

Signal Reconstruction Performance Under Quantized Noisy Compressed Sensing

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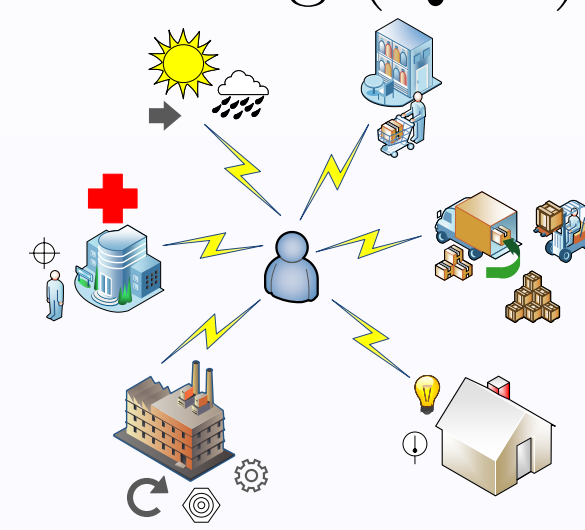
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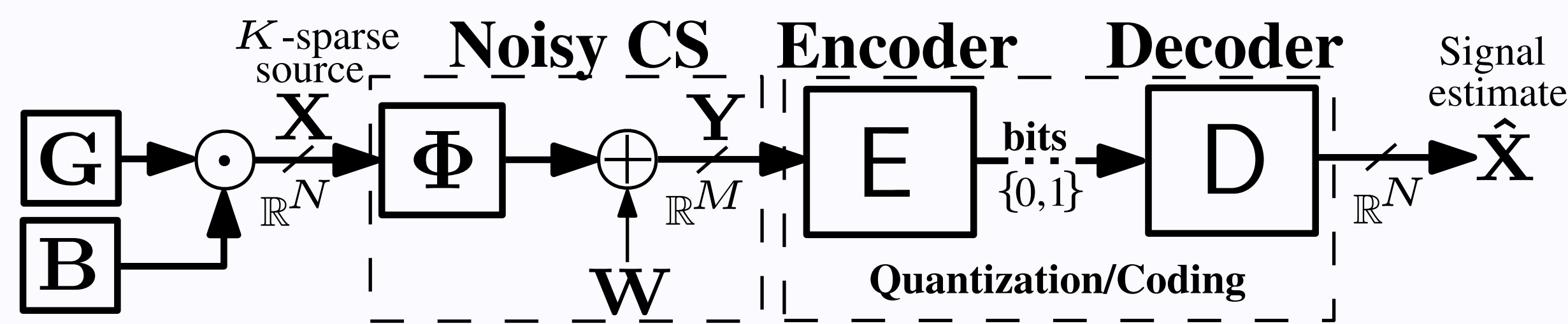
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Abstract

- Finite-rate acquisition of sparse sources via noisy compressive measurements
- Motivated by low-power sensor and IoT applications
 - Minimizing the number of bits to compress and communicate real-valued sources with a pre-defined distortion is crucial to prolong the network lifetime etc.
- Rate-distortion (RD) performance of quantized compressed sensing (QCS)
- Practical QCS methods: symbol-by-symbol quantizers and three different compression strategies
- Information-theoretical QCS limits through a lower bound and 2) numerical approximation of the remote RD function (RDF)



QCS Framework



- The encoder E observes the information source \mathbf{X} via noisy linear measurements $\mathbf{Y} \Rightarrow$ Remote source coding
- Finite-rate quantization/encoding at E
- Signal reconstruction at decoder D
- Problem: Study the achievable signal reconstruction performance of
 - Practical QCS methods where E-D is a **symbol-by-symbol** quantizer and relies on different compression strategies
 - Information-theoretical context with excessively high complex E-D
- Distortion: Mean square error (MSE) $D = \mathbb{E}[\|\mathbf{X} - \hat{\mathbf{X}}\|_2^2]$
- Signal: K -sparse source $\mathbf{X}_n = [X_{n,1} \dots X_{n,N}]^T$, $\|\mathbf{x}\|_0 = K \leq N$
 - $\mathbf{X}_n = \mathbf{G}_n \odot \mathbf{B}_n$: 1) Gaussian $\mathbf{G}_n \sim \mathcal{N}(\mathbf{0}, \Sigma_G)$; 2) binary \mathbf{B}_n , $\|\mathbf{b}_s\|_0 = K$, $s = 1, \dots, \binom{N}{K}$
- Sensing: Indirect observations by a CS-based sensor: $\mathbf{Y}_n = \Phi \mathbf{X}_n + \mathbf{W}_n$
 - Fixed and known measurement matrix $\Phi \in \mathbb{R}^{M \times N}$, $K \leq M \leq N$
 - Noise random vector $\mathbf{W}_n \sim \mathcal{N}(\mathbf{0}, \Sigma_W)$

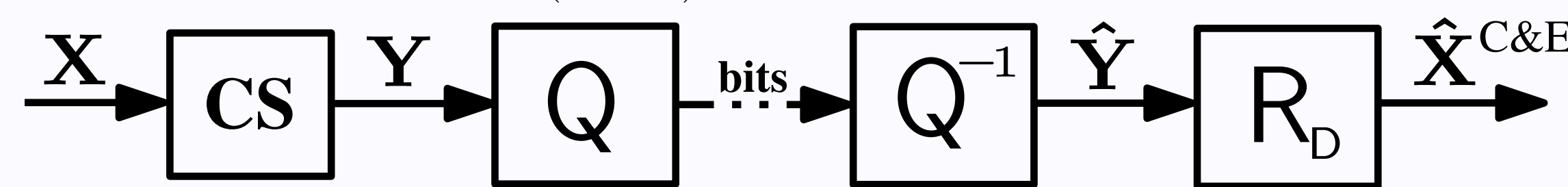
Quantizers

- Quantizer \mathbf{Q} with 1) encoder regions $\mathcal{S}_i \subseteq \mathbb{R}^L$, $\bigcup_{i=1}^{|\mathcal{I}|} \mathcal{S}_i = \mathbb{R}^L$, and 2) a reconstruction codebook $\mathcal{C} = \{\mathbf{c}_1, \dots, \mathbf{c}_{|\mathcal{I}|}\}$ with $\mathbf{c}_i \in \mathbb{R}^L$
 - Quantizer encoder $\mathbf{Q} : \mathbb{R}^L \rightarrow \mathcal{I}$ operating as $i = \mathbf{Q}(\mathbf{u})$ if $\mathbf{u} \in \mathcal{S}_i$
 - Quantizer decoder $\mathbf{Q}^{-1} : \mathcal{I} \rightarrow \mathbb{R}^L$ operating as $\hat{\mathbf{u}} = \mathbf{Q}^{-1}(i) = \mathbf{c}_i \in \mathcal{C}$
- 1) A **uniform scalar quantizer** (USQ) \mathbf{Q}^u of rate R' bits/U
- 2) A **fixed-rate Lloyd-Max quantizer** \mathbf{Q}^{lm} of rate R' bits/U optimizes the $|\mathcal{I}| = 2^{R'}$ quantization regions and the codebook to minimize the MSE distortion $D' = \sum_{i=1}^{2^{R'}} p(i) \mathbb{E}[\|\mathbf{U} - \mathbf{c}_i^{\text{lm}}\|_2^2 | I = i]$
 - Two-step iterative Lloyd and Linde-Buzo-Gray (LBG) algorithms for offline training

- 3) A **variable-rate quantizer** \mathbf{Q}^{vr} minimizes a cost function $(1 - \mu')D' - \mu' \sum_{i \in \mathcal{I}} p(i) \log(p(i))$ for an RD trade-off parameter $\mu' \in [0, 1]$
 - Three-step training algorithm using **entropy-constrained quantization** (ECSQ/ECVQ)
 - Source codebook $\mathcal{H} \triangleq \{\mathbf{h}_1, \dots, \mathbf{h}_{|\mathcal{H}|}\}$ with *variable-length* binary codewords and average rate $\sum_{i=1}^{|\mathcal{H}|} p(i) l(\mathbf{h}_i)$ bits/U (e.g. Huffman coding)

Practical QCS Methods

- Three compression strategies of different complexity-performance tradeoffs
- A **Compress-and-Estimate** (C&E) scheme:

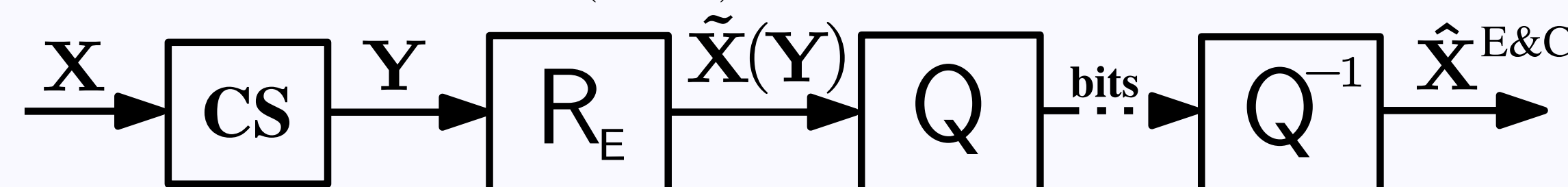


- A compression stage: the encoder quantizes \mathbf{Y} with respect to an MSE distortion that depends only on \mathbf{Y} (not on \mathbf{X})
- An estimation stage: the decoder estimates \mathbf{X} from the decoded quantized measurements $\hat{\mathbf{Y}} = \mathbf{Q}^{-1}(\mathbf{Q}(\mathbf{Y}))$

$$D^{\text{C\&E}} = \mathbb{E}[\|\mathbf{X} - \hat{\mathbf{X}}^{\text{C\&E}}\|_2^2] = \mathbb{E}[\|\mathbf{X} - \mathbf{R}_D[\mathbf{Q}^{-1}(\mathbf{Q}(\mathbf{Y}))]\|_2^2]$$

- $\mathbf{R}_D : \hat{\mathbf{Y}} \rightarrow \hat{\mathbf{X}}^{\text{C\&E}}$ is a signal reconstruction algorithm at D
- C&E principle underlies many early QCS algorithms

- An **Estimate-and-Compress** (E&C) scheme:

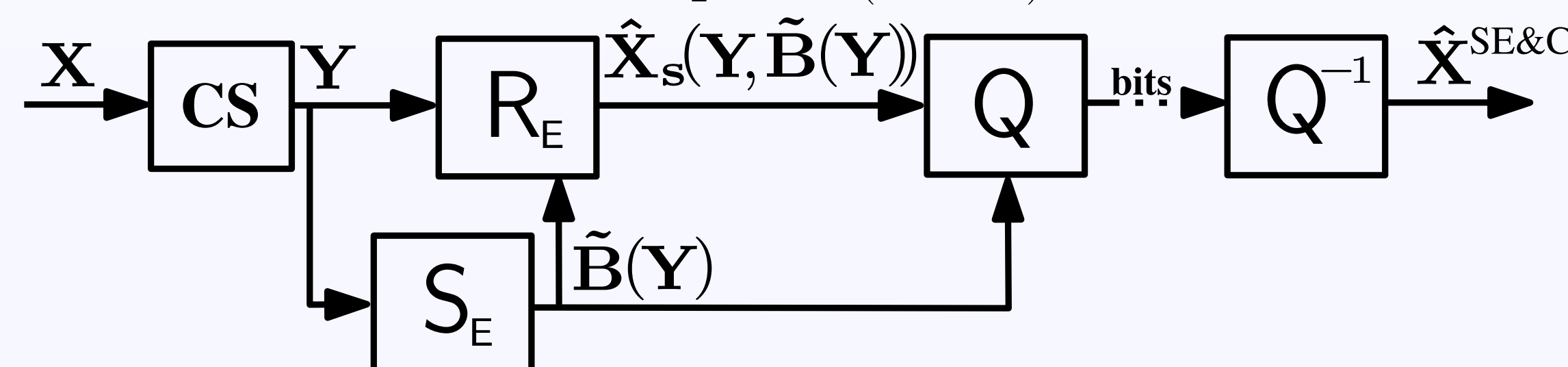


- An estimation stage: the encoder estimates \mathbf{X} from \mathbf{Y}
- A compression stage: the encoder quantizes the resulting estimate with respect to an MSE distortion of \mathbf{X}

$$D^{\text{E\&C}} = \mathbb{E}[\|\mathbf{X} - \hat{\mathbf{X}}^{\text{E\&C}}\|_2^2] = \mathbb{E}[\|\mathbf{X} - \mathbf{Q}^{-1}[\mathbf{Q}(\mathbf{R}_E(\mathbf{Y}))]\|_2^2]$$

- $\mathbf{R}_E : \mathbf{Y} \rightarrow \tilde{\mathbf{X}}(\mathbf{Y})$ is a reconstruction algorithm at E
- $\tilde{\mathbf{X}}(\mathbf{Y})$ denotes the estimator of \mathbf{X} from \mathbf{Y}
- E&C is the *optimal encoding structure* for remote source coding

- A **Support-Estimation-and-Compress** (SE&C) scheme:



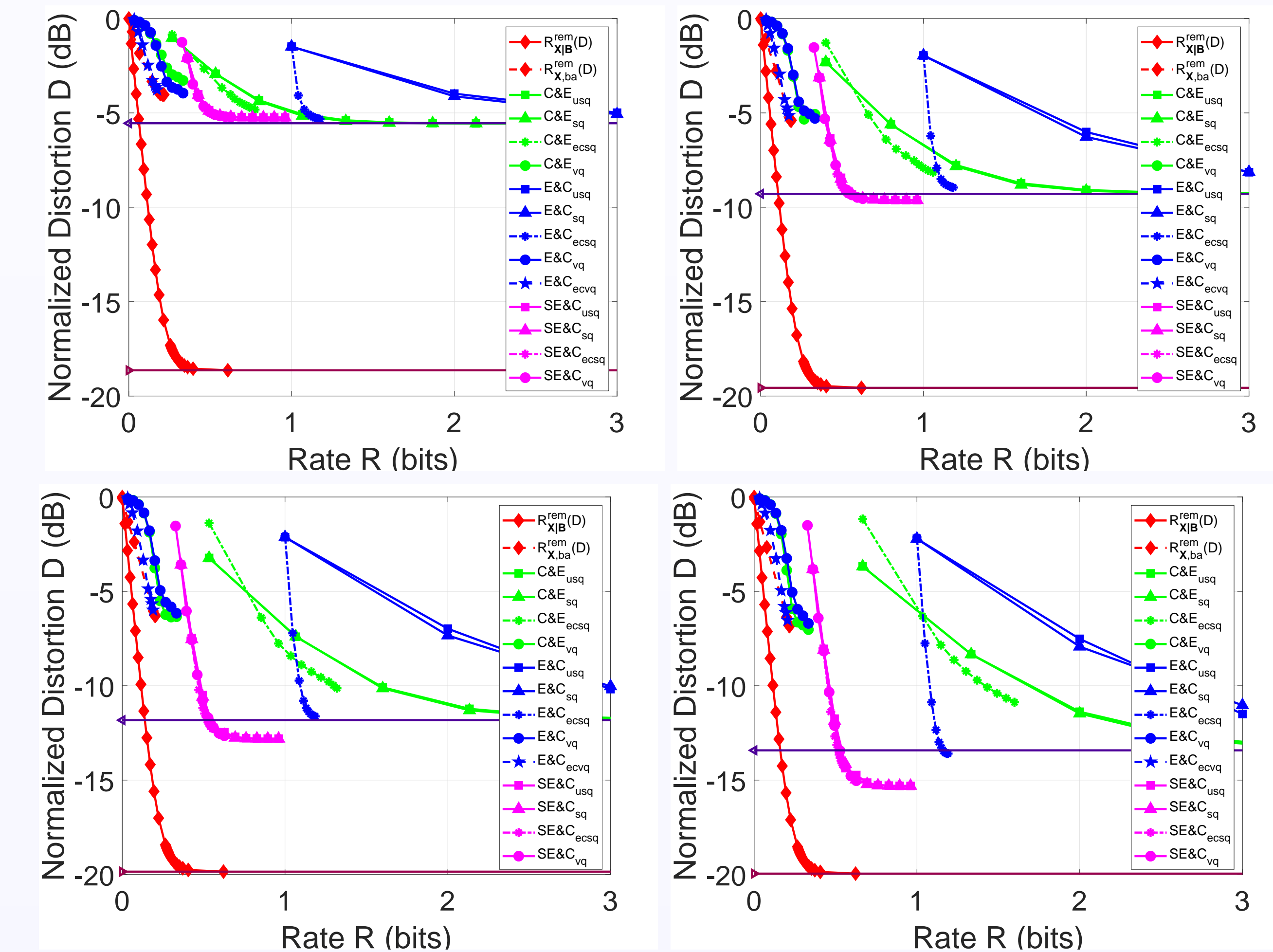
- A support estimation stage: the encoder estimates \mathbf{B} from \mathbf{Y}
- An estimation stage: the encoder estimates \mathbf{X} given \mathbf{Y} and the support estimator
- A two-phase compression stage: the encoder compresses the estimate by
 - Lossless compression for $\tilde{\mathbf{B}}$, ii) Lossy compression for the non-zero part

$$D^{\text{SE\&C}} = \mathbb{E}[\|\mathbf{X} - \hat{\mathbf{X}}^{\text{SE\&C}}\|_2^2] = \mathbb{E}[\|\mathbf{X} - \mathbf{Q}^{-1}[\mathbf{Q}(\mathbf{S}_E(\mathbf{Y}) + \mathbf{R}_E(\mathbf{Y}|\mathbf{S}_E(\mathbf{Y})))]\|_2^2]$$

- $\mathbf{S}_E : \mathbf{Y} \rightarrow \tilde{\mathbf{B}}(\mathbf{Y})$ is a support estimation algorithm at E
- $\tilde{\mathbf{B}}(\mathbf{Y})$ denotes the estimator of \mathbf{B} from \mathbf{Y}
- The sparsity K is assumed to be known by $\mathbf{S}_E(\cdot)$

Numerical Results

- QCS algorithms with 1) USQ, 2) SQ, 3) ECSQ, 4) VQ, and 5) ECVQ
- The compression limit of QCS: the minimum achievable rate R for a given distortion D is given by the *remote RDF* of source \mathbf{X} , $R_{\mathbf{X}}^{\text{rem}}(D)$
 - 1) Analytical lower bound: the conditional remote RDF $R_{\mathbf{X}|\mathbf{B}}^{\text{rem}}(D) \leq R_{\mathbf{X}}^{\text{rem}}(D)$ that assumes support side information \mathbf{B} at the encoder and decoder
 - 2) Numerical approximation of $R_{\mathbf{X}}^{\text{rem}}(D)$ via the modified Blahut-Arimoto (BA) algorithm $R_{\mathbf{X},\text{ba}}^{\text{rem}}(D) \simeq R_{\mathbf{X}}^{\text{rem}}(D)$ under VQ discretized encoder input \mathbf{Y}
- An example with $N = 30$, $M = \{8, 12, 16, 20\}$, $K = 2$
 - $\Sigma_G = \mathbf{I}_N$, $\Sigma_W = 0.01\mathbf{I}_M$, $p(\mathbf{b}_s) = 1/|\mathcal{B}|$, $\forall \mathbf{b}_s \in \mathcal{B}$, and DCT-type Φ
 - Basis pursuit denoising (BPDN) as \mathbf{R}_D in C&E, \mathbf{R}_E in E&C, and \mathbf{S}_E in SE&C (\mathbf{S}_E preserves only the indices of the K largest magnitudes)
 - Horizontal lines: the analytical MMSE estimation floor with support side information (lower); the error floor of the BPDN reconstruction (upper)
- SQ based: E&C < C&E < SE&C; VQ based: SE&C < C&E < E&C



Acknowledgments & References

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