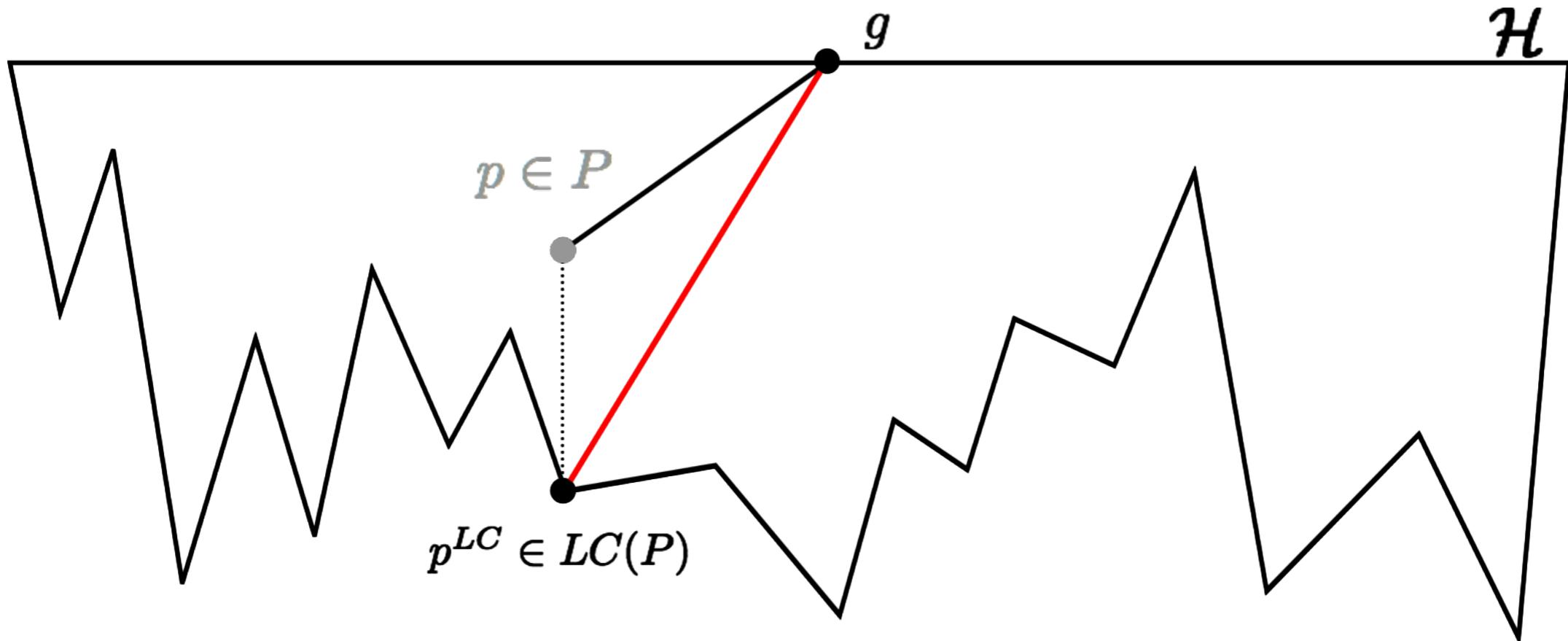
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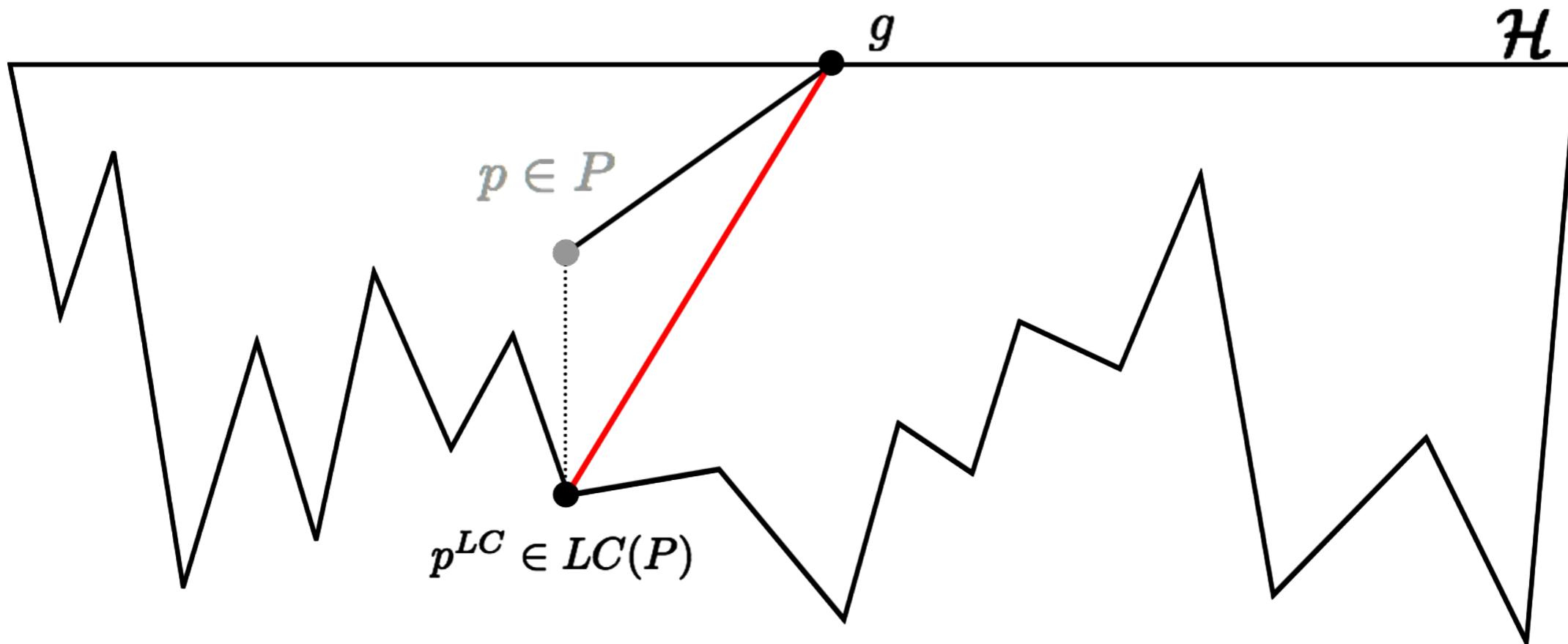
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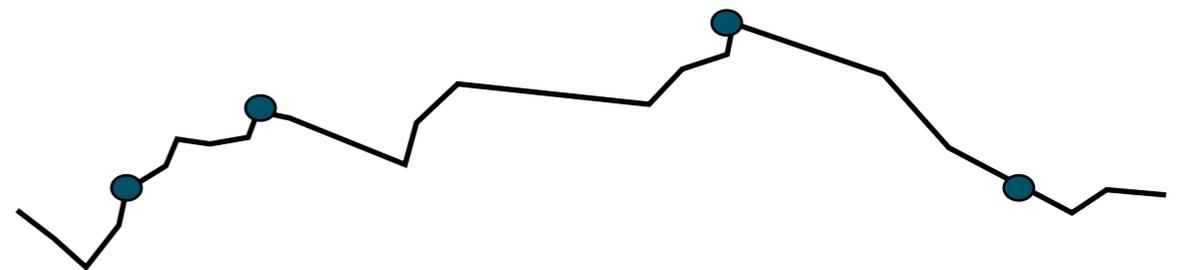
→ ATGP and AGP for uni-monotone polygons equivalent



Art Gallery Problem (AGP)

Given: a polygon P .

Find: a minimum guard set that covers P .



Terrain Guarding Problem (TGP)

Given: a terrain T .

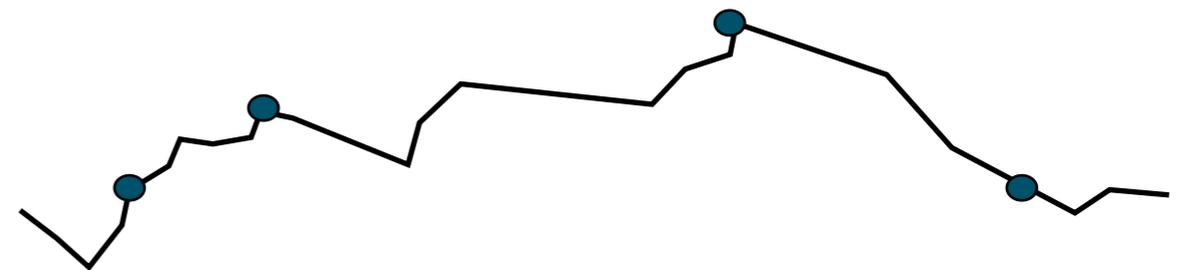
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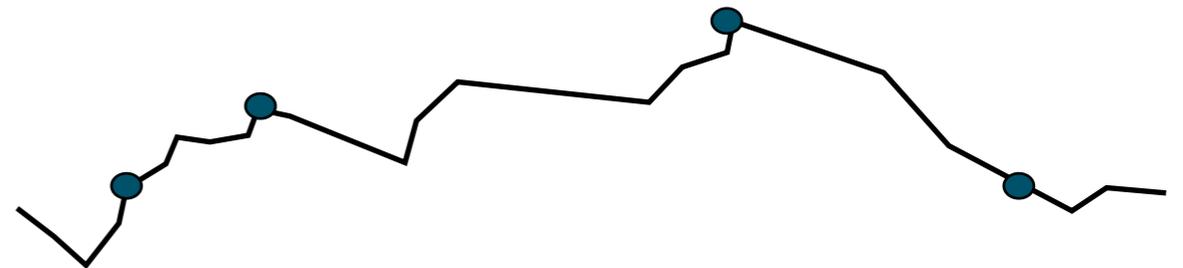


Art Gallery Problem (AGP)

Given: a polygon P .

A minimum guard set that covers P .

NP-hard, even in monotone polygons



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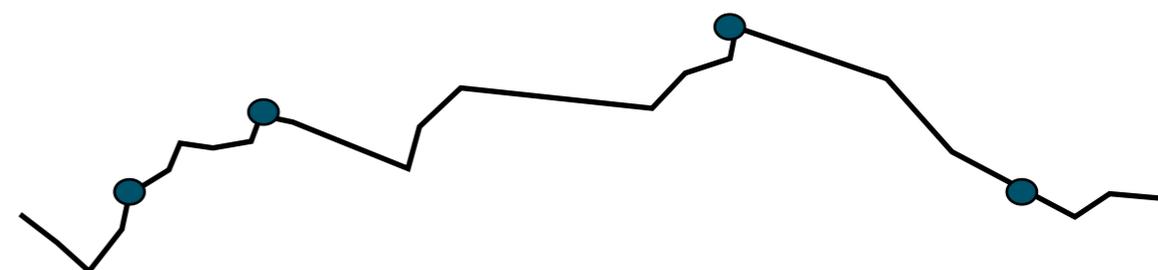


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Art Gallery Problem (AGP) in Uni-Monotone Polygons

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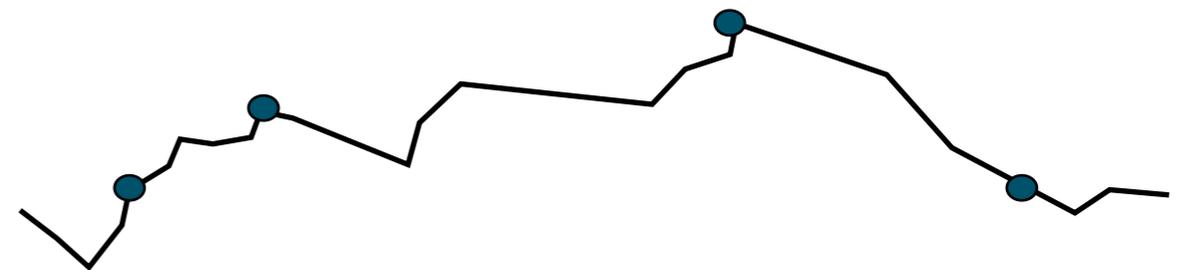
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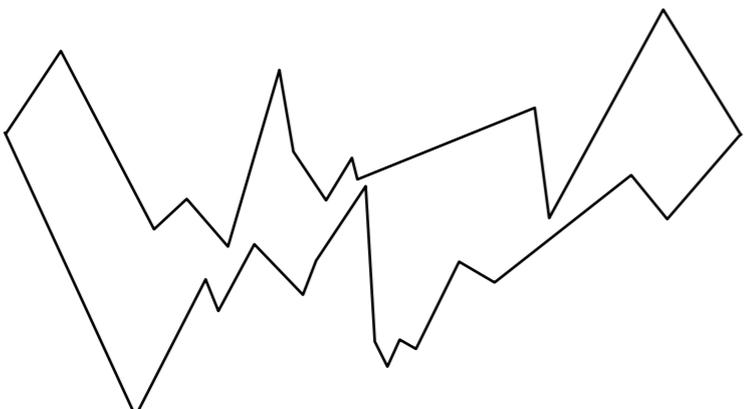
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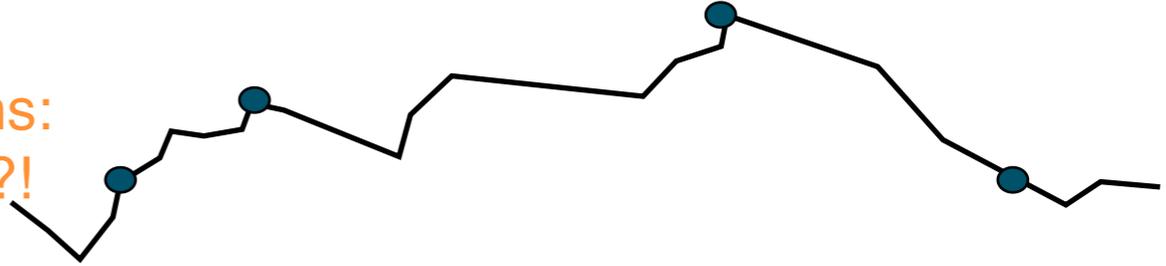
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Our Problems:
“Inbetween”?!



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Both polytime



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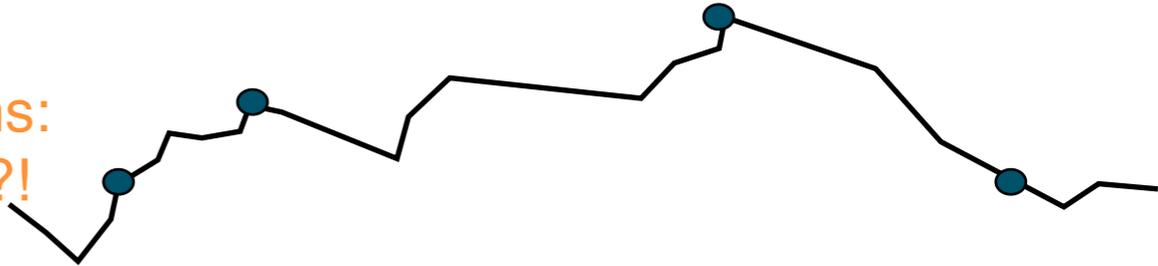


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NP-hard, even in monotone polygons

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- A polytime algorithm for AGTP and AGP in uni-monotone polygons

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- Uni-monotone polygons are perfect - first non-trivial class

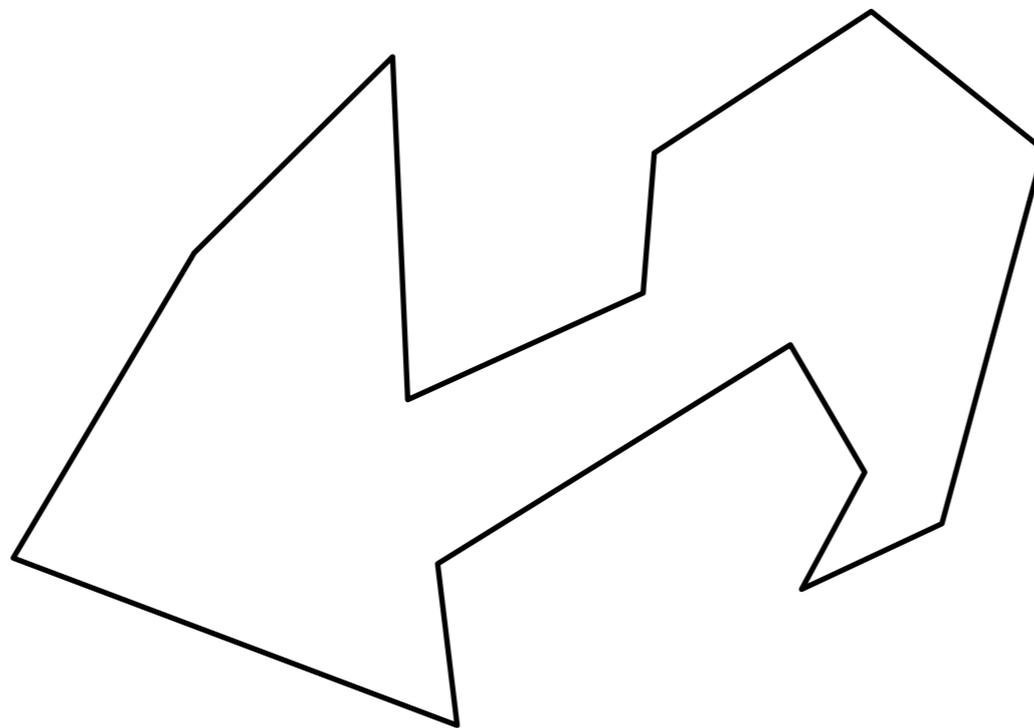
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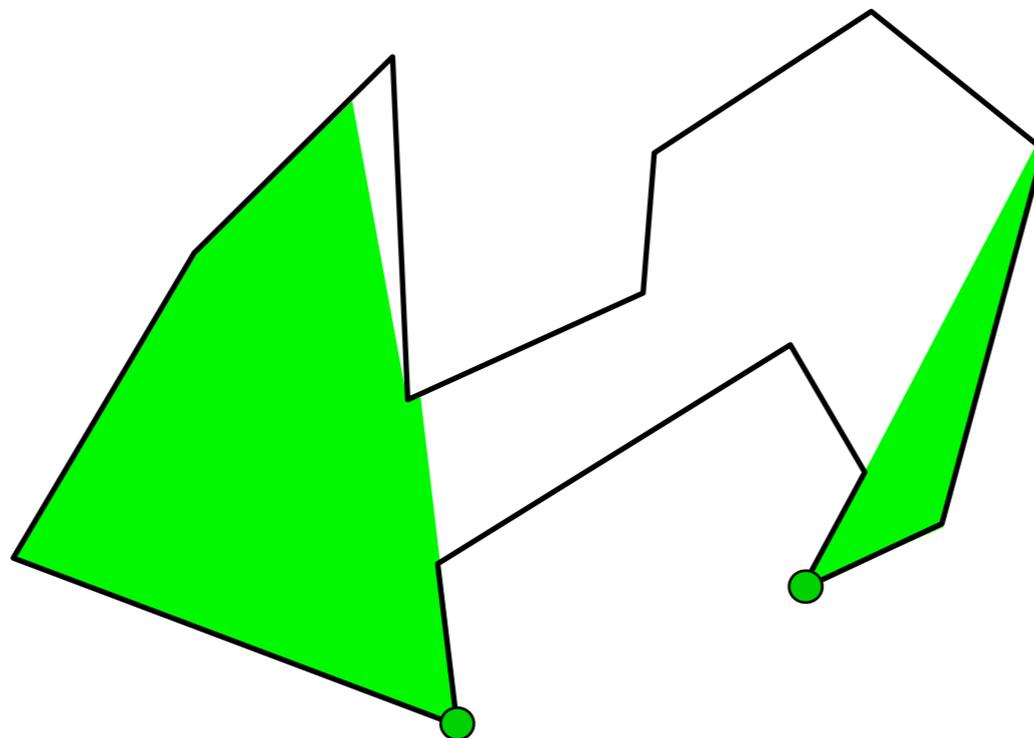
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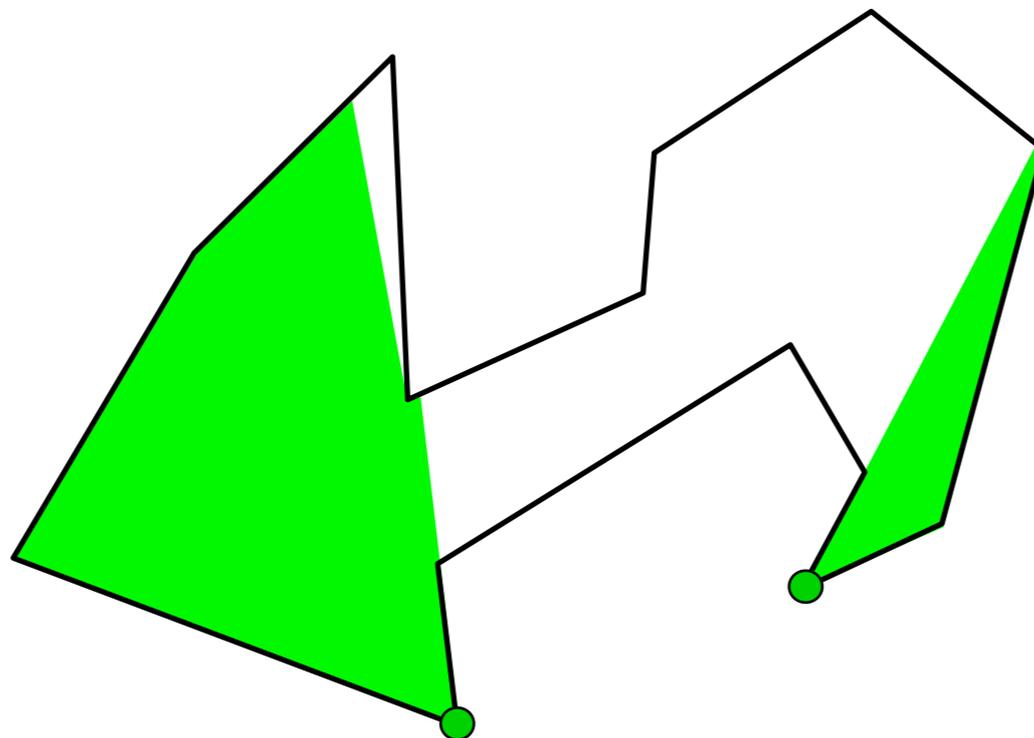


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A **maximum witness set** W_{opt} is a witness set of maximum cardinality, $|W_{opt}| = \max\{|W|: \text{witness set } W\}$.



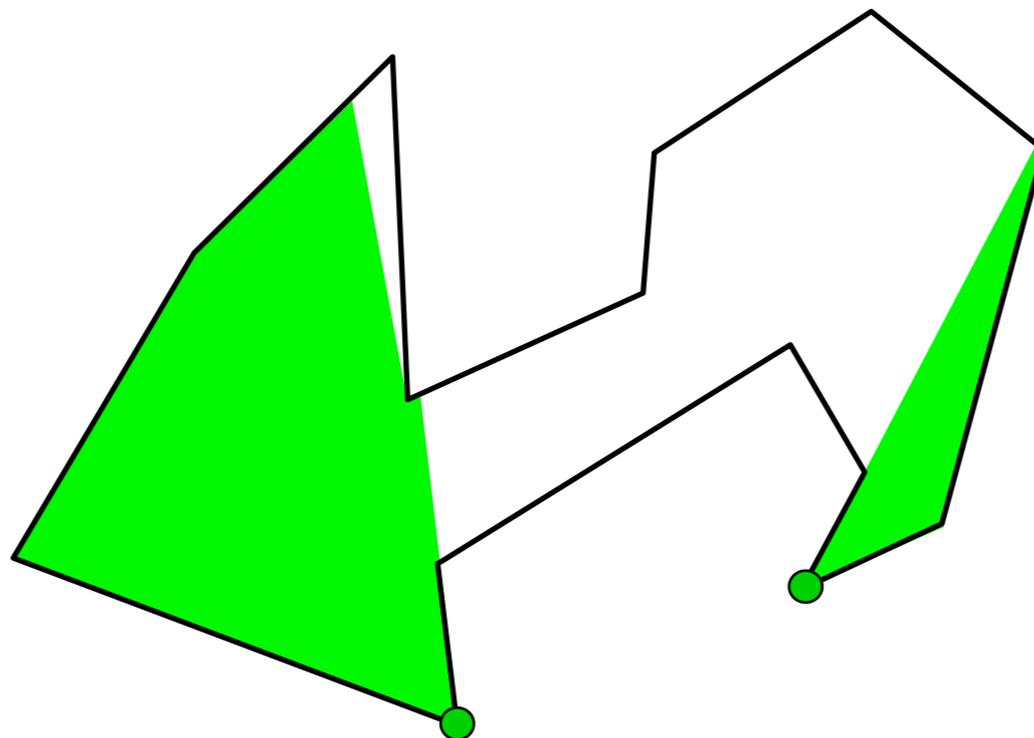
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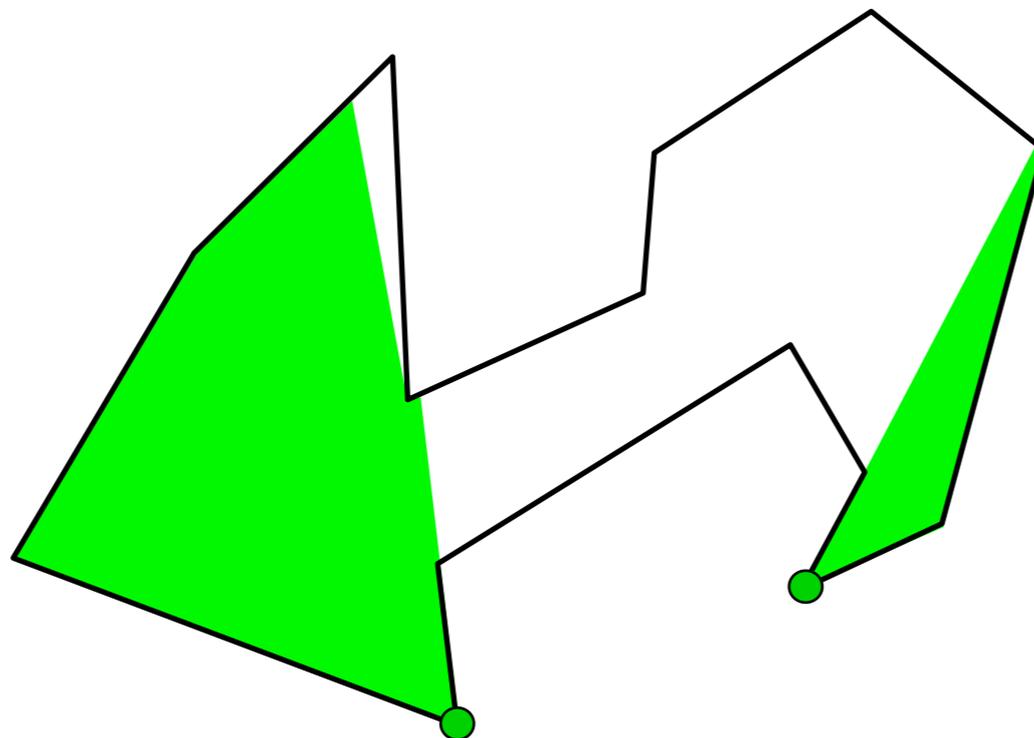
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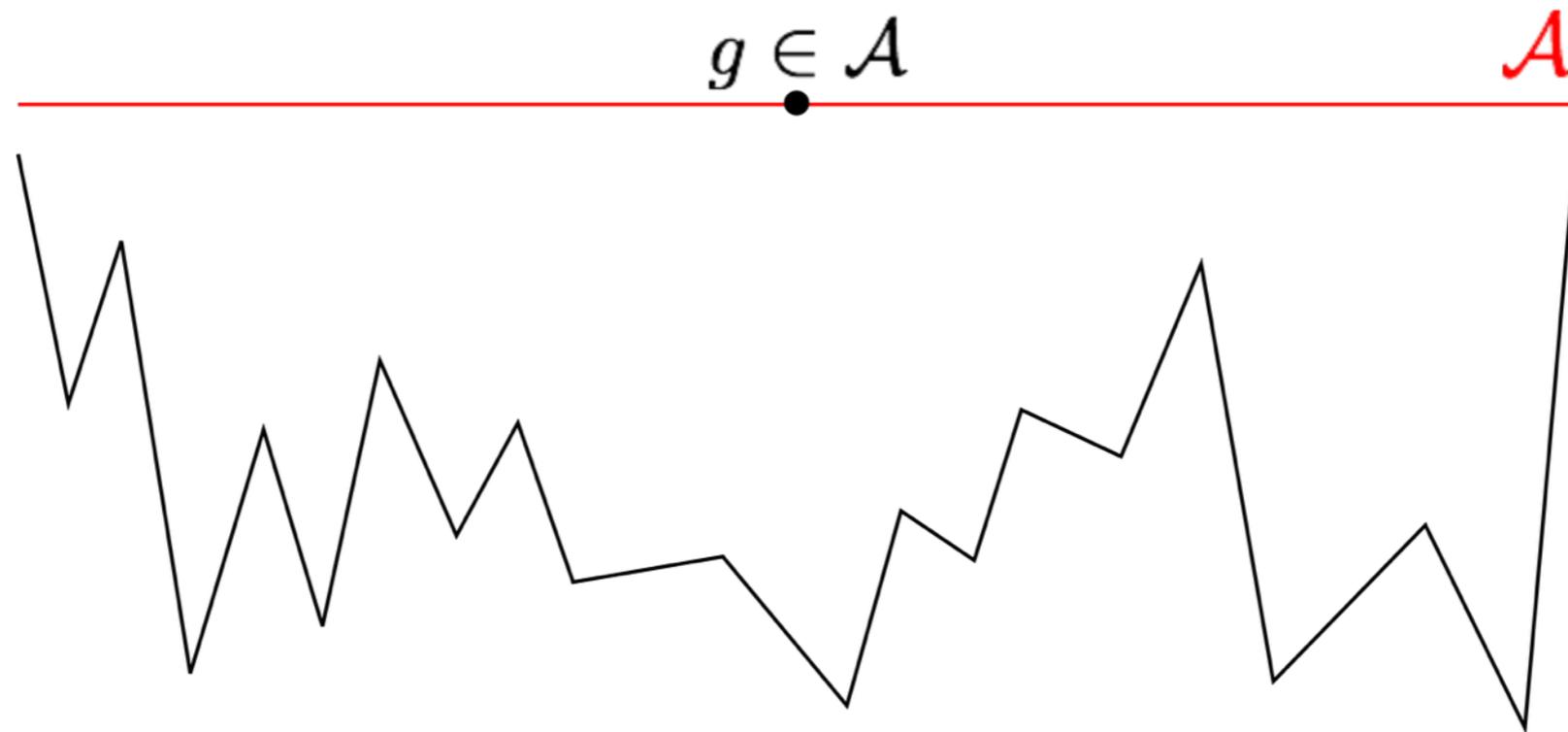


Altitude Terrain Guarding Problem

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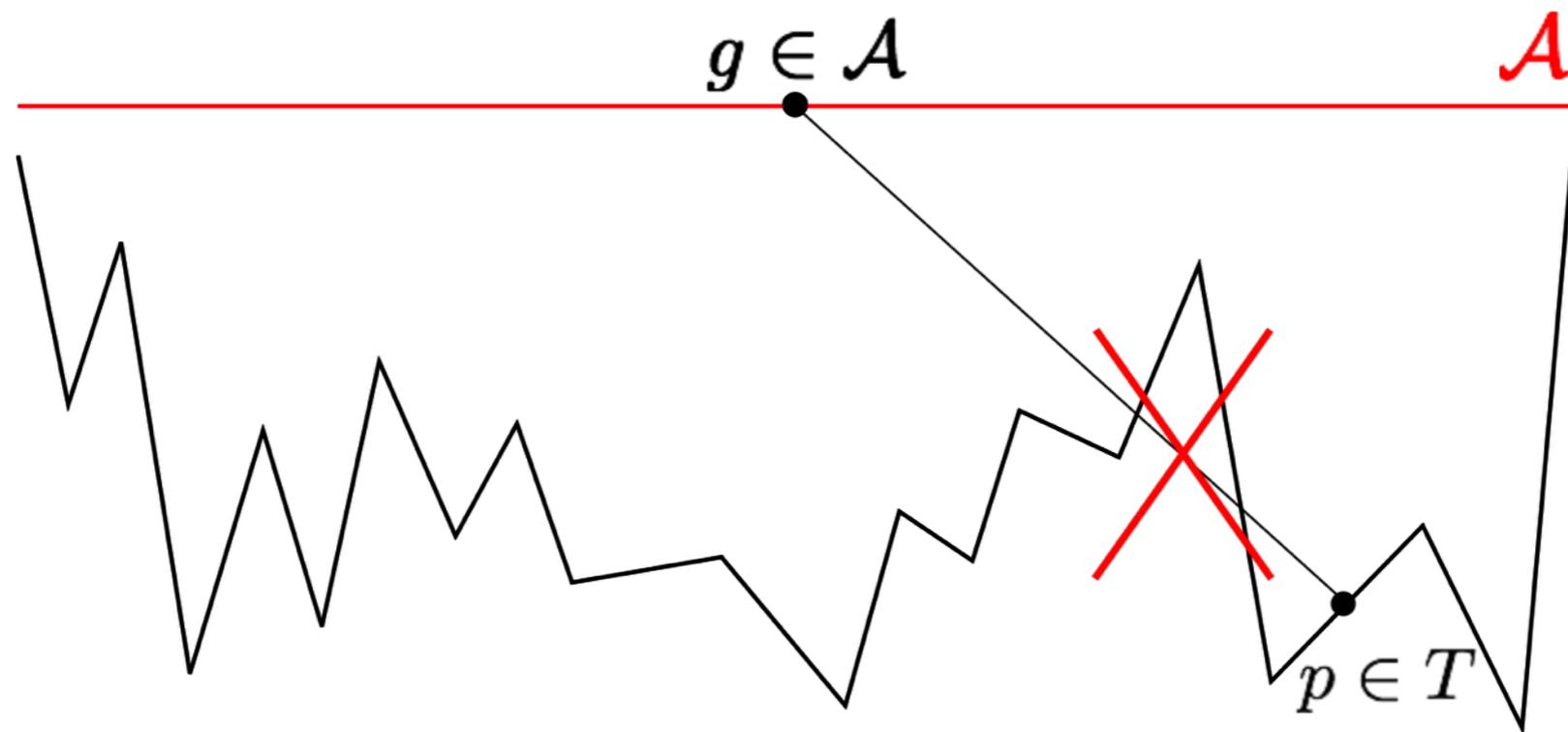
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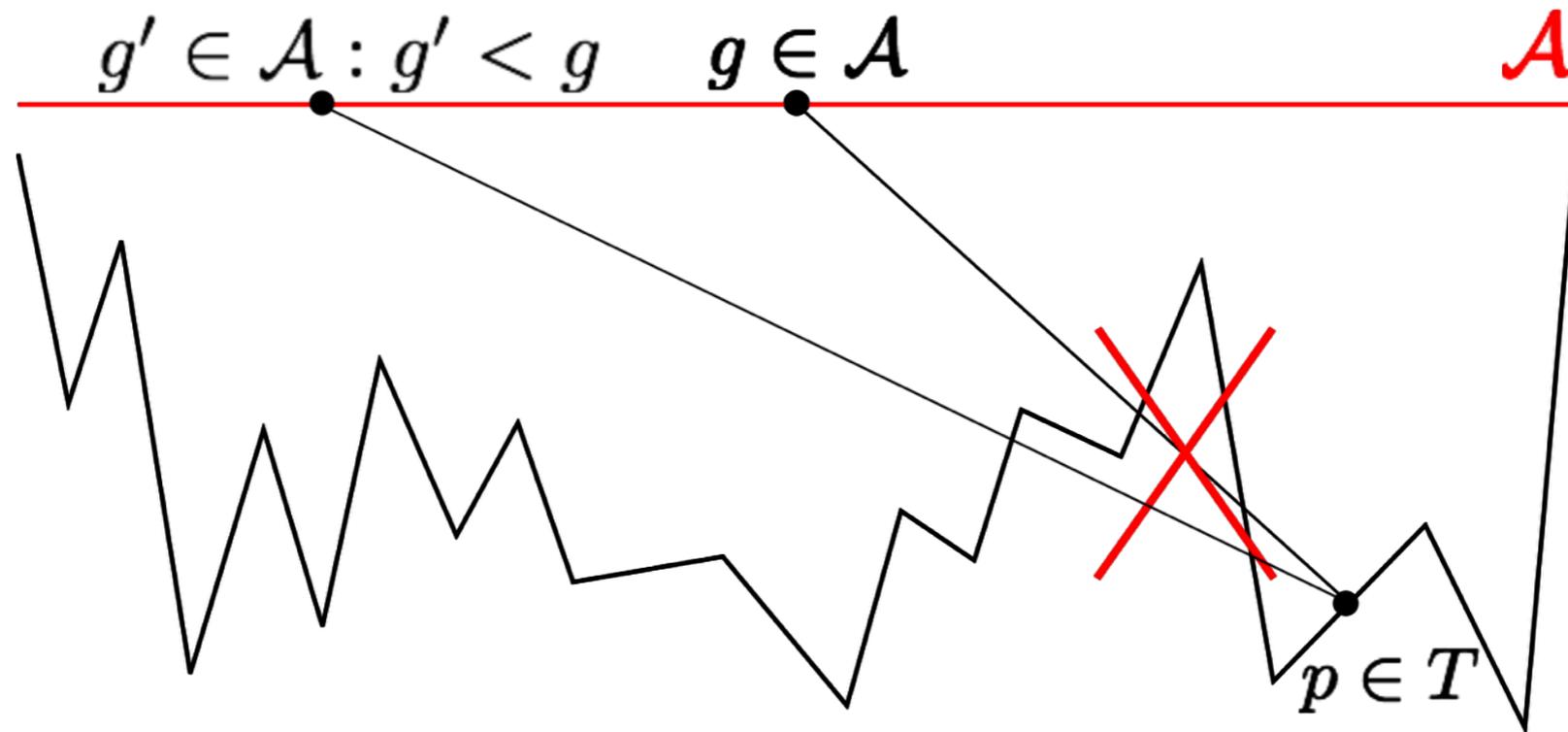
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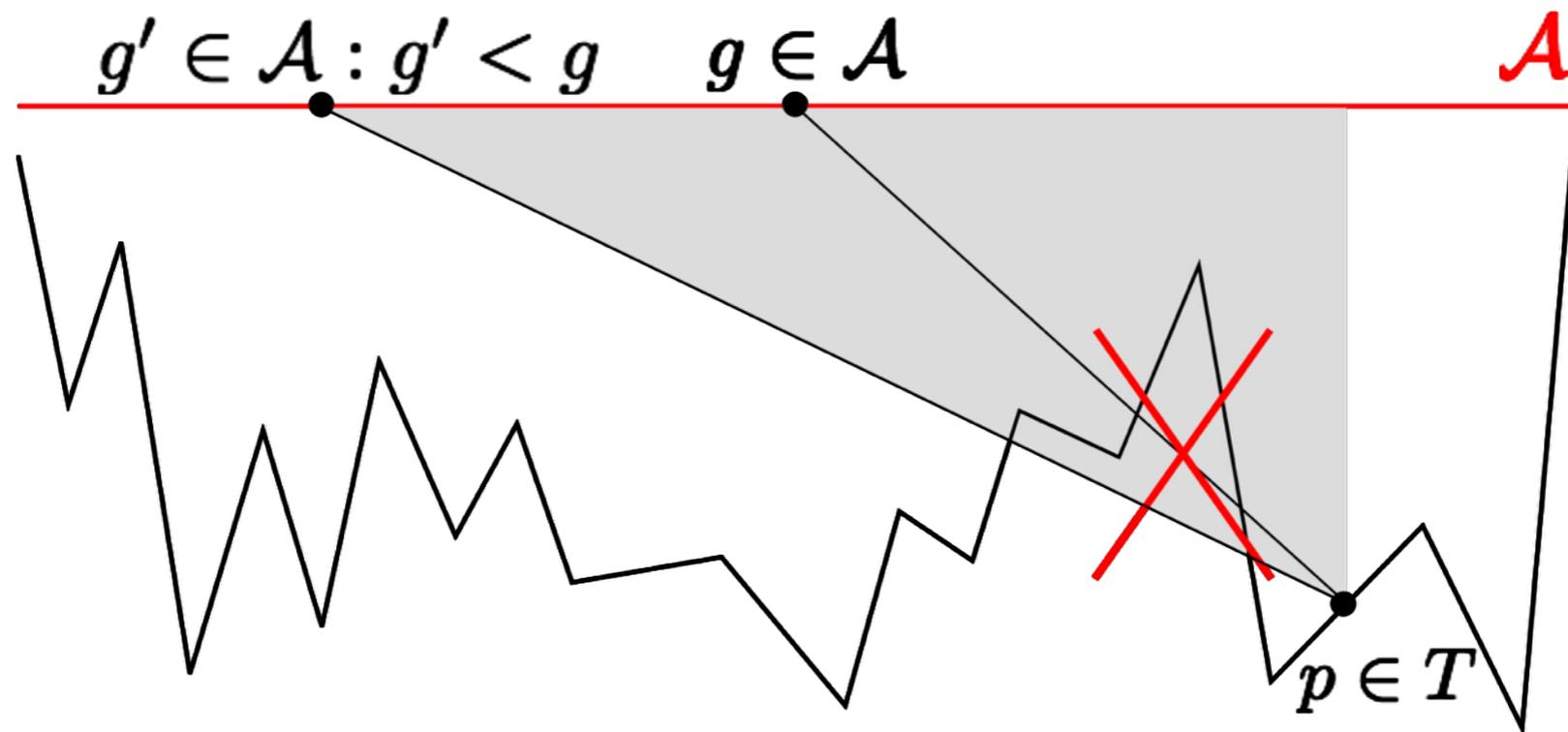
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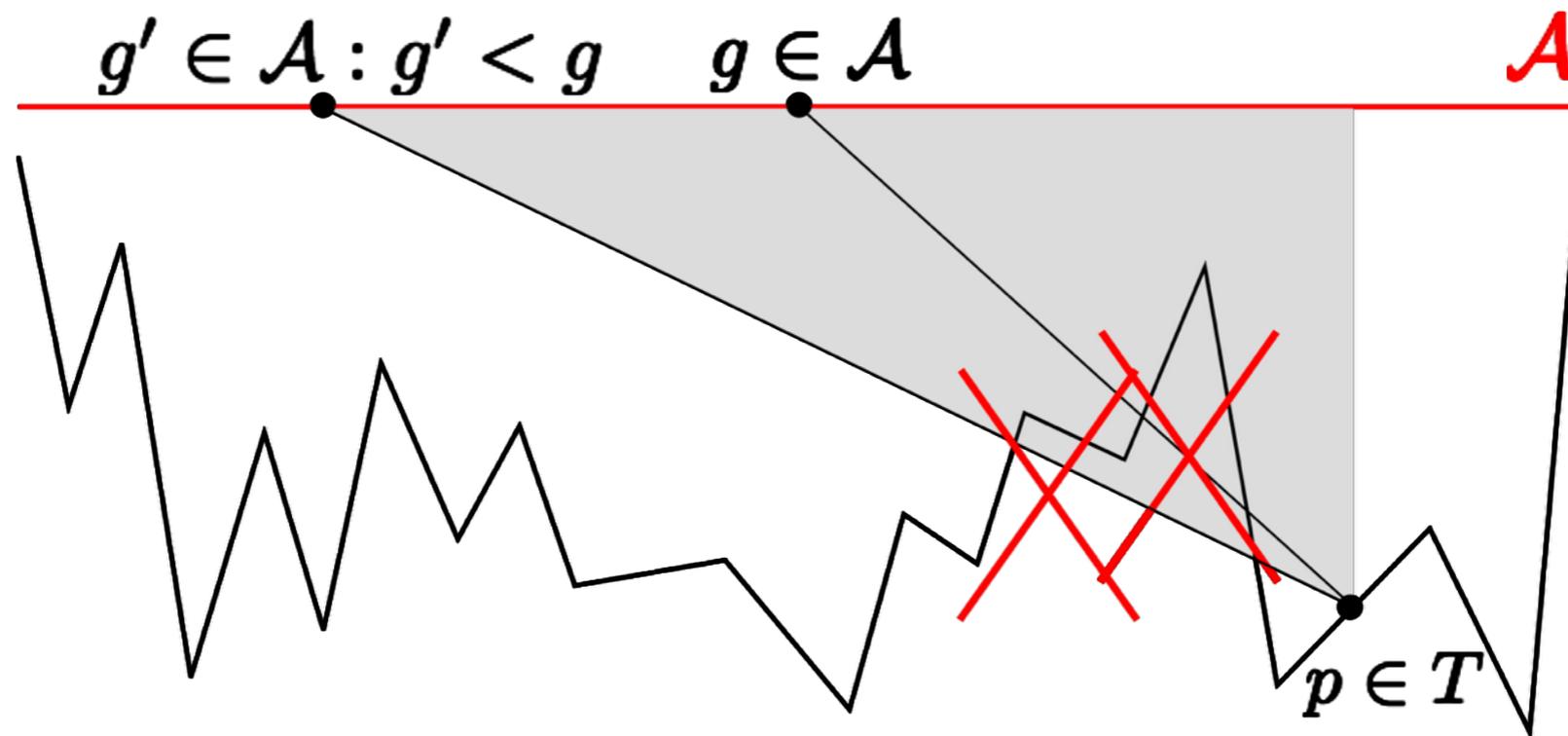
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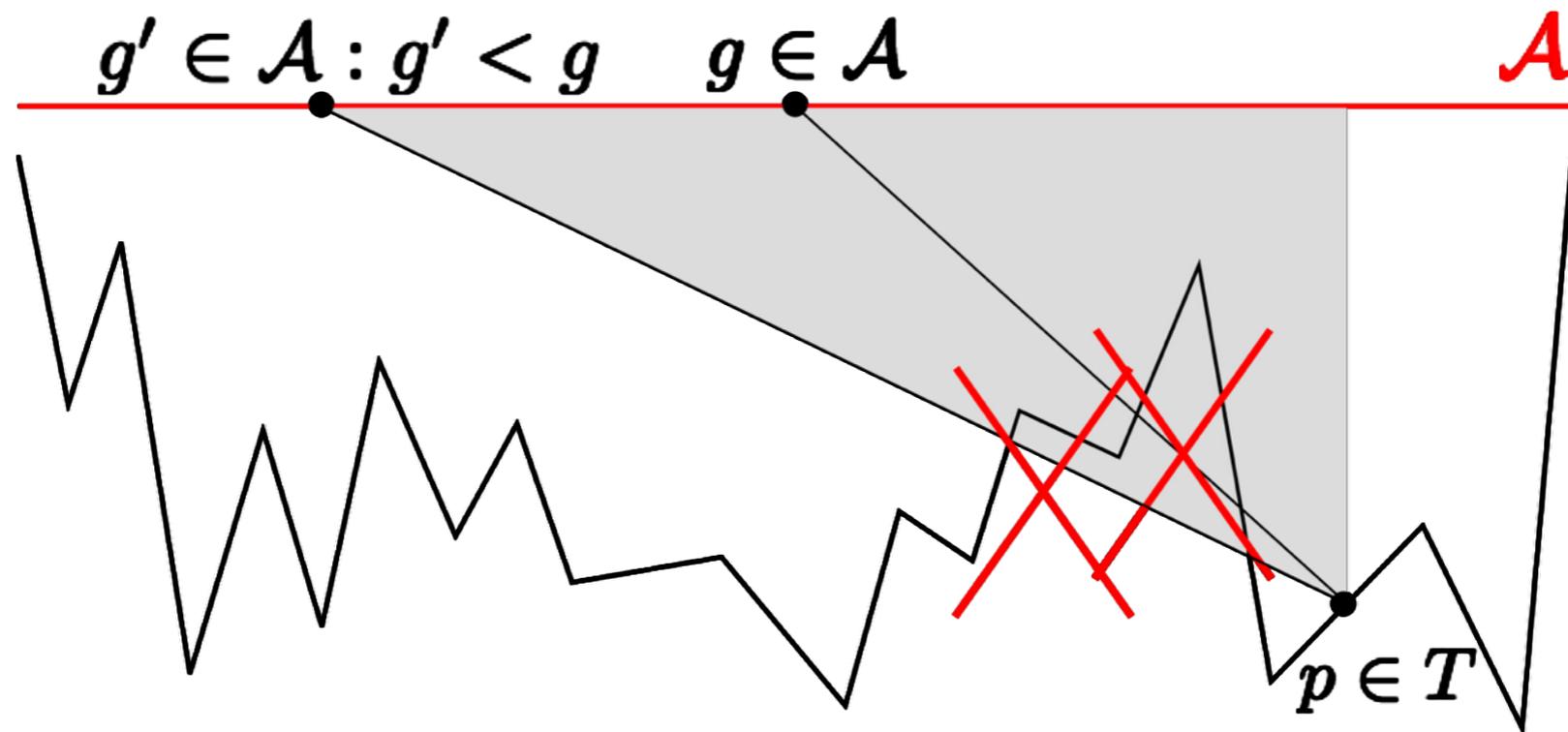
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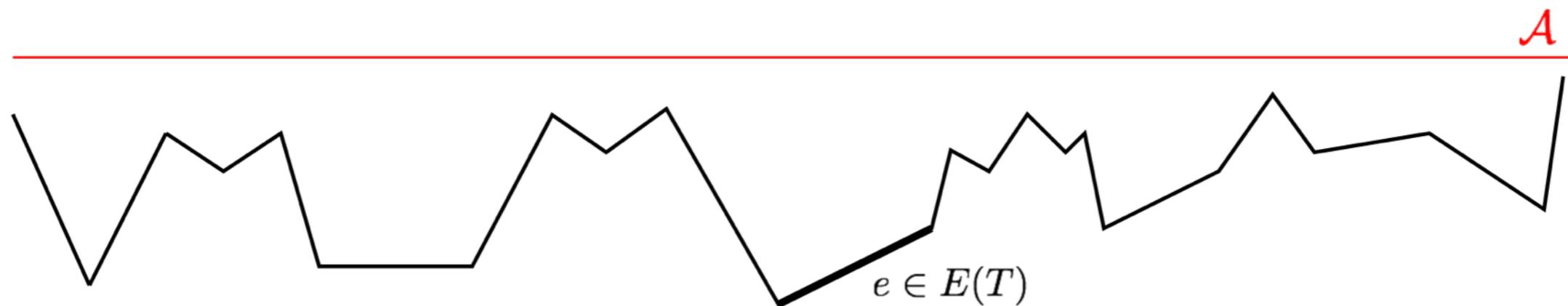


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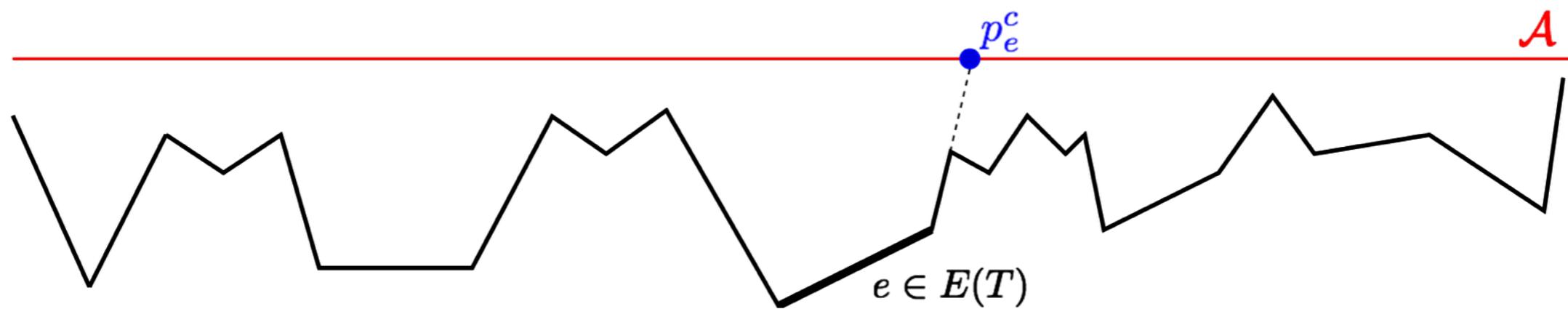
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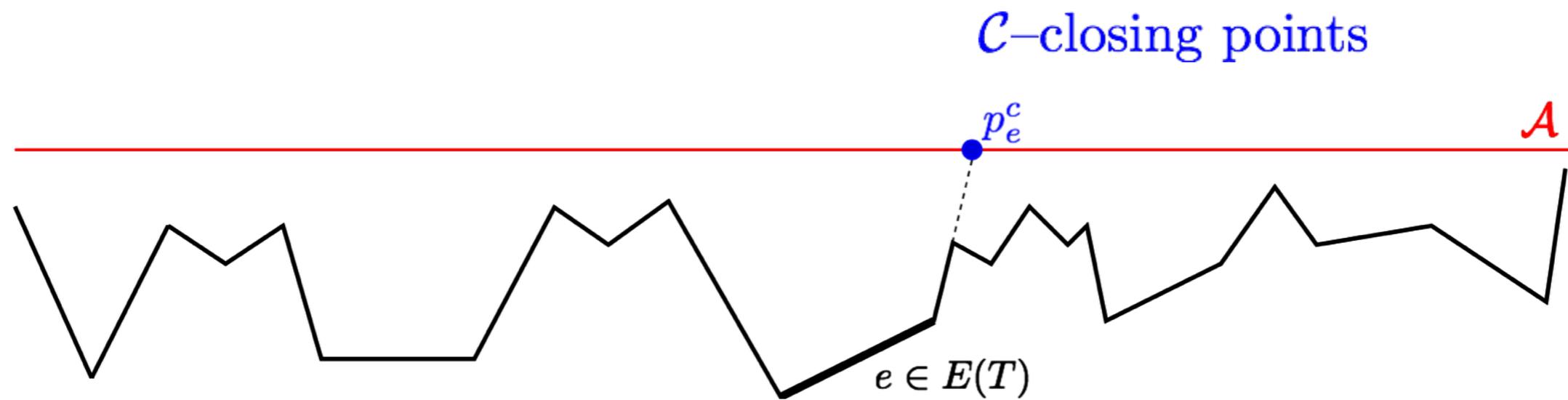
Sweep Algorithm



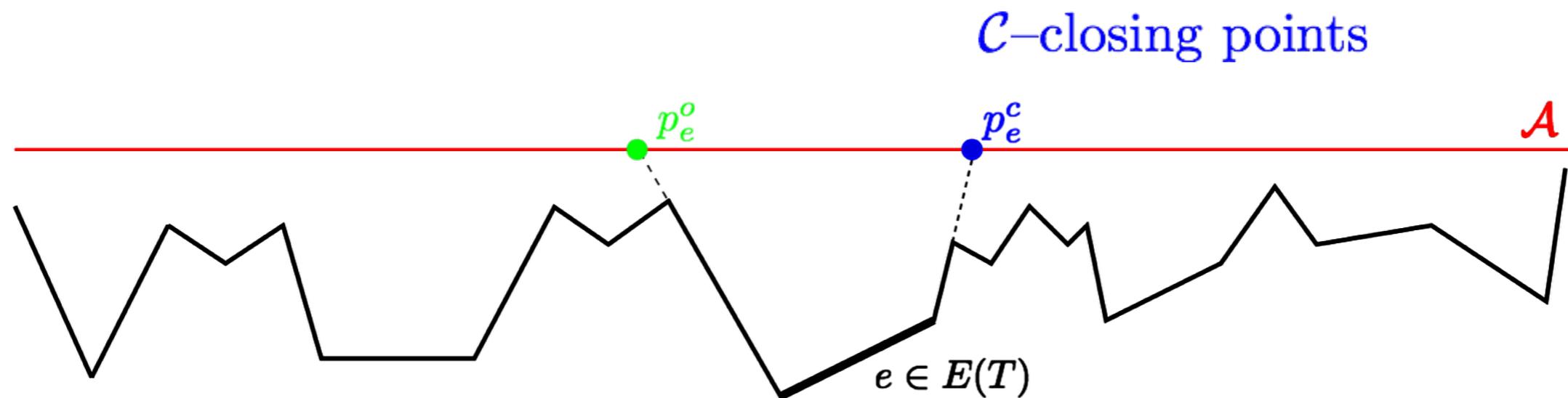
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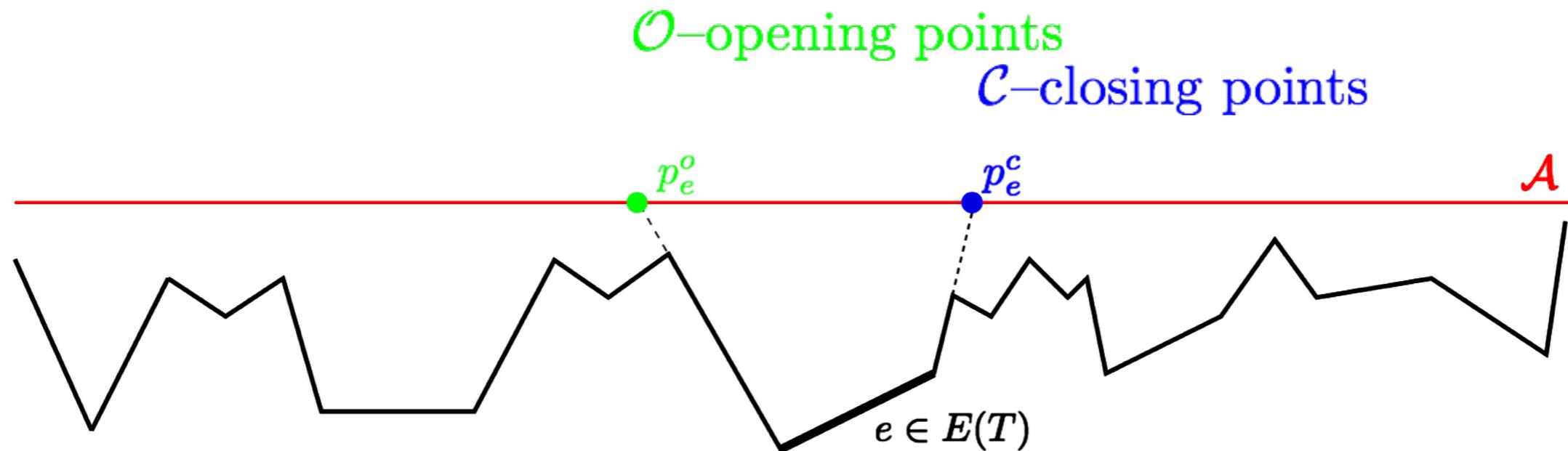
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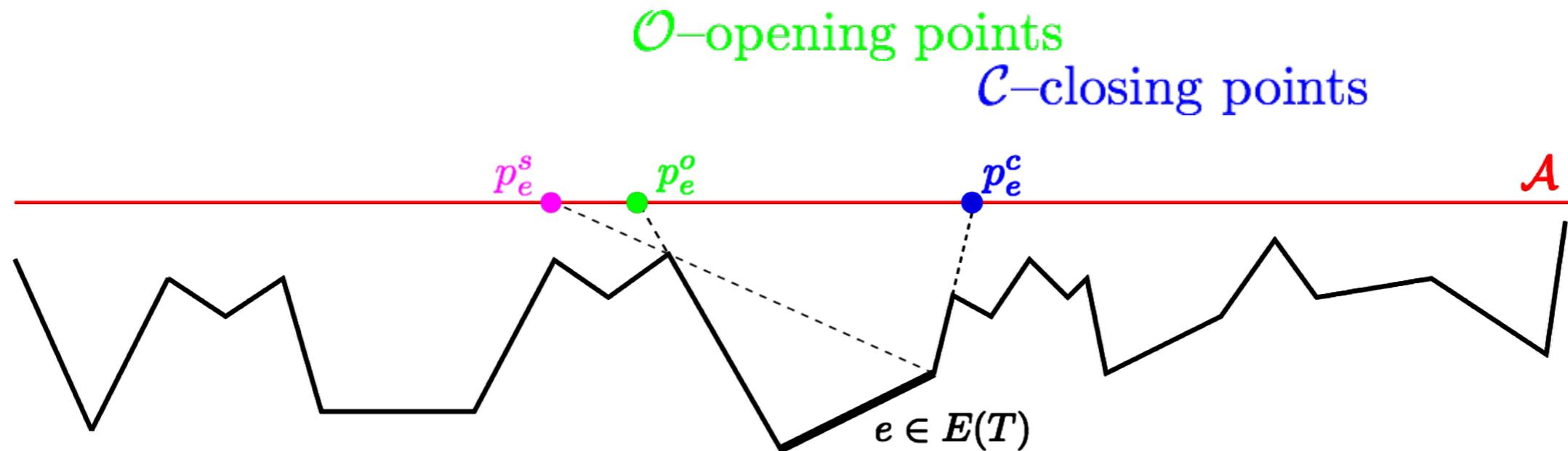
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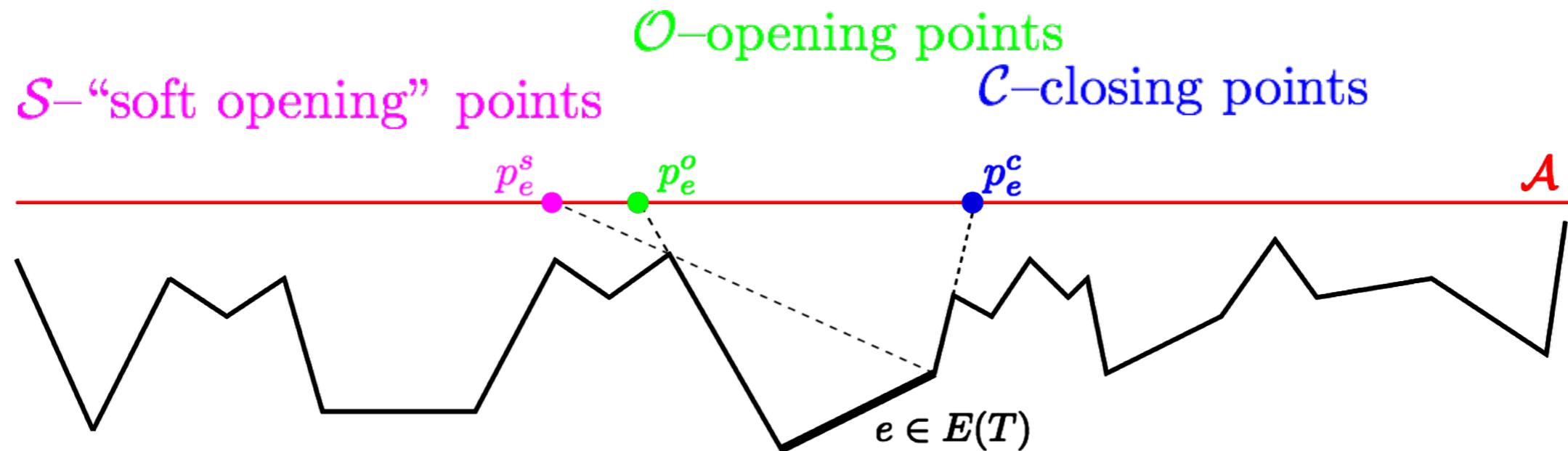
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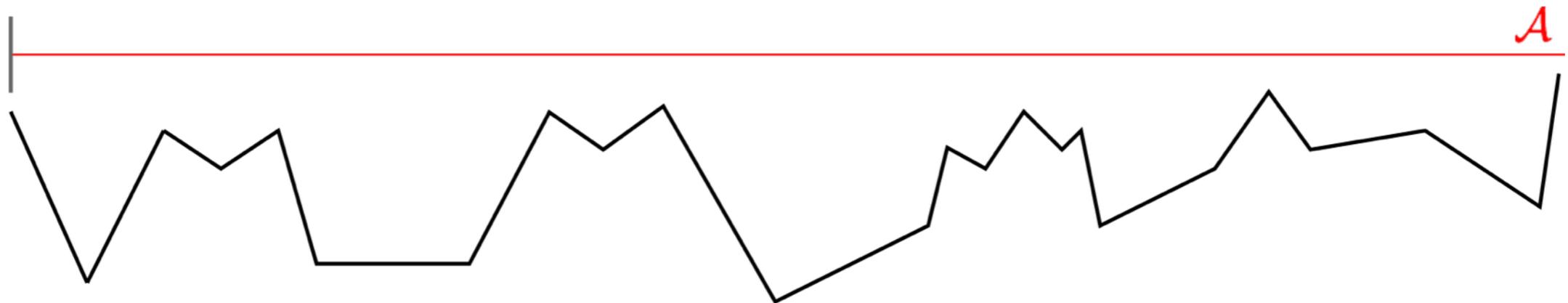


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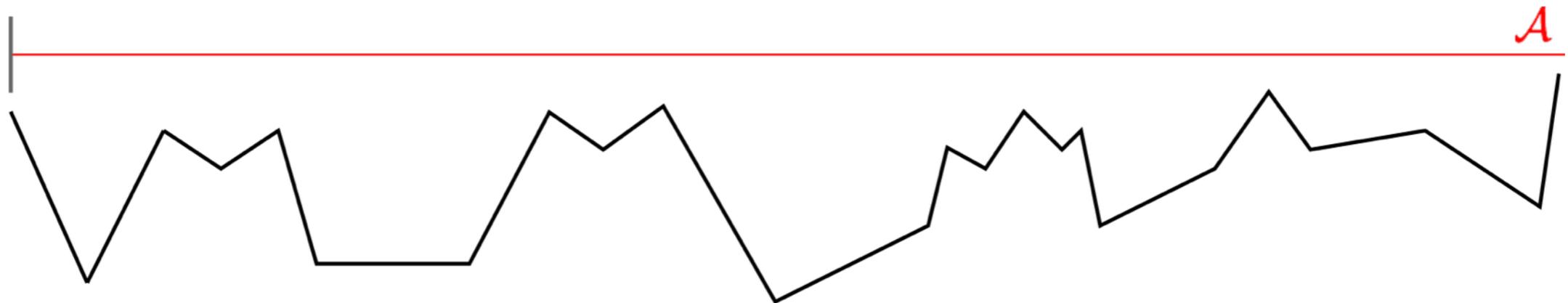
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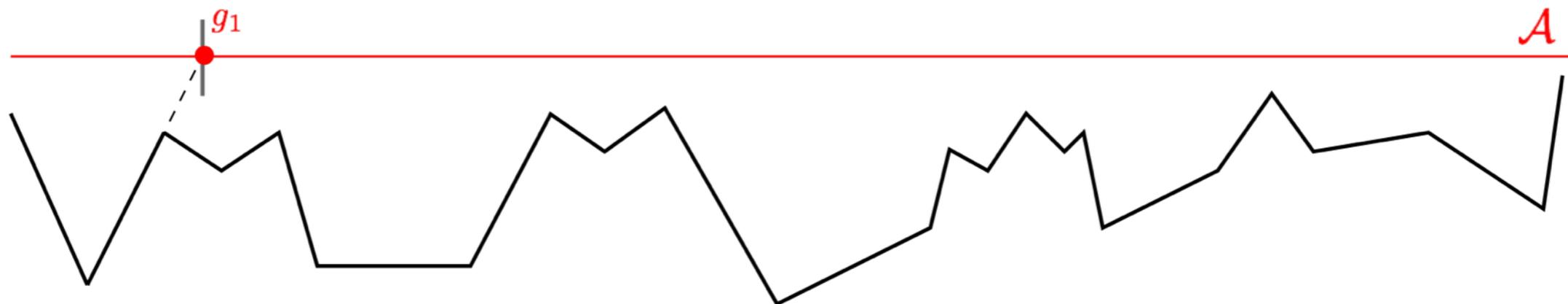
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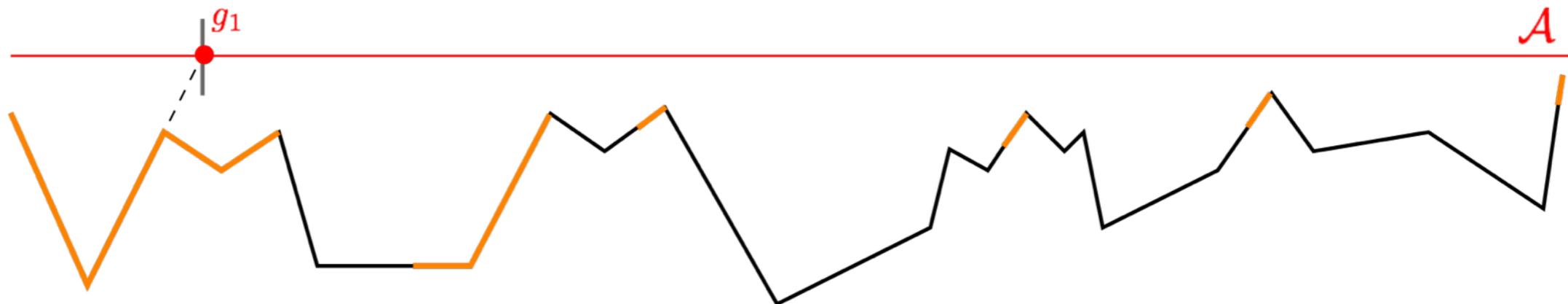
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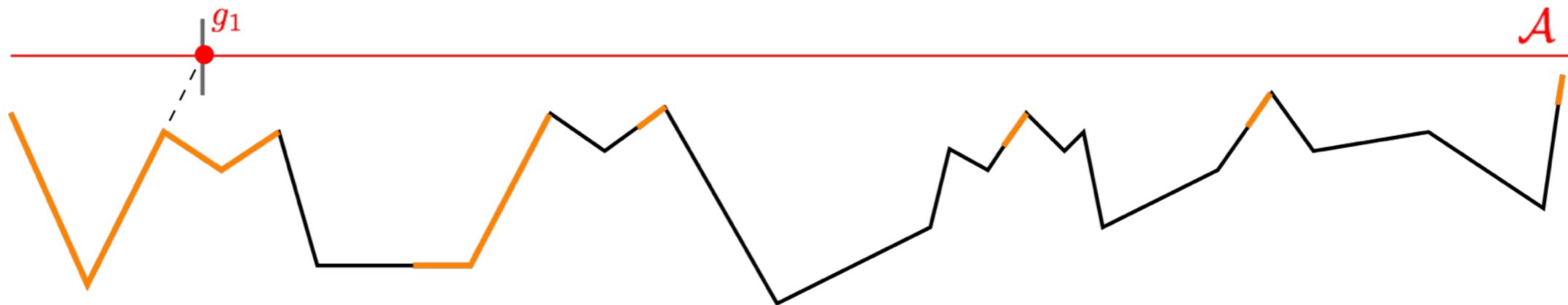
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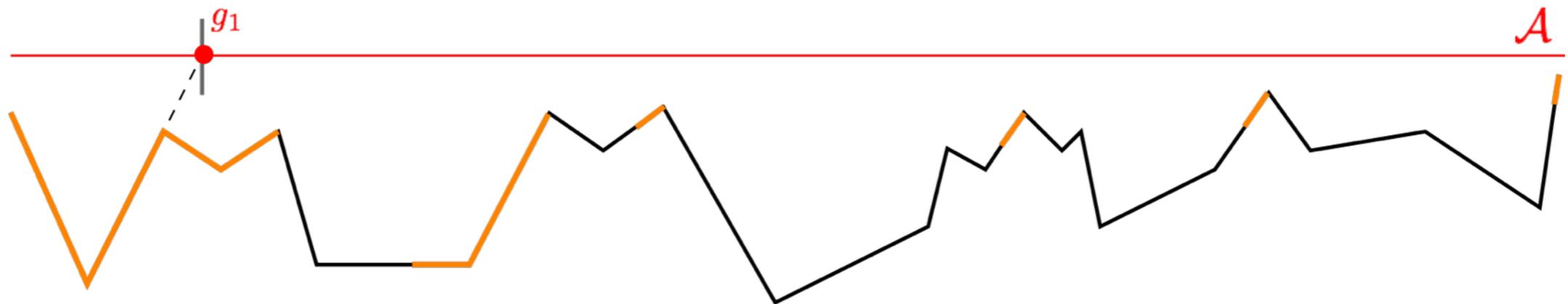
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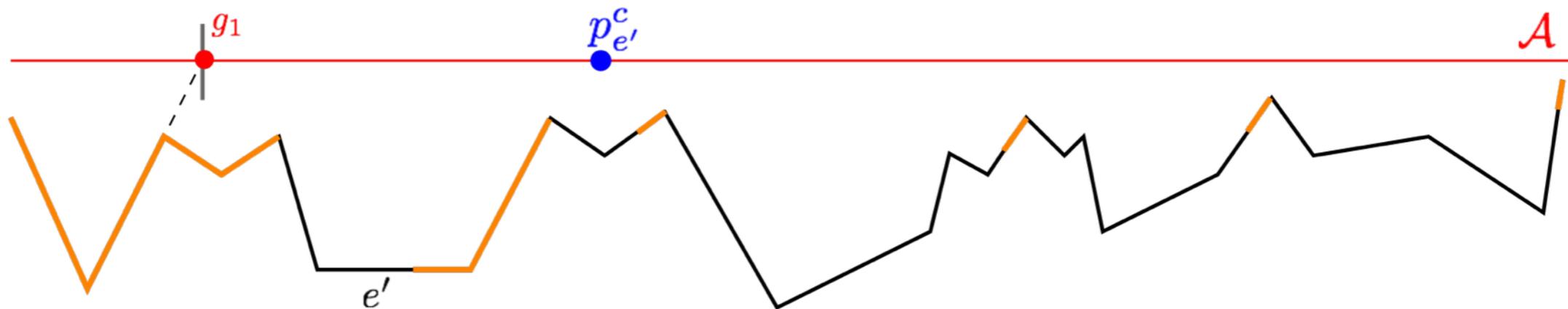
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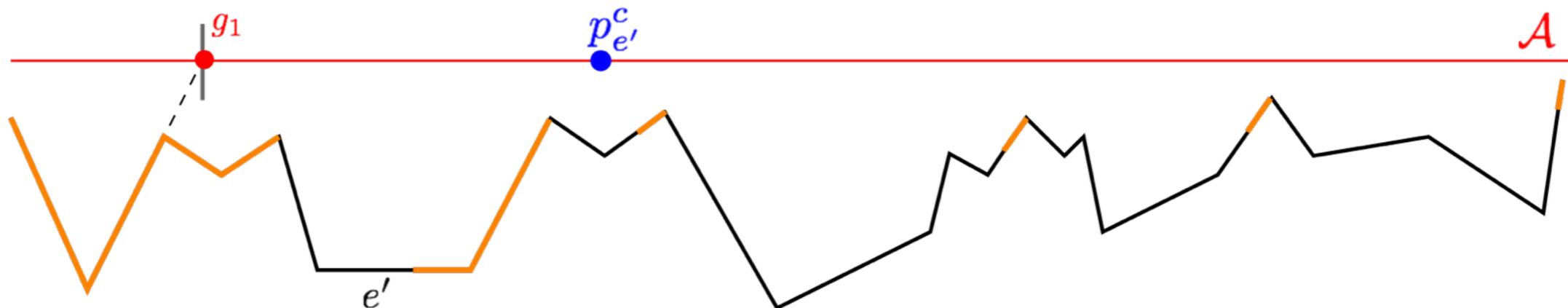
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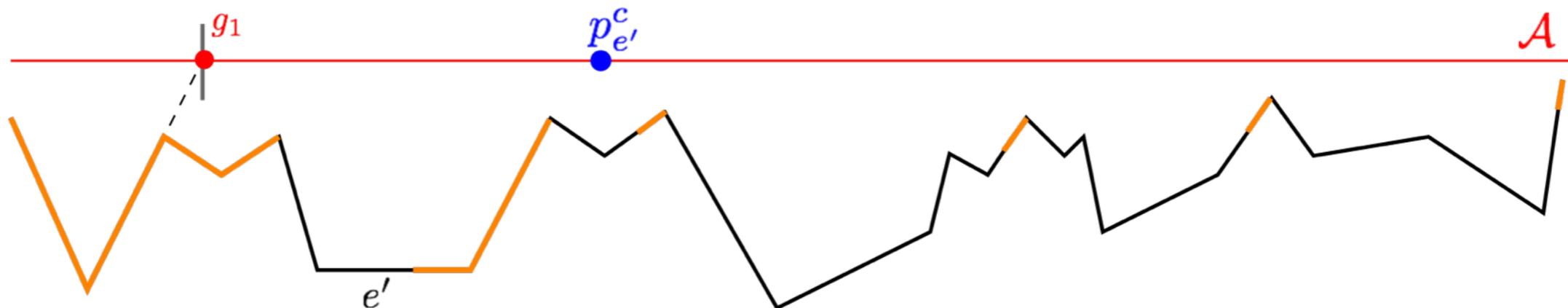
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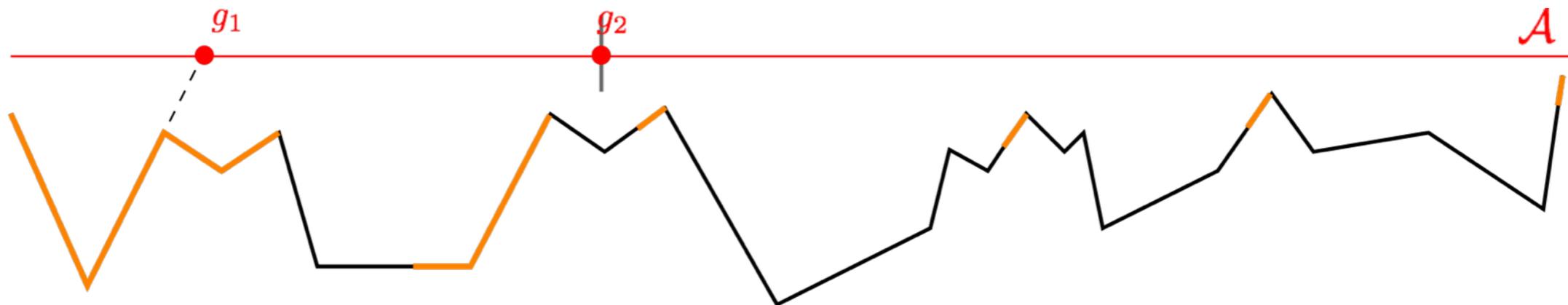
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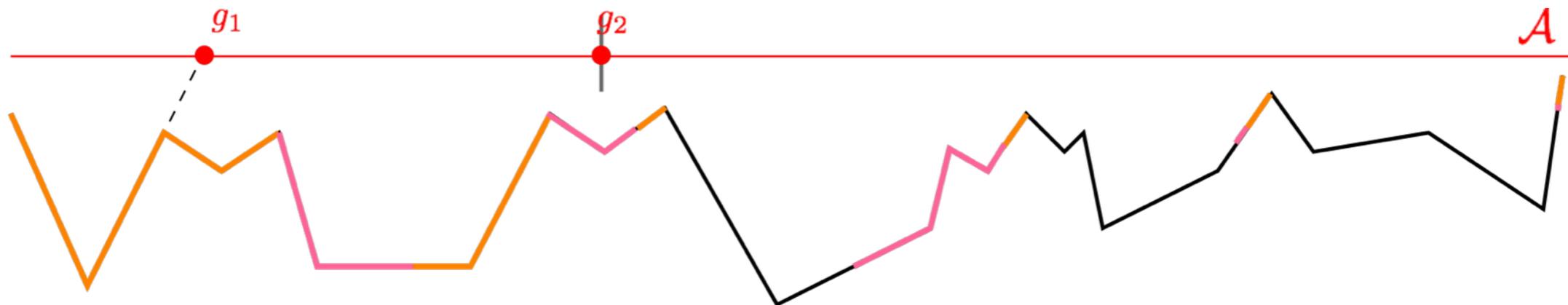
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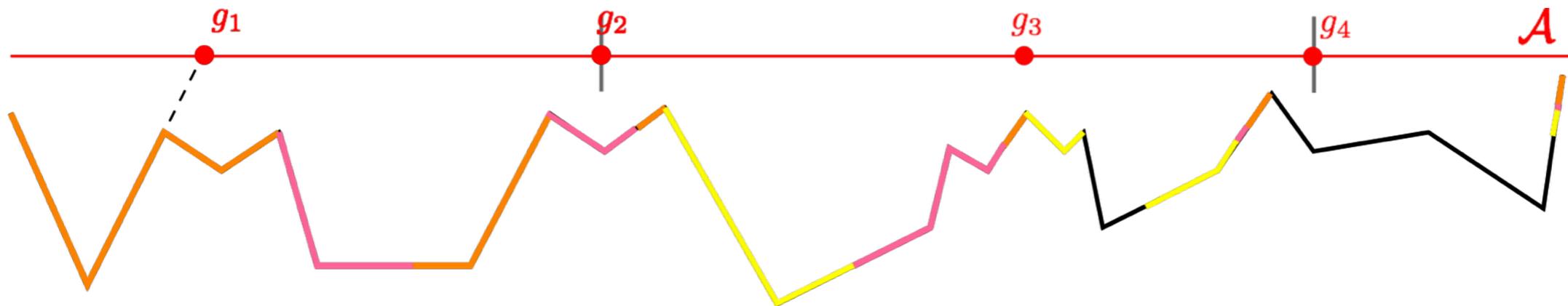
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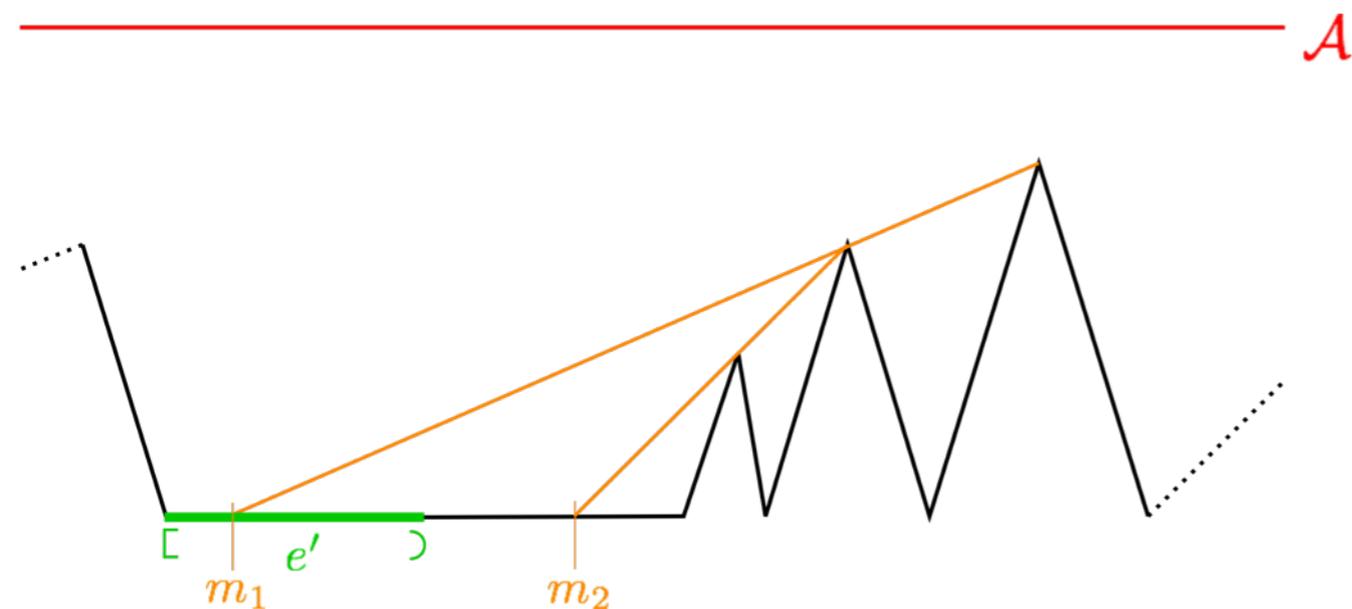
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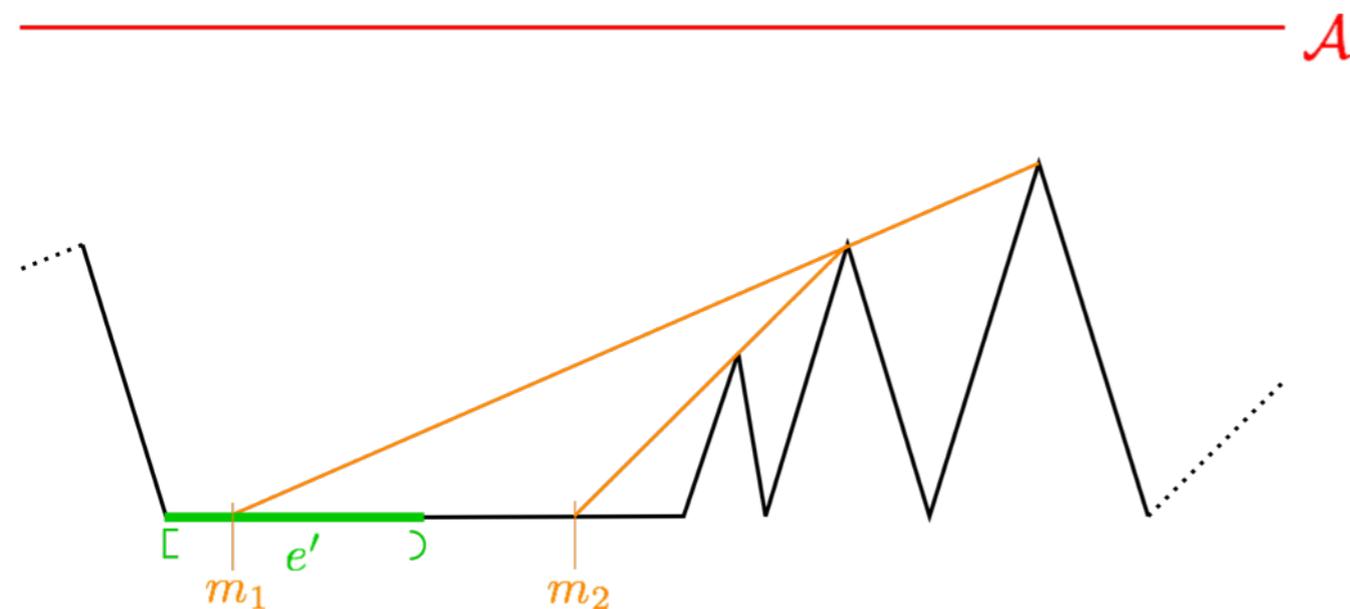
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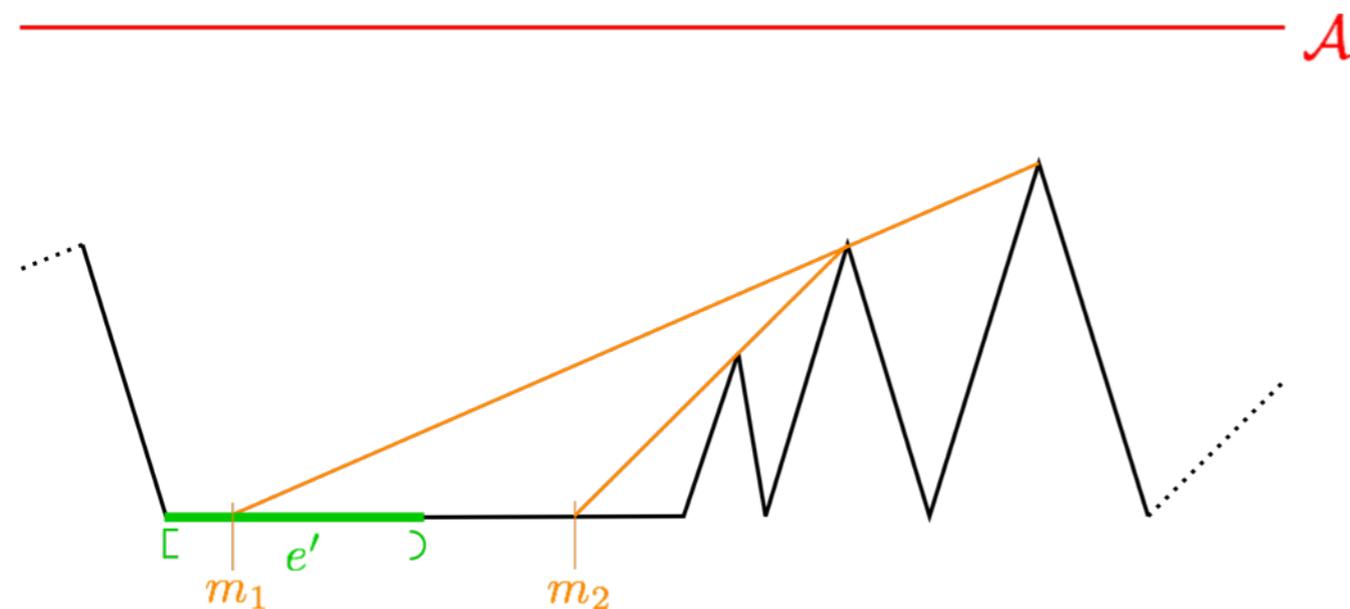
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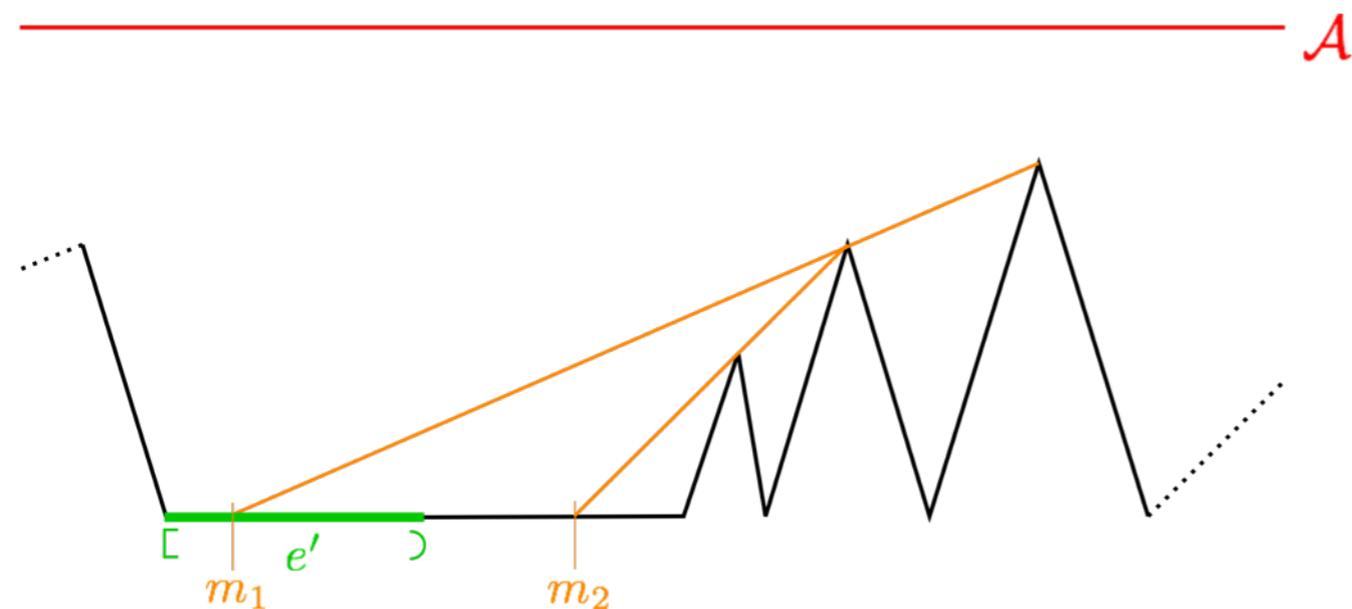
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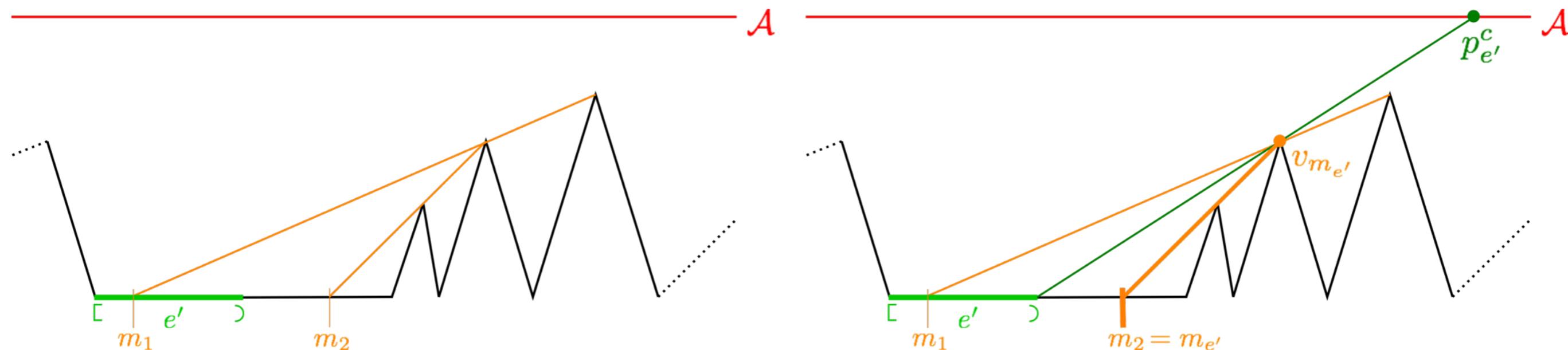
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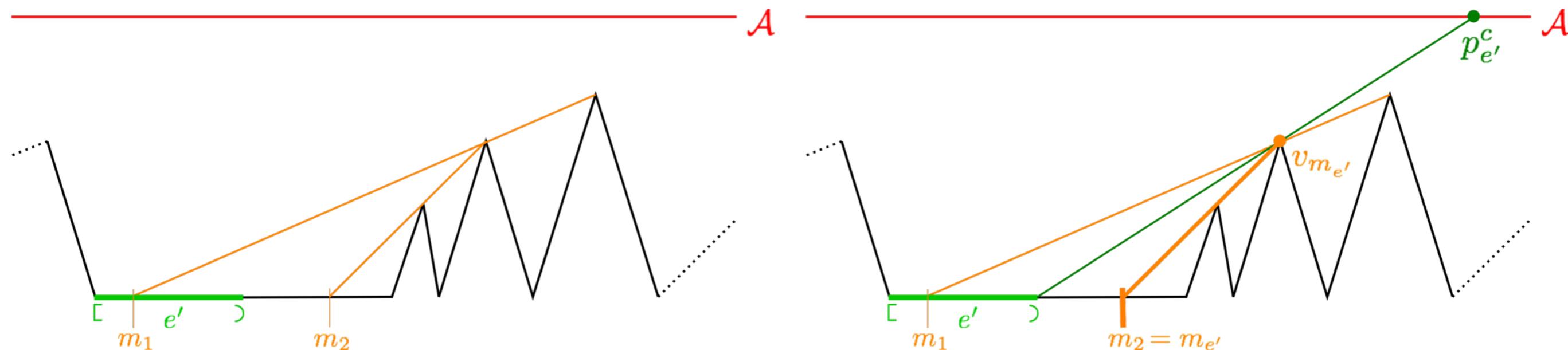
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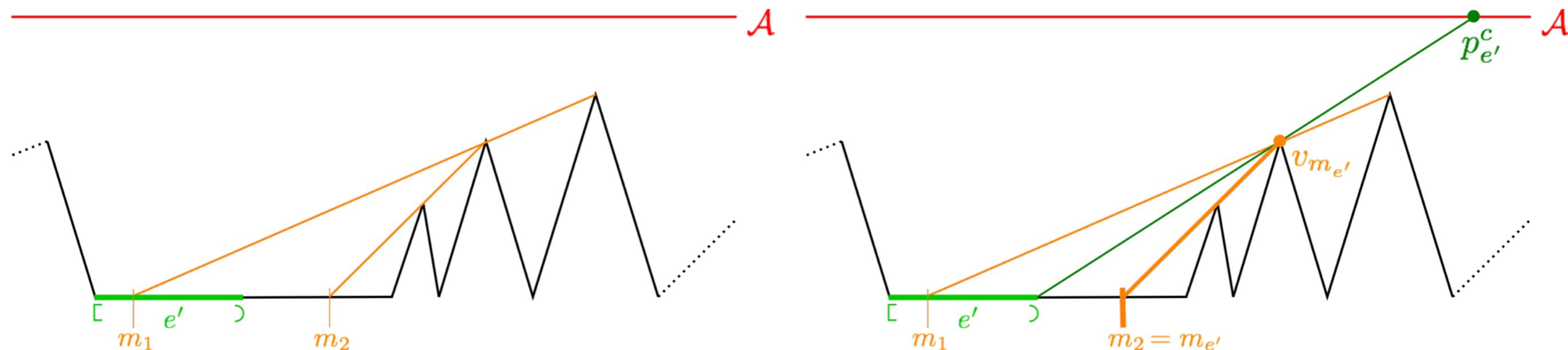
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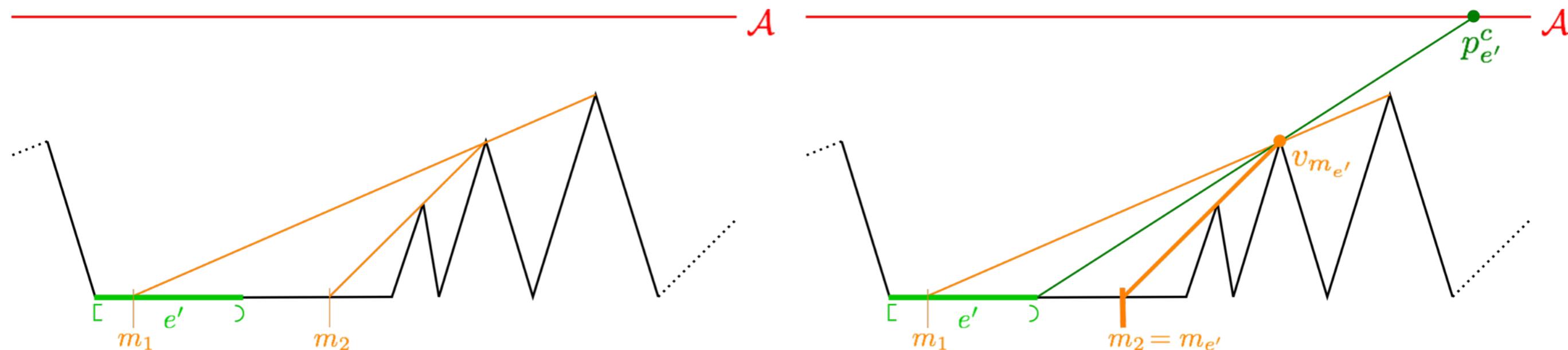
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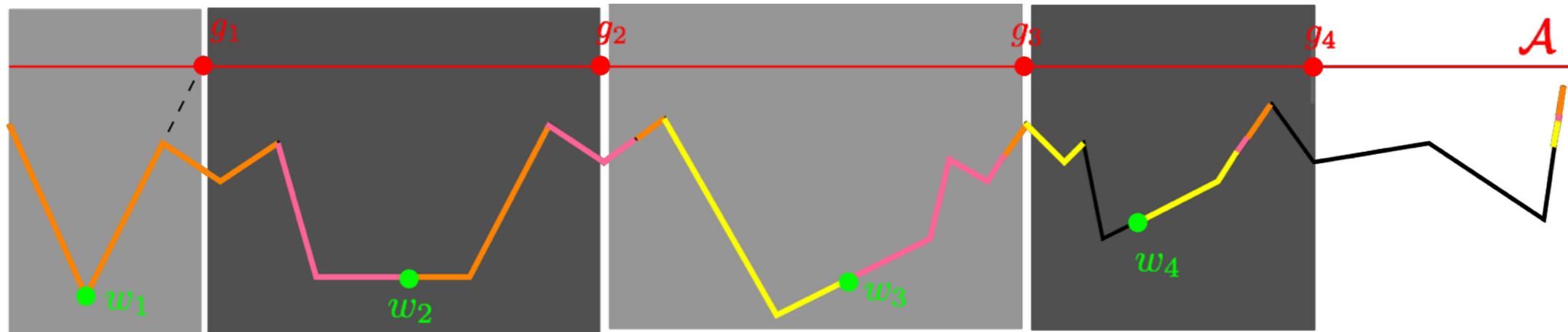
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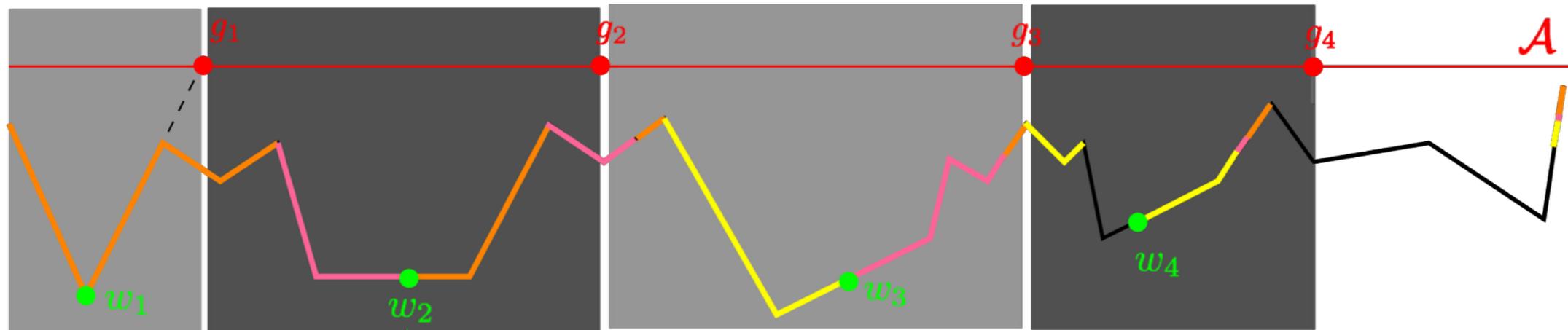
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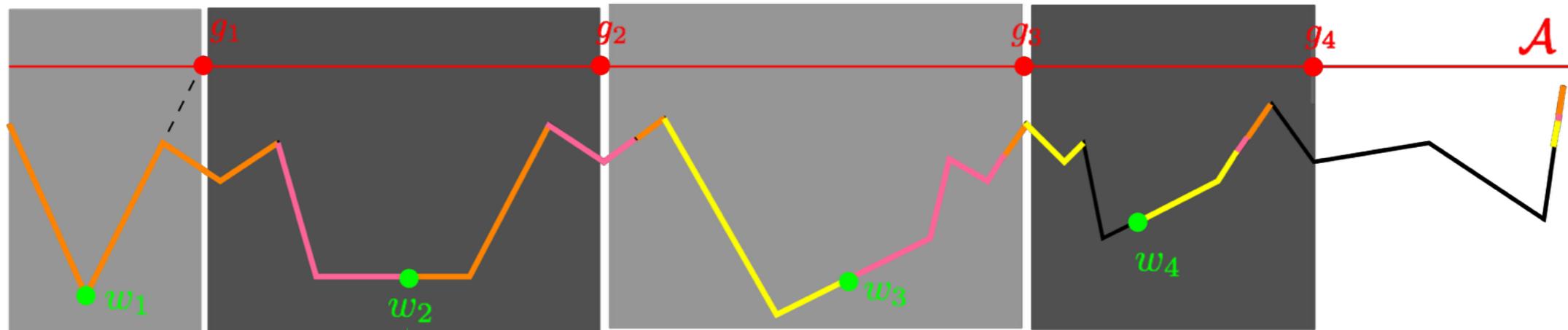
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Theorem 3: Uni-monotone polygons are perfect.

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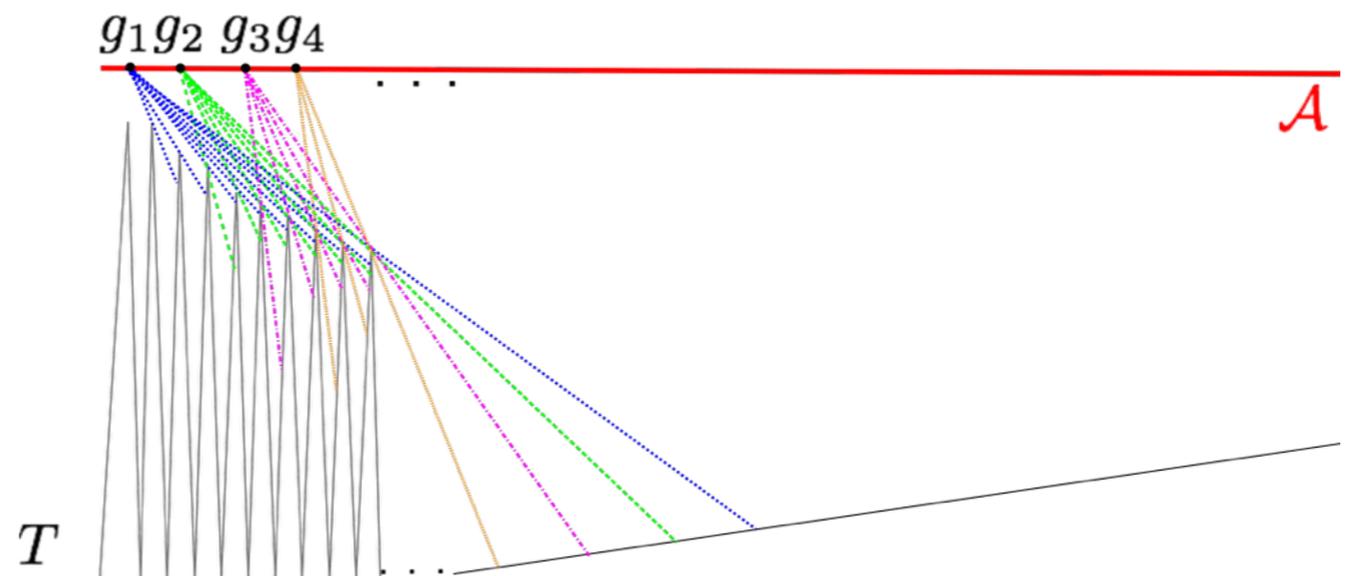
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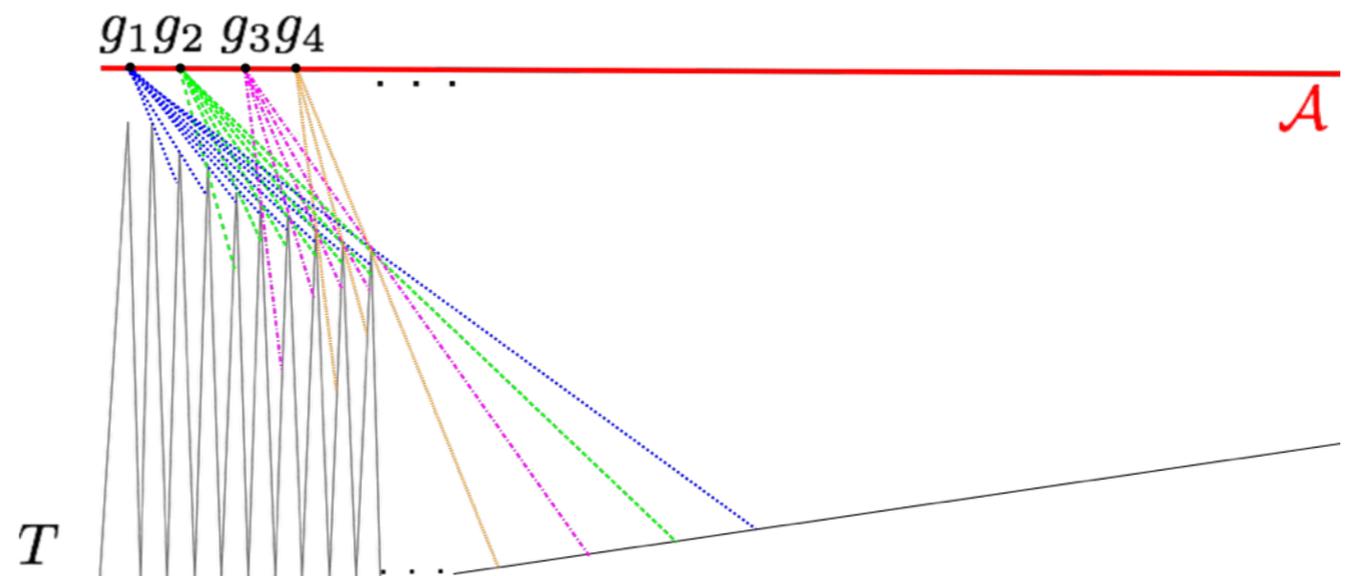
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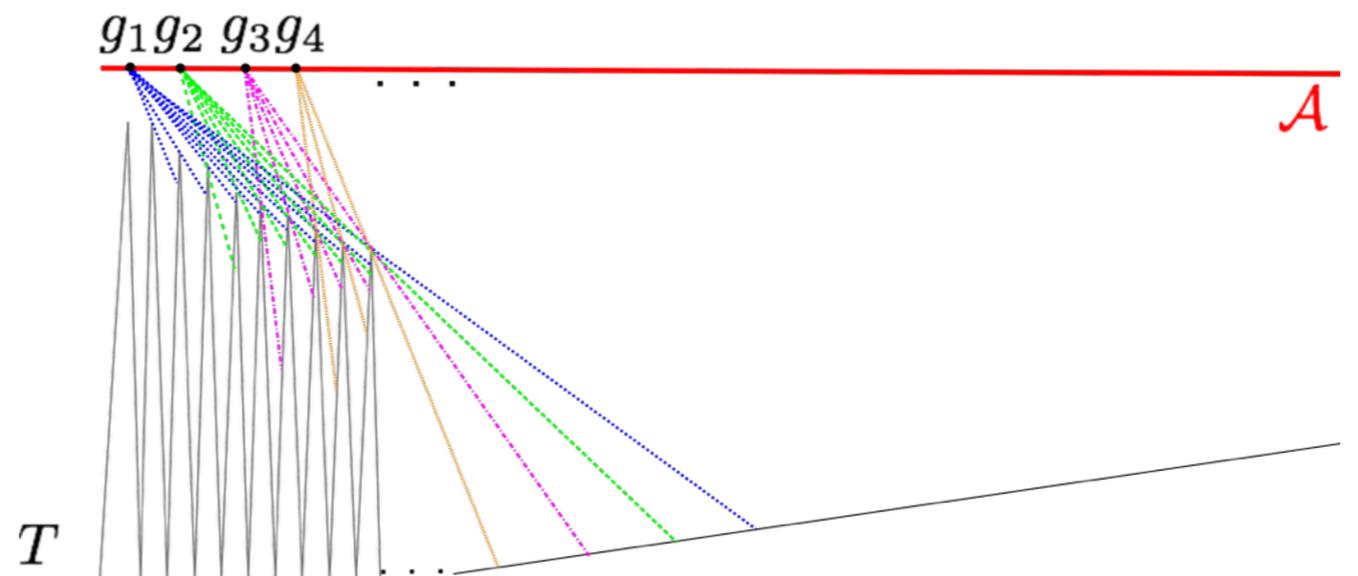
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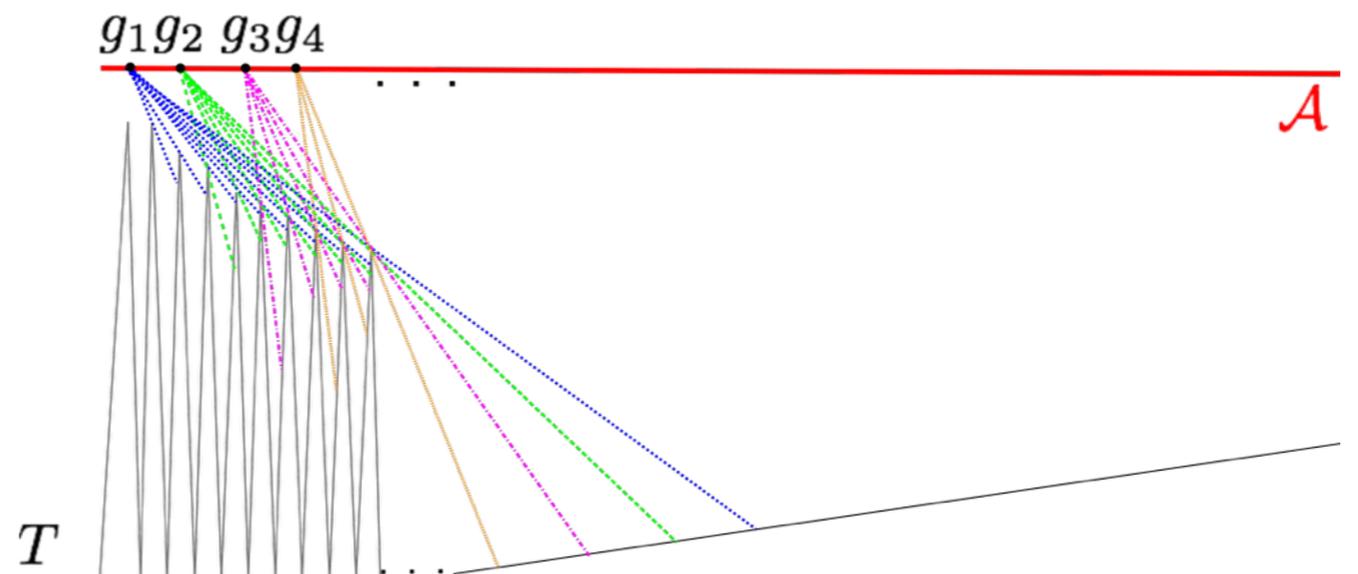


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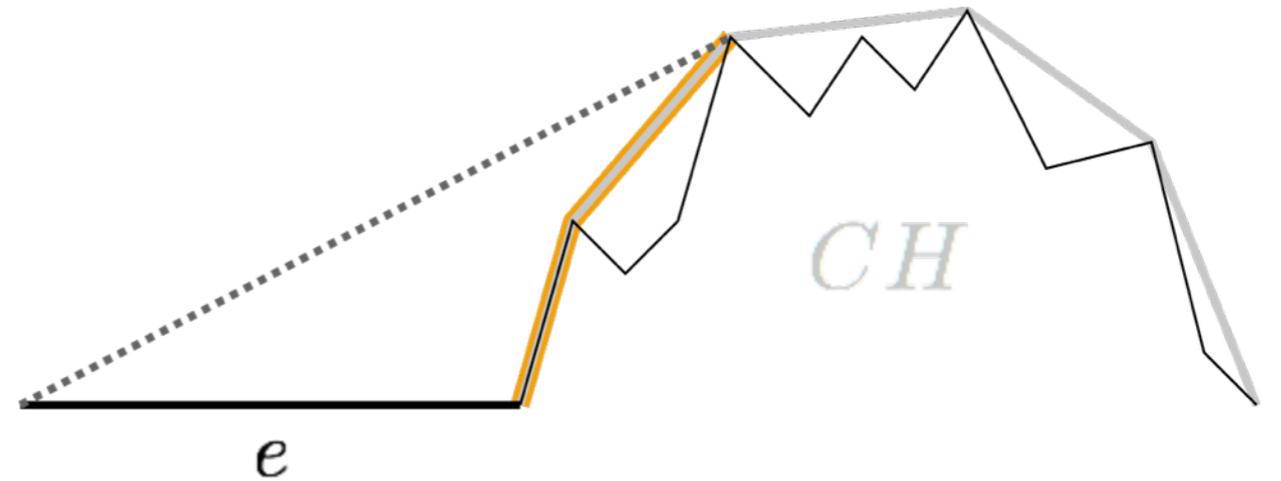
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 - Shoot $O(n)$ rays
 - For each of intersection points r_e : shoot ray through v_{me}
- ➔ $O(n^2 \log n)$ - not optimized



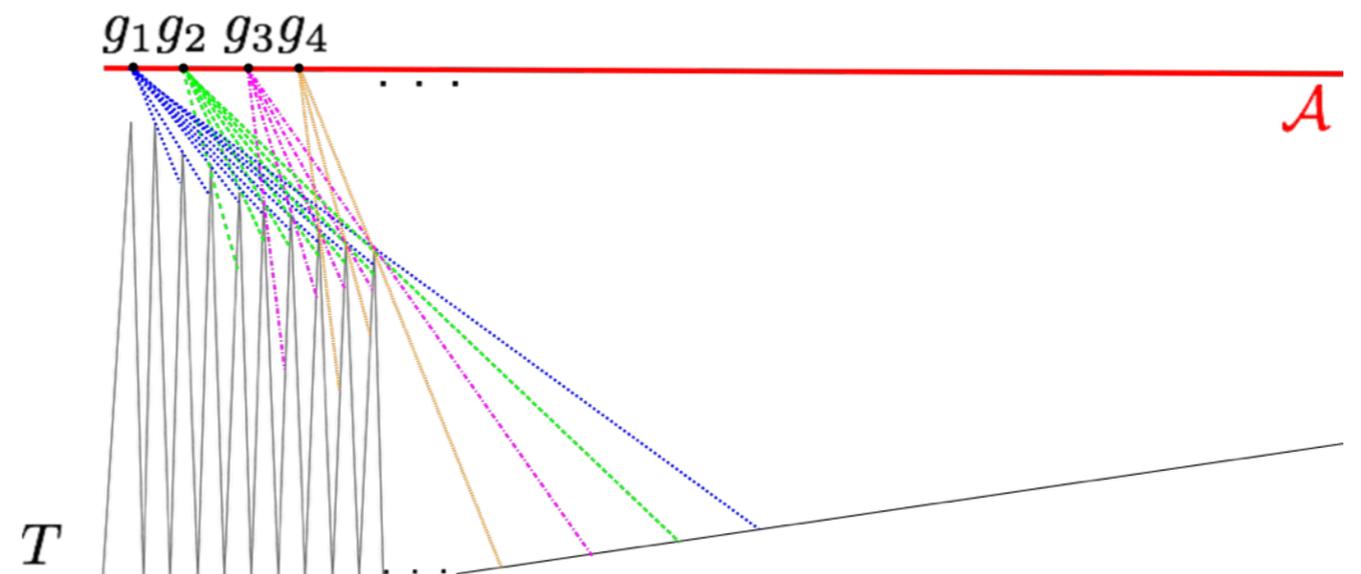
Runtime



$O(n)$



- Preprocessing: mark points $O(n^2)$
 - Accordingly: mark points from left for opening points (using left vertex of an edge to shoot the ray) and for soft opening points (using right vertex of an edge to shoot the ray)
 - Whenever we insert a guard
 - Shoot $O(n)$ rays
 - For each of intersection points r_e : shoot ray through v_{me}
- ➔ $O(n^2 \log n)$ - not optimized



Lemma 1: The set G output by the algorithm is feasible.

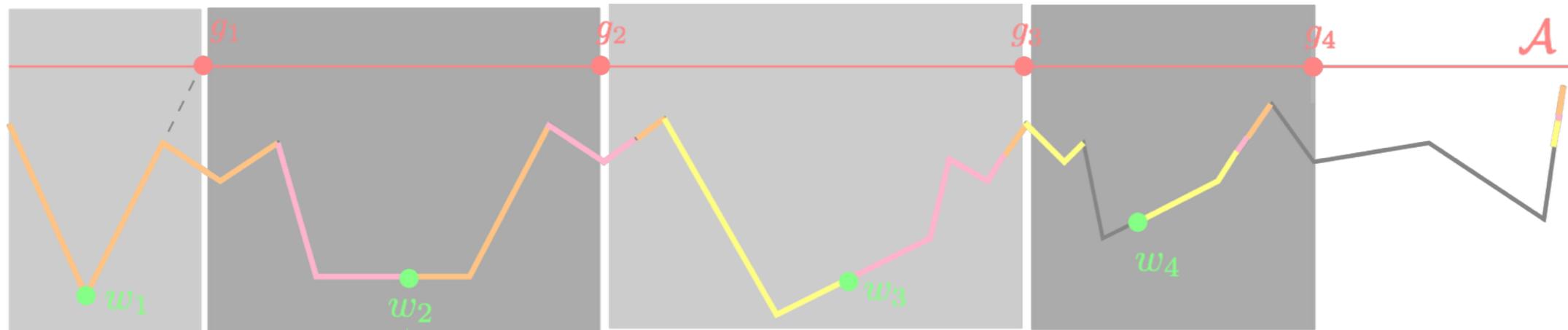
Theorem 2: The set G output by the algorithm is optimal.

Proof idea: If we can find a witness set with $|W|=|G|$, G is optimal.

Let S_i be the strip of all points with x -coordinates between $x(g_{i-1}) + \varepsilon$ and $x(g_i)$.

We place a witness w_i per guard g_i such that $V_T(w_i) \subseteq S_i \forall i$.

Thanks.



$e' = [v_j, q)$ for some point $q \in e_j$, $q \neq v_{j+1}$
we place witness at q^ε , a point ε to the left of q on T

Theorem 3: Uni-monotone polygons are perfect.